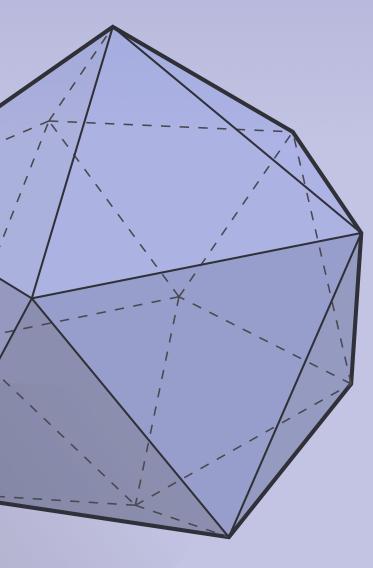
DISCRETE DIFFERENTIAL GEOMETRY: AN APPLIED INTRODUCTION Keenan Crane • CMU 15-458/858



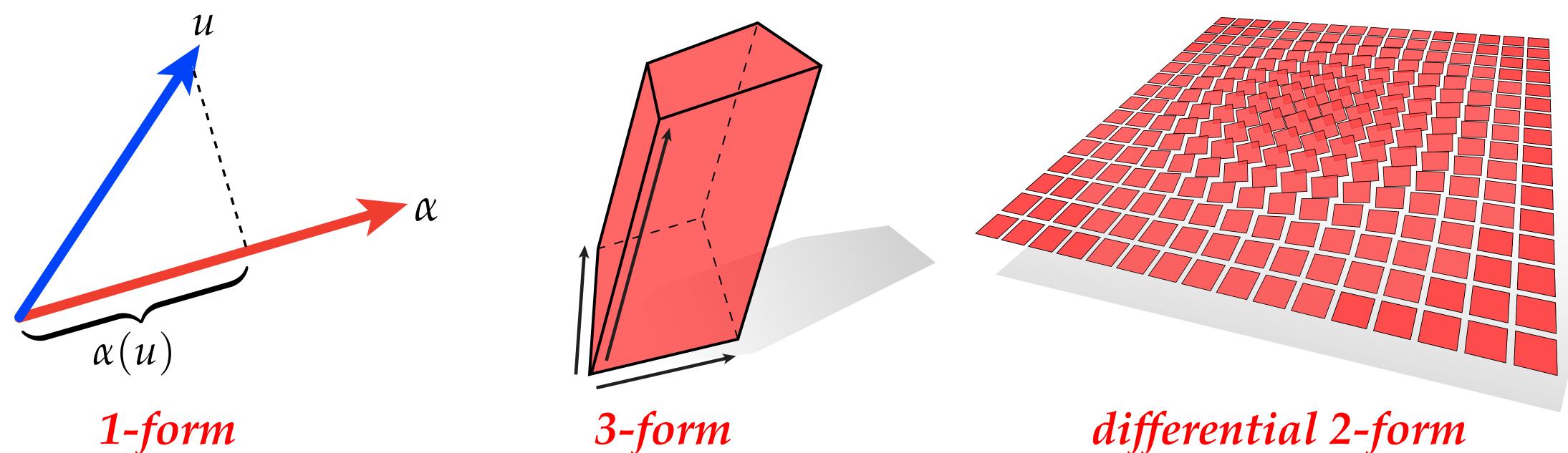
Lecture 6: EXTERIOR CALCULUS — DIFFERENTIATION

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Exterior Calculus—Overview

- Previously:
 - •1-form—linear measurement of a vector
 - *k*-form—multilinear measurement of volume
 - differential *k*-form—*k*-form at each point



- Today: exterior calculus
 - how do k-forms change?
 - how do we *integrate* k-forms?

Integration and Differentiation

- Two big ideas in calculus:
 - differentiation
 - integration
 - linked by fundamental theorem of calculus
- Exterior calculus generalizes these ideas
 - differentiation of k-forms (exterior derivative)
 - integration of *k*-forms (measure volume)
 - linked by *Stokes' theorem*

$$\int_{a}^{b} f' dx = f(b) - f(a)$$

$$\int_M d\alpha = \int_{\partial M} \alpha$$

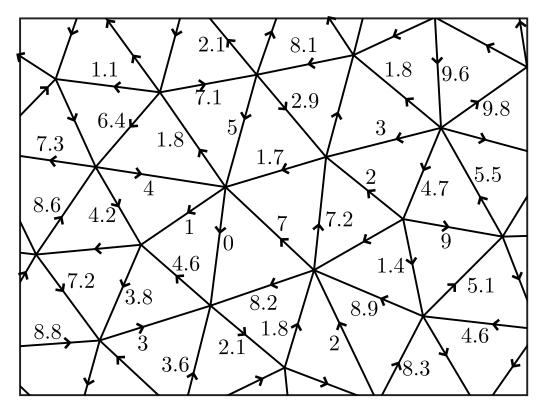
• Goal: integrate differential forms over meshes to get *discrete exterior calculus* (DEC)

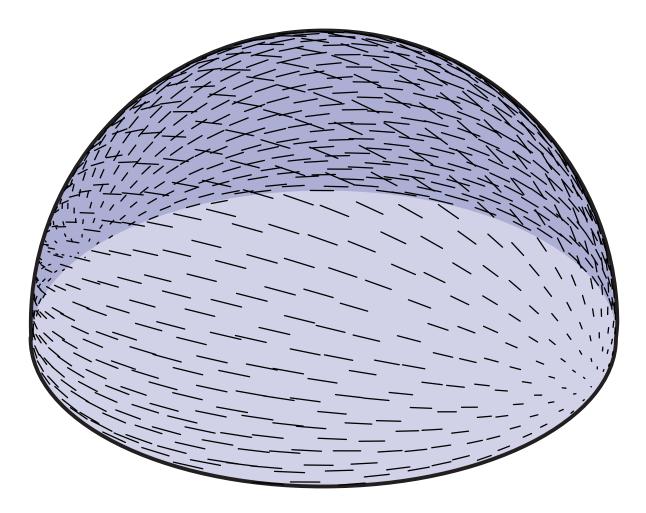


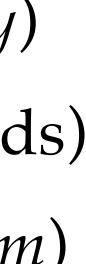
Motivation for Exterior Calculus

- Why study these two very similar viewpoints? (*I.e.*, **vector** vs. **exterior** calculus) • Hard to measure change in *volumes* using basic vector calculus

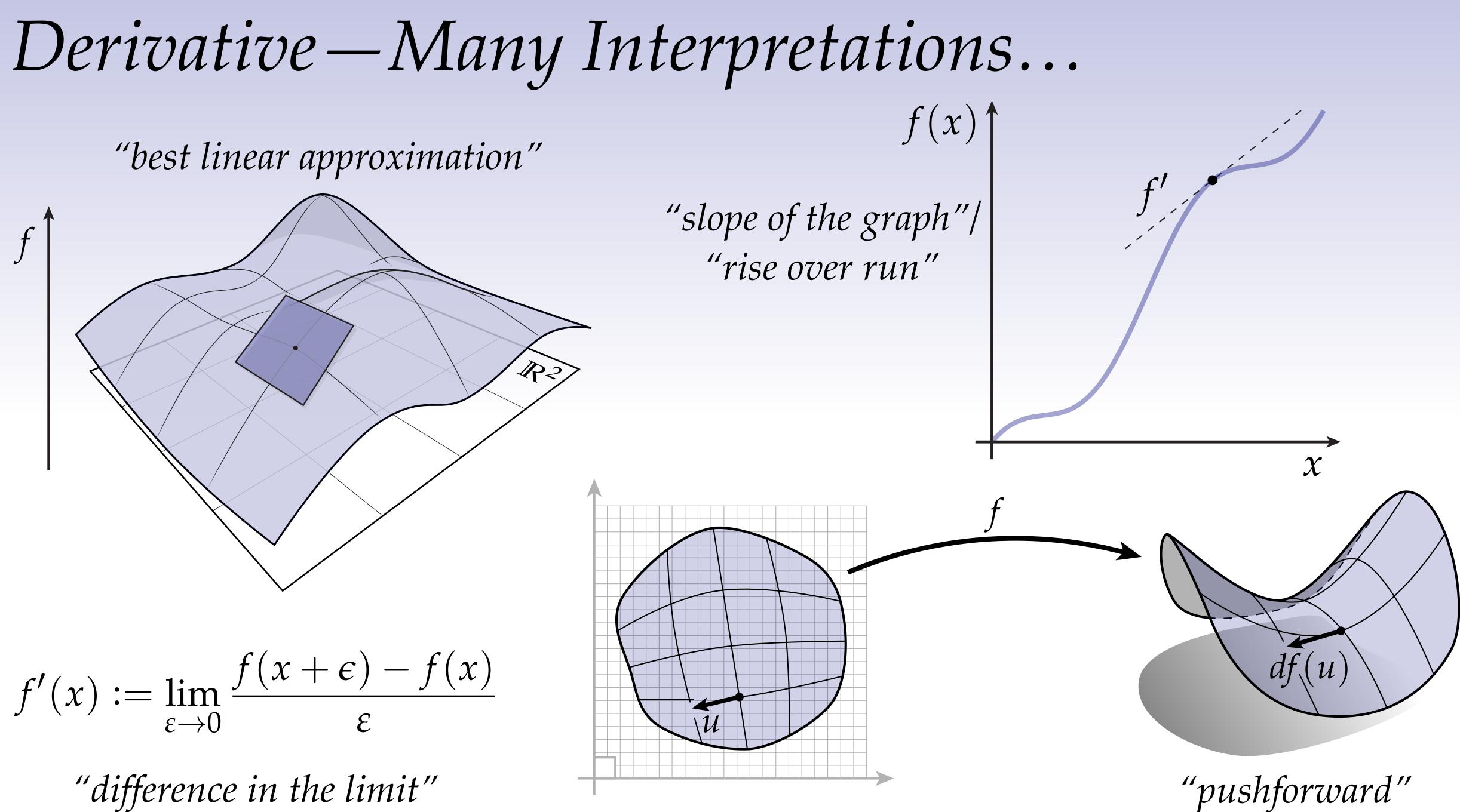
 - Duality clarifies the distinction between different concepts / quantities
 - **Topology**: notion of differentiation that does not require metric (e.g., *cohomology*)
 - Geometry: clear language for calculus on *curved* domains (Riemannian manifolds)
 - **Physics**: clear distinction between physical quantities (e.g., *velocity* vs. *momentum*)
 - **<u>Computer Science</u>**: Leads directly to discretization/computation!



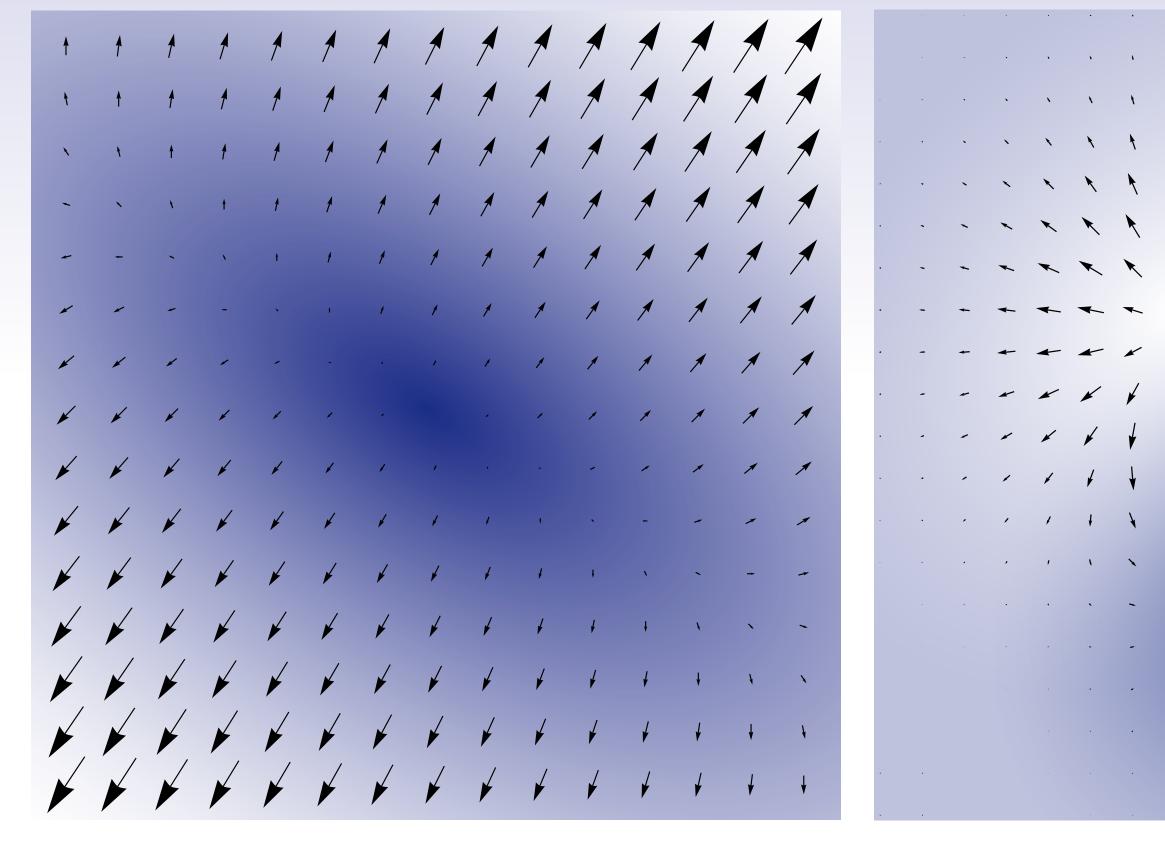




Exterior Derivative

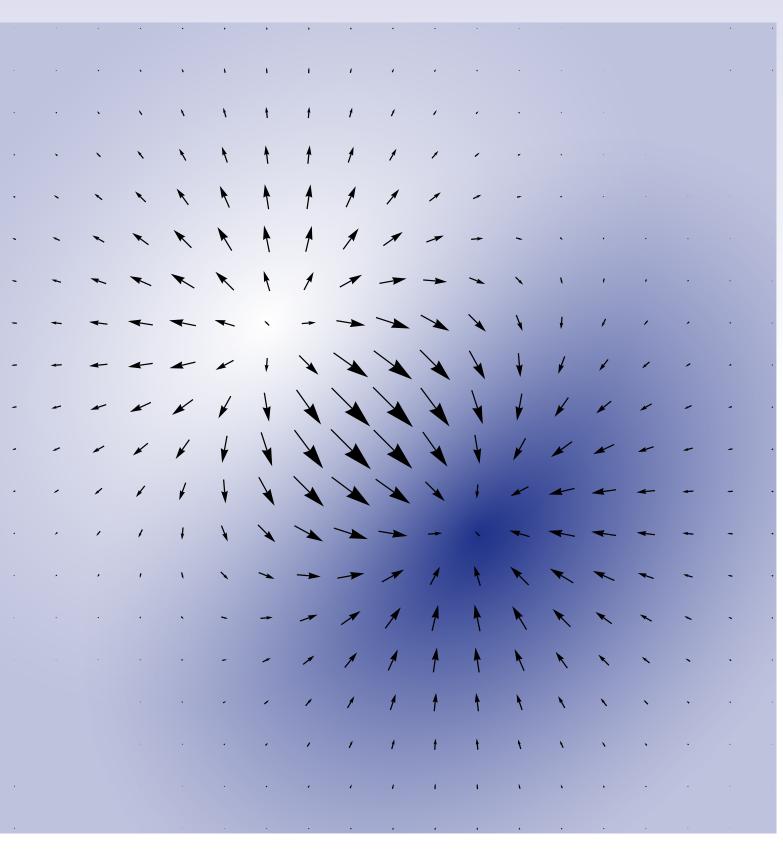


Vector Derivatives – Visualized

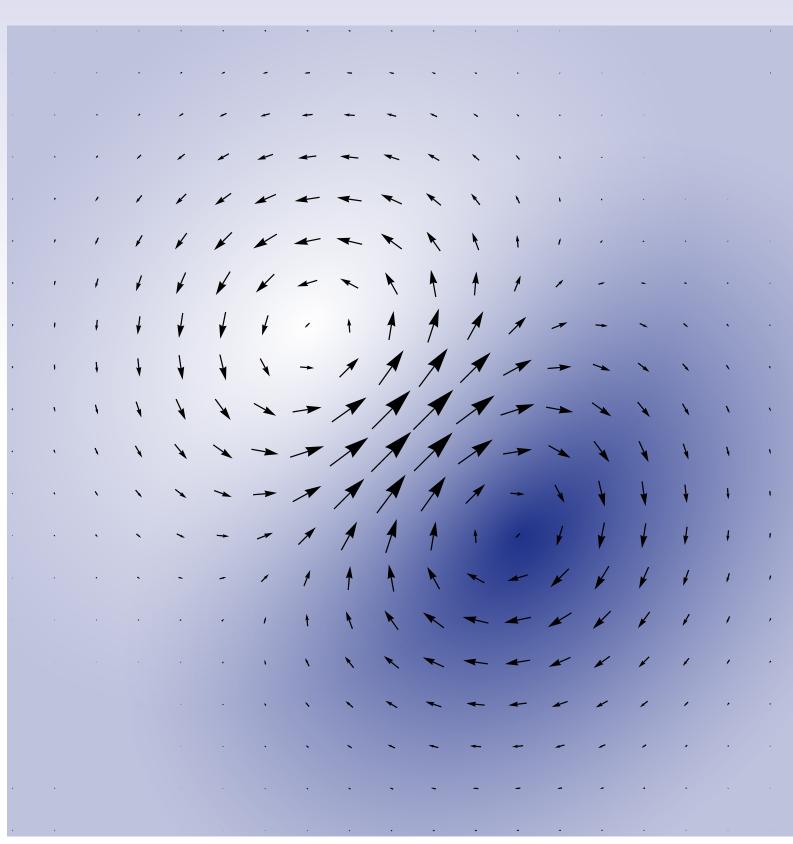


grad ϕ

X







curl Y

Review – Vector Derivatives in Coordinates

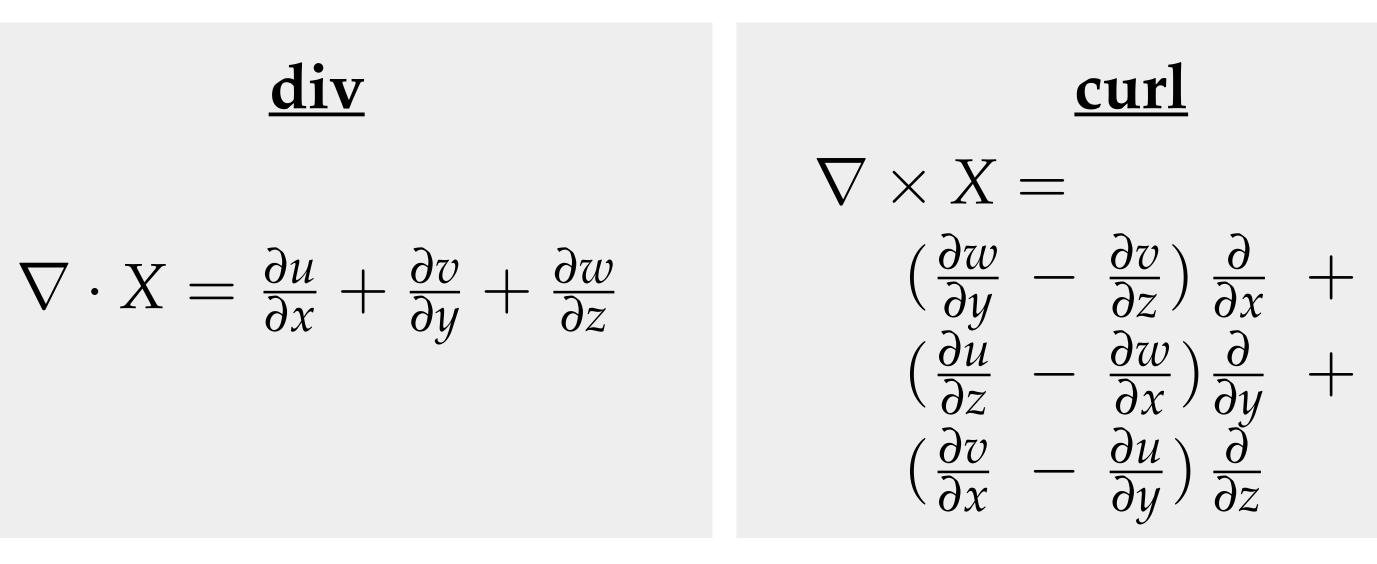
How do we express grad, div, and curl in coordinates? Consider a scalar function $\phi : \mathbb{R}^3 \to \mathbb{R}$ and a vector field

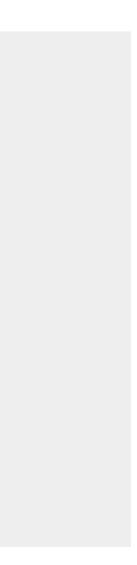
$$X = u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}$$

where $u, v, w : \mathbb{R}^n \to \mathbb{R}$ are coordinate functions that vary over the domain, and $\frac{\partial}{\partial x}$, $\frac{\partial}{\partial u}$, $\frac{\partial}{\partial z}$ are the standard basis vector fields.

grad

$$\nabla \phi = \frac{\partial \phi}{\partial x} \frac{\partial}{\partial x} + \frac{\partial \phi}{\partial y} \frac{\partial}{\partial y} + \frac{\partial \phi}{\partial z} \frac{\partial}{\partial z}$$





Exterior Derivative

differential

product rule

 $d \circ d = 0$ exactness

> Where do these rules come from? (What's the geometric motivation?)

 $(\Omega^k - \text{space of all differential } k - \text{forms})$

Unique *linear* map $d : \Omega^k \to \Omega^{k+1}$ such that

for k = 0, $d\phi(X) = D_X \phi$ $d(\alpha \wedge \beta) = d\alpha \wedge \beta + (-1)^k \alpha \wedge d\beta$



Exterior Derivative – Differential

Review: Directional Derivative

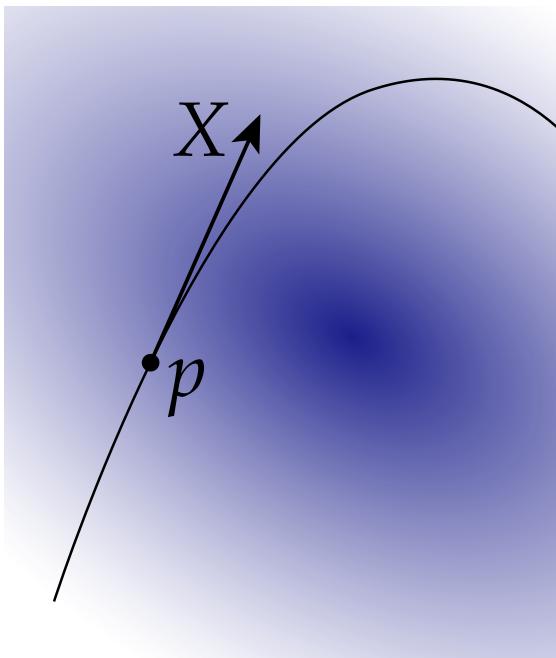
- The *directional derivative* of a scalar function at a point p with respect to a vector *X* is the rate at which that function increases as we walk away from *p* with velocity *X*.
- More precisely:

$$D_X \phi \Big|_p := \lim_{\varepsilon \to 0} \frac{\phi(p + \varepsilon X)}{\varepsilon}$$

• Alternatively, suppose that X is a vector field, rather than just a vector at a single point. Then we can write just:

• The result is a *scalar function*, whose value at each point *p* is the directional derivative along the vector *X*(*p*).

 $) - \phi(p)$



 $\phi: \mathbb{R}^2 \to \mathbb{R}$



Review: Gradient

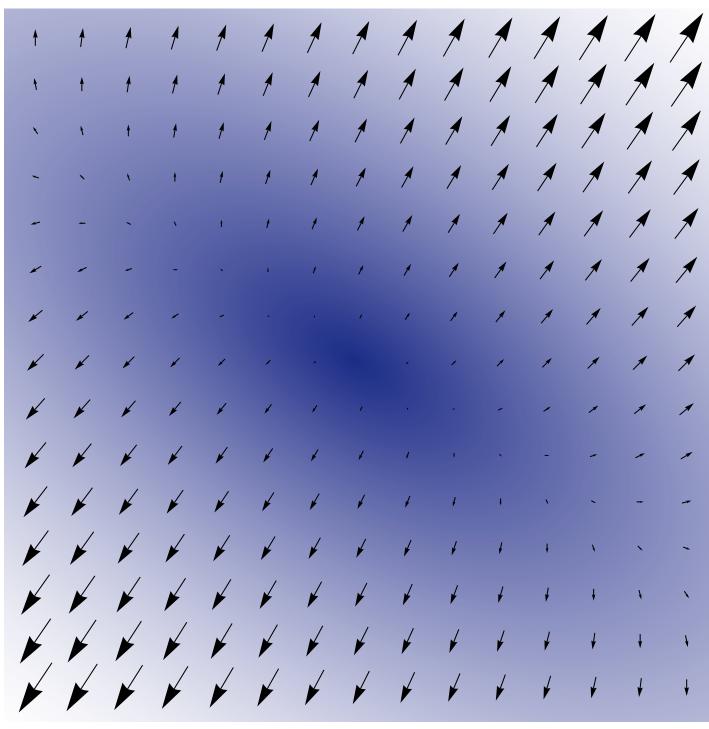
Let $\phi : \mathbb{R}^n \to \mathbb{R}$. What is the gradient of ϕ ? Geometric intuition. "Uphill direction." **Coordinate approach.** In Euclidean \mathbb{R}^n , list of partials:

$$\nabla \phi = \frac{\partial \phi}{\partial x^1} \frac{\partial}{\partial x^1} + \dots + \frac{\partial \phi}{\partial x^n} \frac{\partial}{\partial x^n} = \begin{bmatrix} \frac{\partial \phi}{\partial x^1} & \dots & \frac{\partial \phi}{\partial x^n} \end{bmatrix}^{-1}$$

Coordinate-free approach. $\langle \nabla \phi, X \rangle = D_X(\phi)$ for all *X*.

*Assuming it exists! I.e., assuming the function is *differentiable*.





I.e., at each point the gradient is the unique vector^{*} such that taking the inner product $\langle \cdot, \cdot \rangle$ with a given vector X yields the directional derivative along X.

Differential of a Function

- Recall that differential 0-forms are just ordinary scalar functions
- Change in a scalar function can be measured via the *differential*
- Two ways to define differential:
 - 1. As unique 1-form such that applying to any vector field gives directional derivative along those directions:

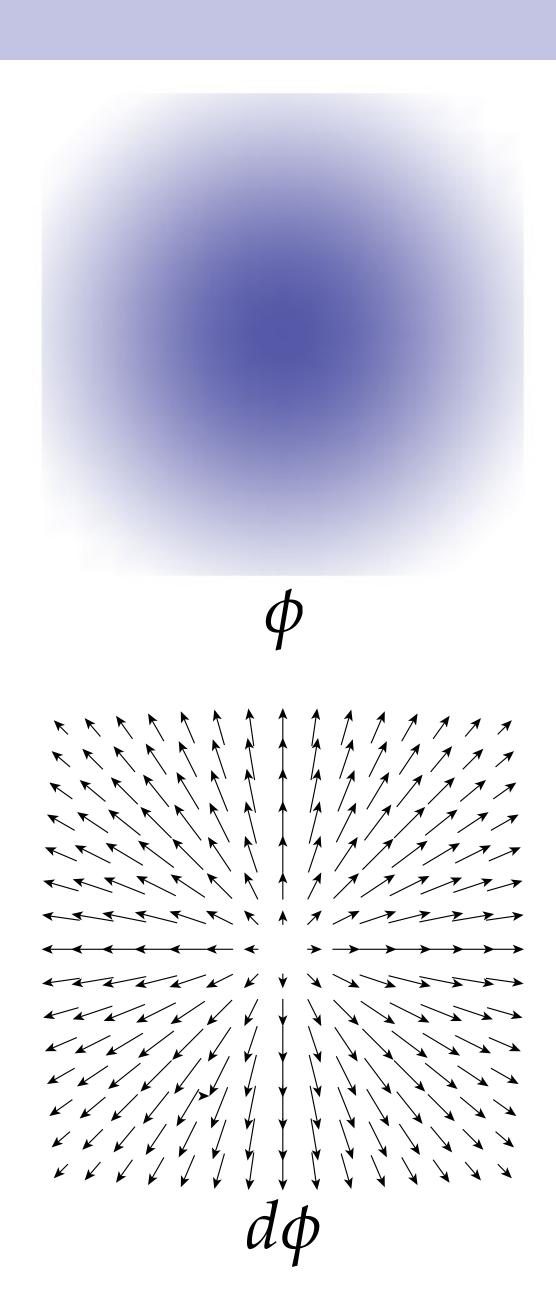
$$d\phi(X) = D_X q$$

2. In coordinates: $d\phi(X) := \frac{\partial\phi}{\partial x^1} dx^1 + \dots +$ $\mathbf{U}\mathbf{\Lambda}$

...but wait, isn't this just the same as the gradient?

D

$$\frac{\partial \phi}{\partial x^n} dx^n$$



Gradient vs. Differential

• Superficially, gradient and differential look quite similar (but not identical!):

$$\langle \nabla \phi, X \rangle = D_X \phi$$

• Especially in R^n :

$$\nabla \phi = \frac{\partial \phi}{\partial x^1} \frac{\partial}{\partial x^1} + \dots + \frac{\partial \phi}{\partial x^n} \frac{\partial}{\partial x^n} \qquad d\phi = \frac{\partial \phi}{\partial x^1} dx^1 + \dots + \frac{\partial \phi}{\partial x^n} dx^n$$

- So what's the difference?
 - For one thing, one is a vector field; the other is a differential 1-form • More importantly, gradient depends on *inner product*; differential doesn't

$$(d\phi)^{\sharp} = \nabla\phi \iff \left[d\phi(\ \cdot\) = \langle \nabla\phi,\ \cdot\ \rangle \right] \iff (\nabla\phi)^{\flat} = d\phi$$

Makes a *big* difference when it comes to curved geometry, numerical optimization, ...

$$d\phi(X) = D_X \phi$$

Exterior Derivative—Product Rule

Exterior Derivative

differential

product rule

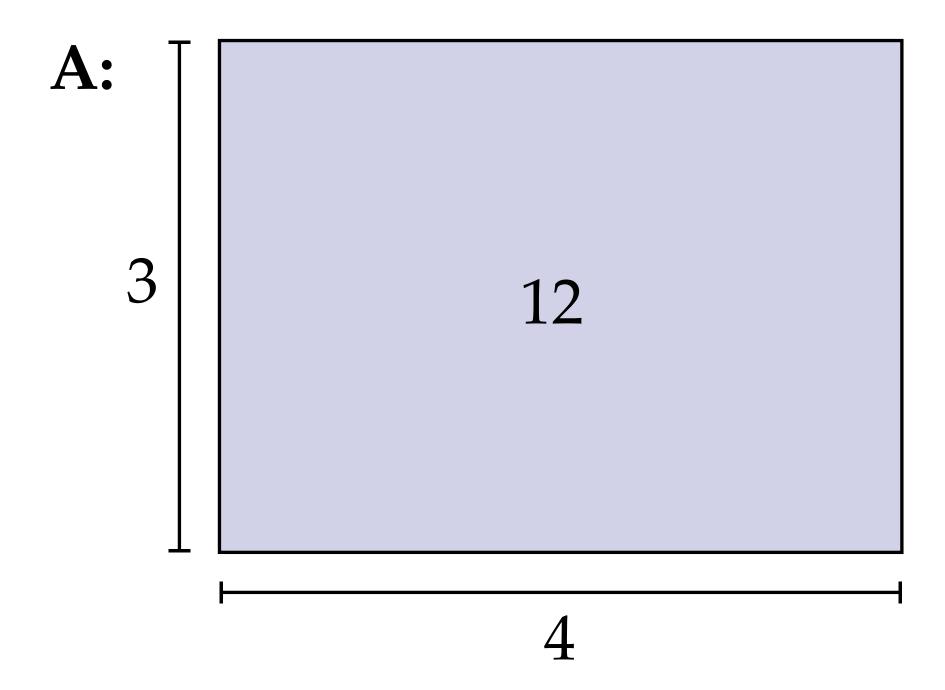
 $d \circ d = 0$ exactness

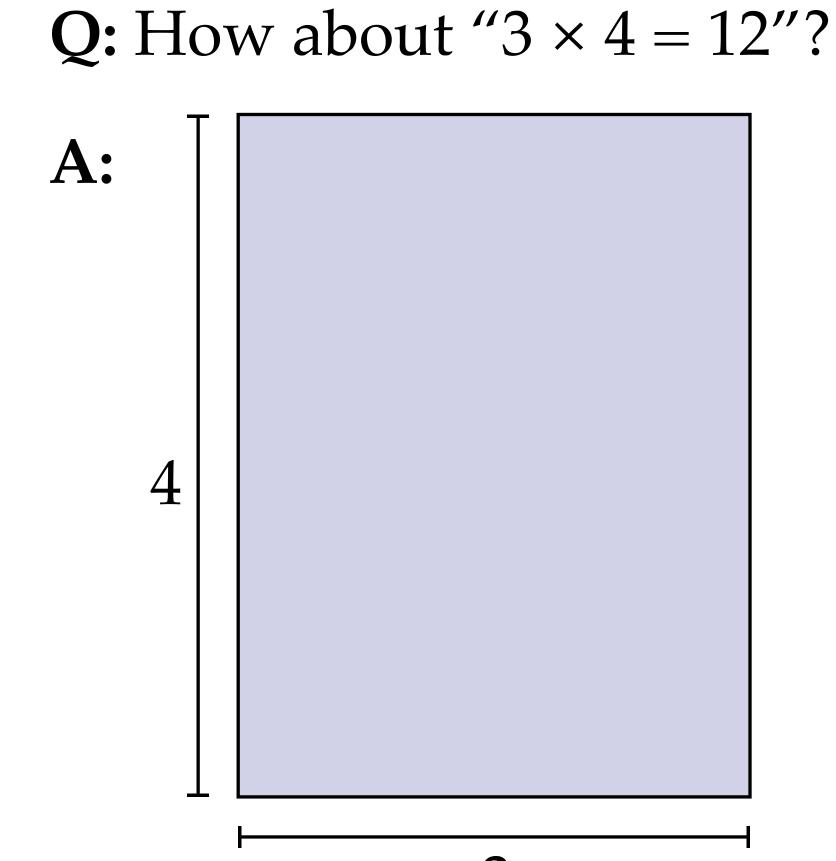
Unique *linear* map $d : \Omega^k \to \Omega^{k+1}$ such that

for k = 0, $d\phi(X) = D_X \phi$ $d(\alpha \wedge \beta) = d\alpha \wedge \beta + (-1)^k \alpha \wedge d\beta$

Review: Product of Numbers

- **Q**: Why is it true that *ab* = *ba* for any two real numbers *a*, *b*?
- **Q**: What's the geometric interpretation of the statement " $4 \times 3 = 12$ "?

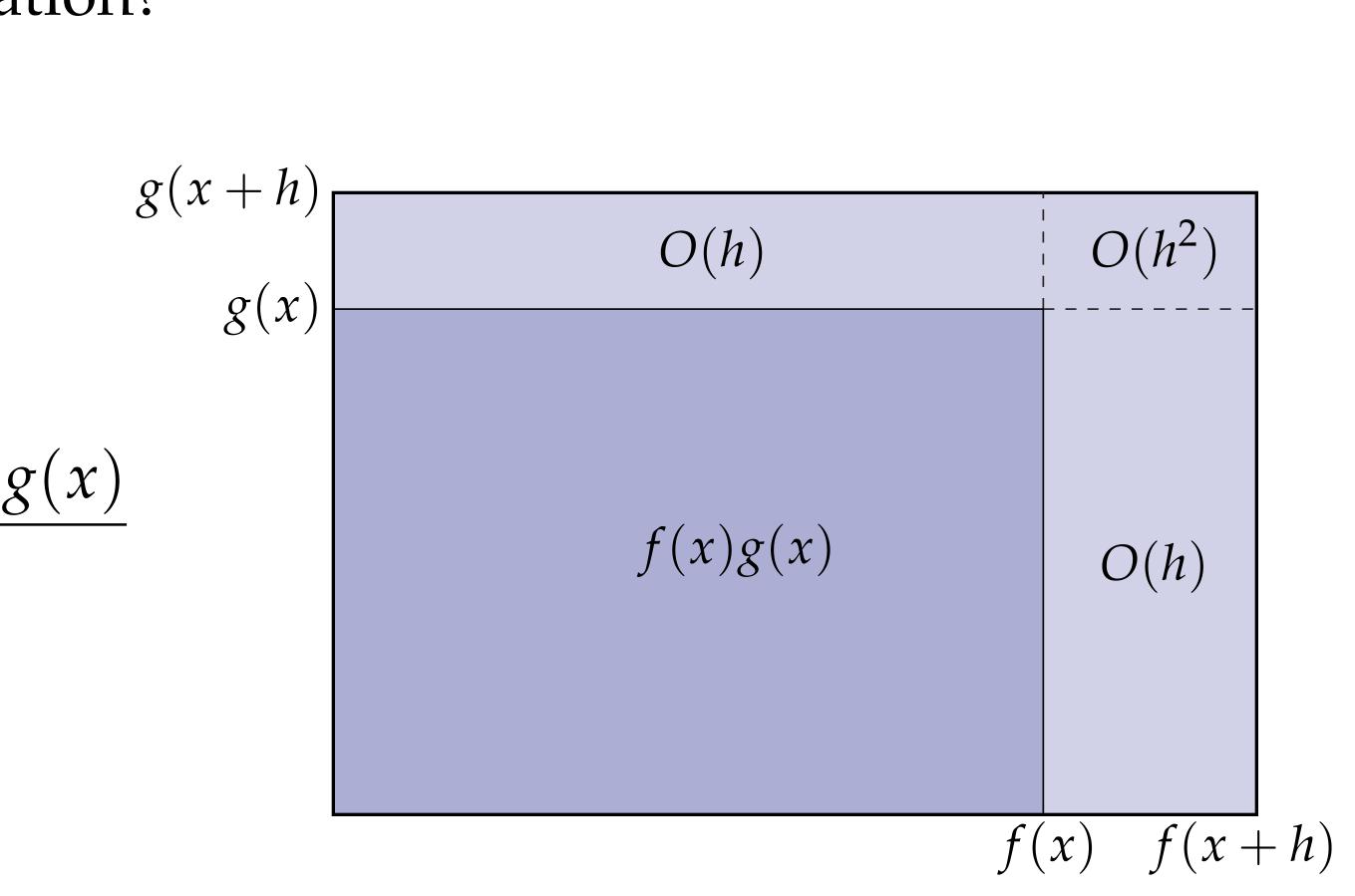




Product Rule—Derivative

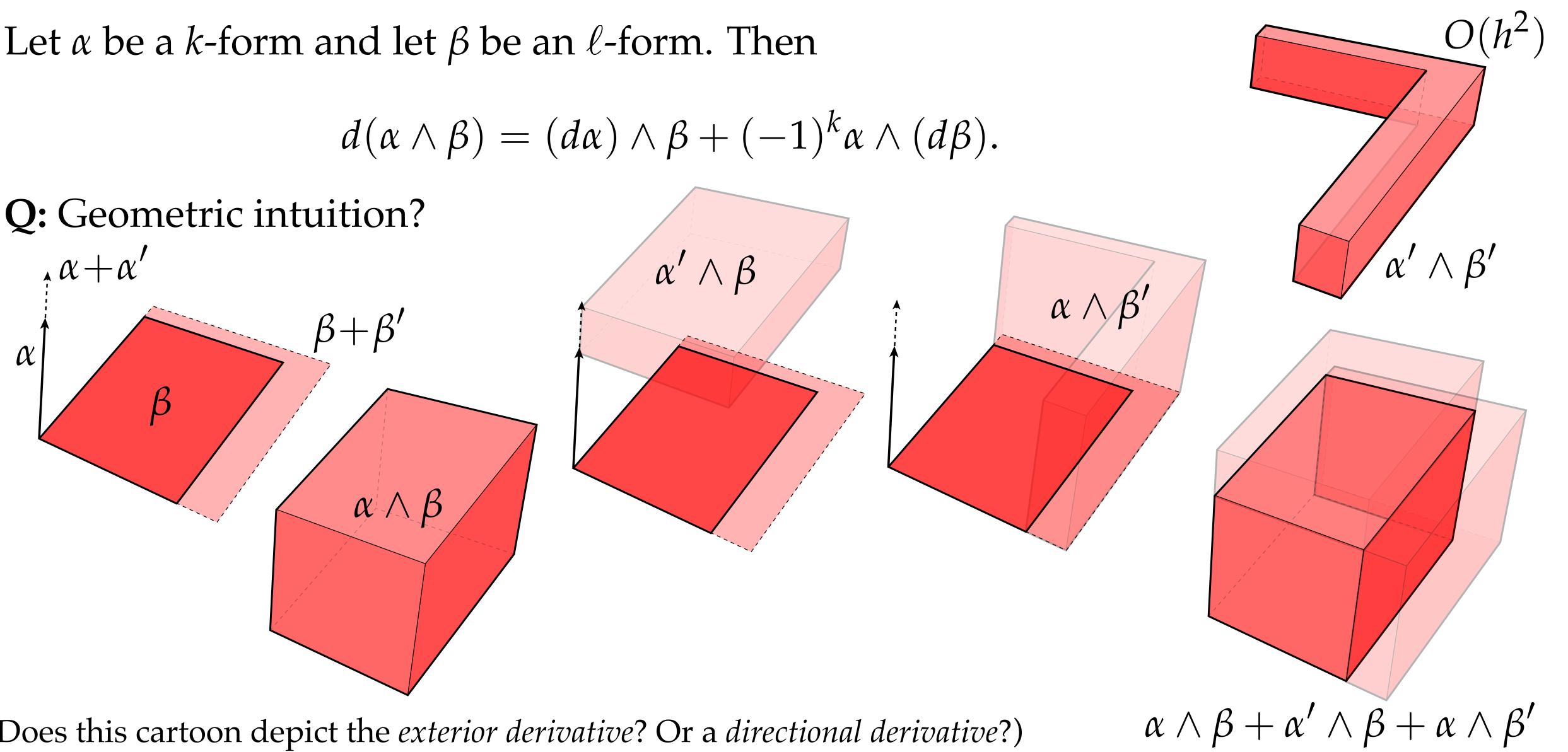
Reminder: For any differentiable function $f : \mathbb{R} \to \mathbb{R}$, (fg)' = f'g + fg'. **Q**: Why? What's the *geometric* interpretation?

$$(fg)'(x) = \lim_{h \to 0} \frac{f(x+h)g(x+h) - f(x)g(x+h)}{h}$$



Product Rule—Exterior Derivative





(Does this cartoon depict the *exterior derivative*? Or a *directional derivative*?)

Product Rule — "Recursive Evaluation"

Example. Let $\alpha := u \, dx$, $\beta := v \, dy$, and $\gamma := w \, dz$ be differential 1-forms on \mathbb{R}^n , where $u, v, w : \mathbb{R}^n \to \mathbb{R}$ are 0-forms, *i.e.*, scalar functions. Also, let $\omega := \alpha \land \beta$. Then

 $d(\omega \wedge \gamma) = (d\omega) \wedge \gamma$

We can then "recursively" evaluate derivatives that appear on the right-hand side:

- $d\omega = (d\alpha) \wedge \beta$
- $d\alpha = (du) \wedge d$
- $d\beta = (dv) \wedge d$
- $d\gamma = (dw) \wedge dw$

to taking the differential of ordinary scalar functions.

$$\gamma + (-1)^2 \omega \wedge (d\gamma).$$

$$3 + (-1)^{1} \alpha \wedge (d\beta),$$

$$dx + (-1)^{0} u (ddx),^{0},$$

$$dy + (-1)^{0} v (ddy),^{0},$$

$$dz + (-1)^{0} w (ddz).^{0},$$

Key idea: The "base case" is the 0-forms, *i.e.*, computing the final result boils down

Exterior Derivative—Examples

Example. Let $\phi(x, y) := \frac{1}{2}e^{-(x^2+y^2)}$. The

Example. Let $\alpha(x, y) = xdx + ydy$. Then

Example. Again let $\alpha(x, y) = xdx + ydy$

en
$$d\phi = \frac{\partial \phi}{\partial x}dx + \frac{\partial \phi}{\partial y}dy$$

= $-2\phi(xdx + ydy)$

$$n d\alpha =$$

$$(\frac{\partial x}{\partial x}dx + \frac{\partial x}{\partial y}dy) \wedge dx + (\frac{\partial y}{\partial x}dx + \frac{\partial y}{\partial y}dy) \wedge dy = dx \wedge dx + dy \wedge dy = 0 + 0 = 0.$$

y. Then
$$d \star \alpha = d(x \star dx + y \star dy)$$

= $d(xdy - ydx)$
= $dx \wedge dy - dy \wedge dx$
= $2dx \wedge dy$.

Exterior Derivative—Exactness

Exterior Derivative

Unique *linear* map $d : \Omega^k \to \Omega^{k+1}$ such that

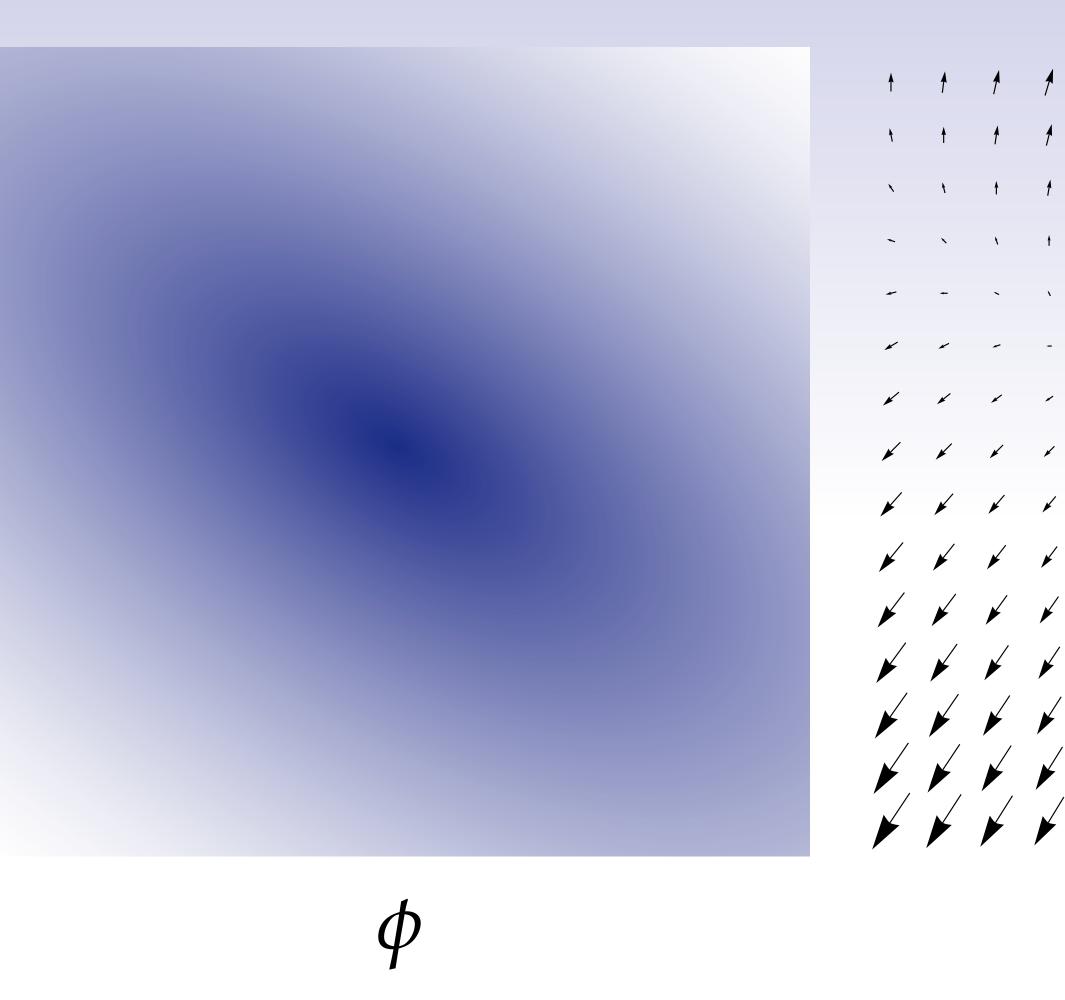
differential

product rule

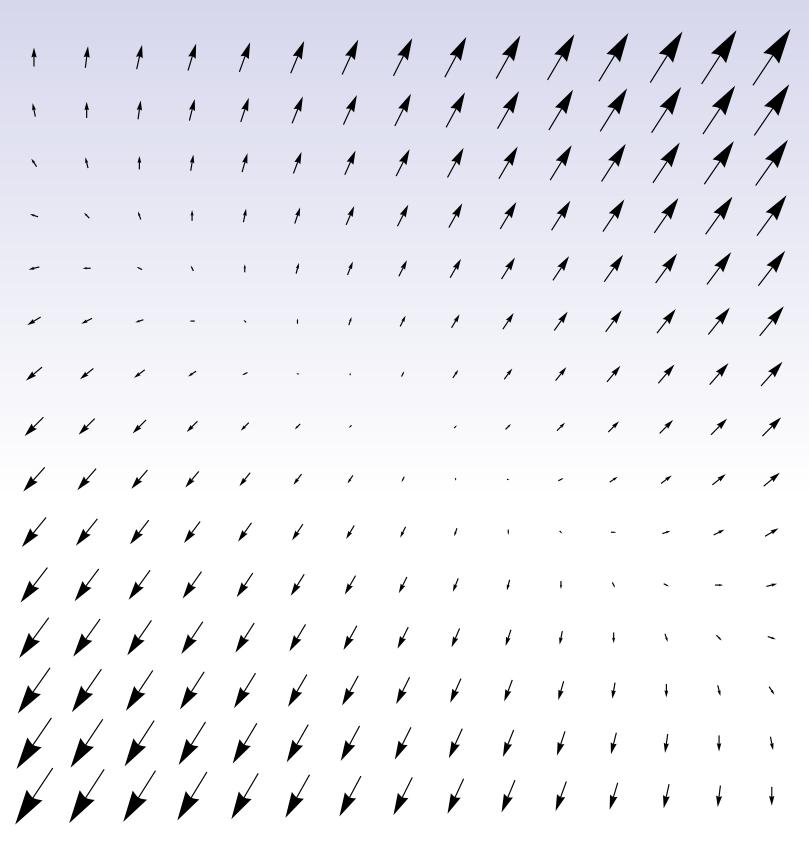
 $d \circ d = 0$ exactness

for k = 0, $d\phi(X) = D_X \phi$ $d(\alpha \wedge \beta) = d\alpha \wedge \beta + (-1)^k \alpha \wedge d\beta$ Why?

Review: Curl of Gradient



Key idea: exterior derivative should capture a similar idea.



grad ϕ

curl \circ grad ϕ

What Happens if $d \circ d = 0$?

A: $d\alpha = d(udx + vdy + wdz) = du \wedge dx$

$$\begin{pmatrix} \frac{\partial u}{\partial x}dx + \frac{\partial u}{\partial y}dy + \frac{\partial u}{\partial z}dz \end{pmatrix} \wedge dx + \\ & \left(\frac{\partial v}{\partial x}dx + \frac{\partial v}{\partial y}dy + \frac{\partial v}{\partial z}dz \right) \wedge dy + \\ & \left(\frac{\partial w}{\partial x}dx + \frac{\partial w}{\partial y}dy + \frac{\partial w}{\partial z}dz \right) \wedge dz$$

 $= -\frac{\partial u}{\partial y}dx \wedge dy + \frac{\partial u}{\partial z}dz \wedge dx + \frac{\partial v}{\partial x}dx \wedge dy = \left(\frac{\partial w}{\partial y} - \frac{\partial v}{\partial z}\right) dy \wedge dz + \left(\frac{\partial u}{\partial z} - \frac{\partial w}{\partial x}\right) dz \wedge dx - \frac{\partial w}{\partial x} dz + \frac{\partial w}{$

Q: Does this operation remind you of anything (*perhaps from vector calculus*)?

Q: Consider a 1-form $\alpha = udx + vdy + wdz$, where the coefficients *u*, *v*, *w* are each scalar functions $\mathbb{R}^3 \to \mathbb{R}$. What is the exterior derivative $d\alpha$ in coordinates x, y, z?

$$+ uddx + dv \wedge dy + vddy + dw \wedge dz + wdd$$

$$(\frac{\partial u}{\partial x}dx \wedge dx + \frac{\partial u}{\partial y}dy \wedge dx + \frac{\partial u}{\partial z}dz \wedge dx) +$$

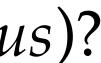
$$= (\frac{\partial v}{\partial x}dx \wedge dy + \frac{\partial v}{\partial y}dy \wedge dy + \frac{\partial v}{\partial z}dz \wedge dy) +$$

$$(\frac{\partial w}{\partial x}dx \wedge dz + \frac{\partial w}{\partial y}dy \wedge dz + \frac{\partial w}{\partial z}dz \wedge dz)^{0}$$

$$\frac{\partial v}{\partial z}dy \wedge dz - \frac{\partial w}{\partial x}dz \wedge dx + \frac{\partial w}{\partial y}dy \wedge dz$$

$$+\left(\frac{\partial v}{\partial x}-\frac{\partial u}{\partial y}\right)dx\wedge dy.$$





Exterior Derivative and Curl Suppose we have a vector field $X := u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}$ Its *curl* is then

$$\begin{array}{l} (\partial w/\partial y \ - \ \partial v/\partial z) \\ \nabla \times X = \ (\partial u/\partial z \ - \ \partial w/\partial x) \\ (\partial v/\partial x \ - \ \partial u/\partial y) \end{array}$$

Looks an awful lot like...

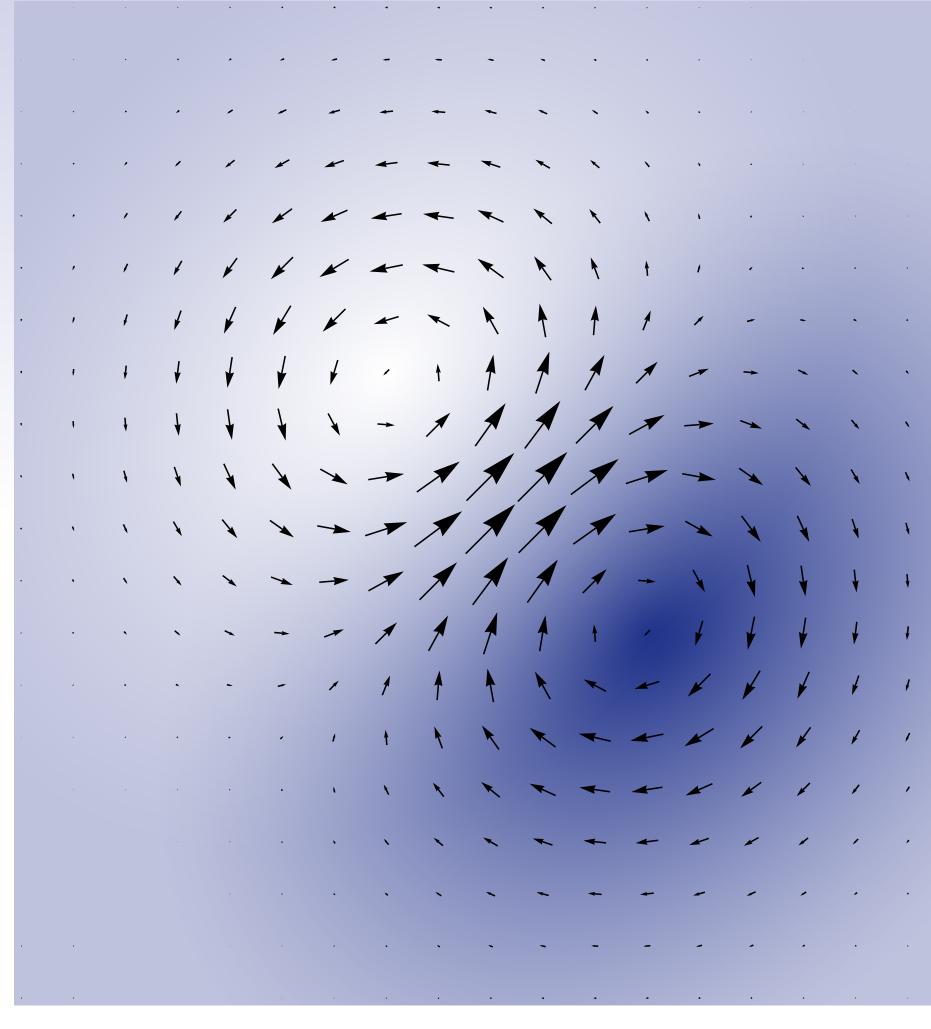
$$d\alpha = \begin{pmatrix} \frac{\partial w}{\partial y} & - \frac{\partial v}{\partial z} \end{pmatrix} dy \wedge dz$$

$$\frac{\partial u}{\partial z} & - \frac{\partial w}{\partial x} \end{pmatrix} dz \wedge dx$$

$$\frac{\partial v}{\partial x} & - \frac{\partial u}{\partial y} dx \wedge dy$$

Especially if we then apply the *Hodge star*.

 $\frac{\partial x}{\partial y} = \frac{\partial y}{\partial z}$

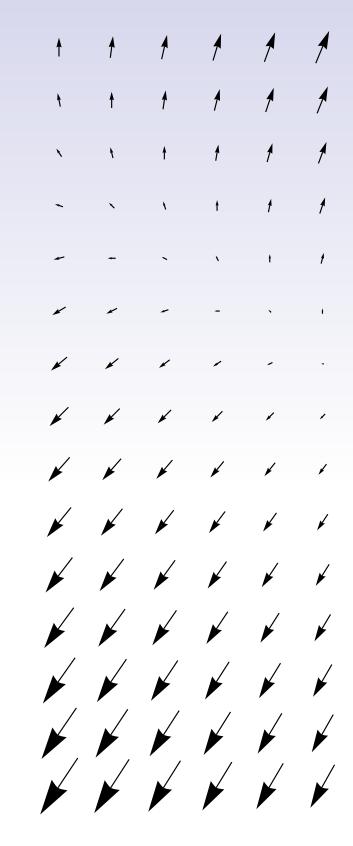


 $\nabla \times X \iff \star d\alpha$

 $\nabla \times X = (\star dX^{\flat})^{\sharp}$

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$d \circ d = 0$



Intuition: in *Rⁿ*, first *d* behaves just like gradient; second *d* behaves just like curl.

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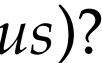
ddφ

Exterior Derivative in 3D (1-forms)

Q: How about $d \star \alpha$? (Still for $\alpha = udx + vdy + wdz$.)

A: $d \star \alpha = d(\star (udx + vdy + wdz))$ $= d(udy \wedge dz + vdz \wedge dx + wdx \wedge dy)$ $= du \wedge dy \wedge dz + dv \wedge dz \wedge dx + dw \wedge dx \wedge dy$ $= \frac{\partial u}{\partial x}dx \wedge dy \wedge dz + \frac{\partial v}{\partial u}dy \wedge dz \wedge dx + \frac{\partial w}{\partial z}dz \wedge dx \wedge dy$ $= \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) dx \wedge dy \wedge dz$

Q: Does this operation remind you of anything (*perhaps from vector calculus*)?



Exterior Derivative and
Suppose we have a vector field
$$X := u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}$$
Its divergence is then

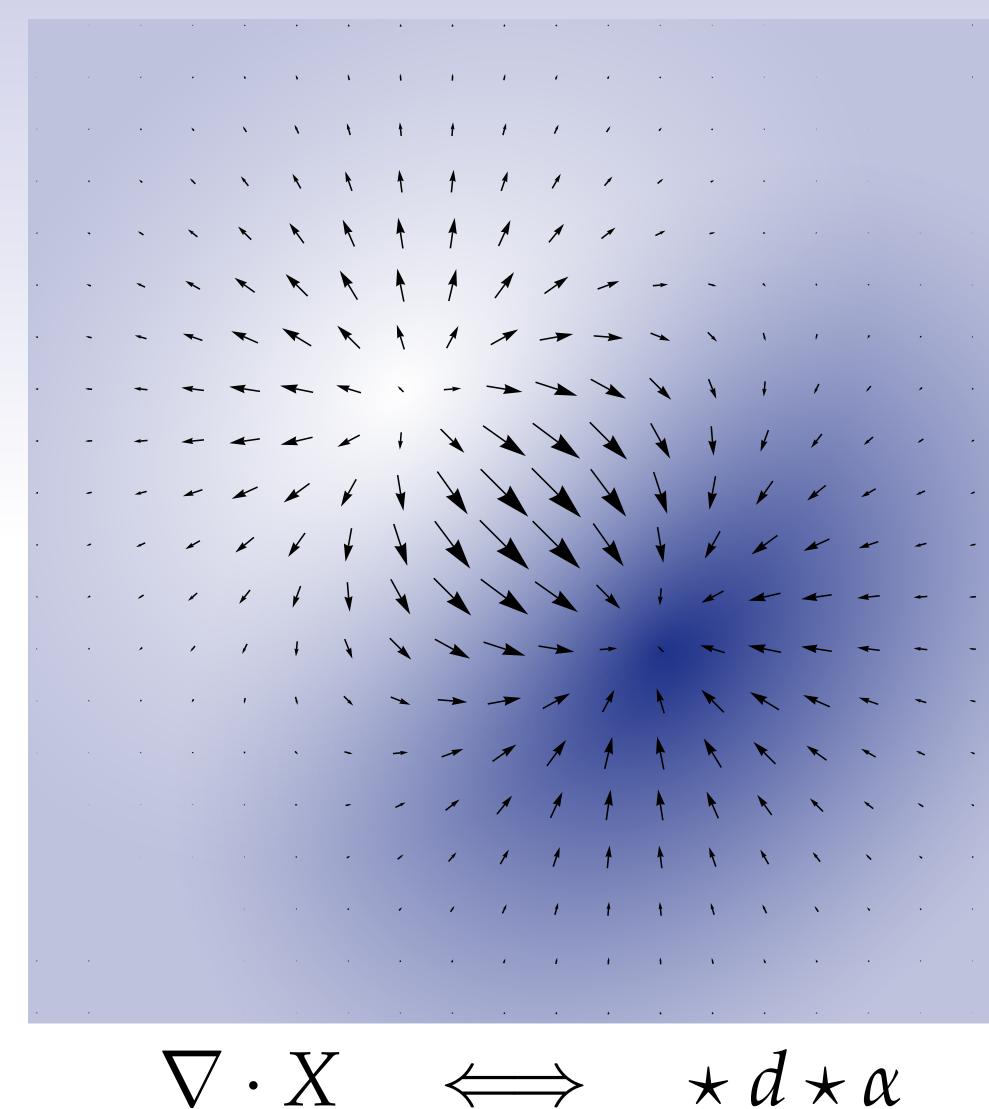
$$\nabla \cdot X = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial u} + \frac{\partial w}{\partial z}$$

Looks an awful lot like...

$$d \star \alpha = \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}\right) dx \wedge dy$$

Especially if we then apply the *Hodge star*.

d Divergence



 $\wedge dz$

 $\nabla \cdot X = \star d \star X^{\flat}$



Exterior Derivative - Divergence

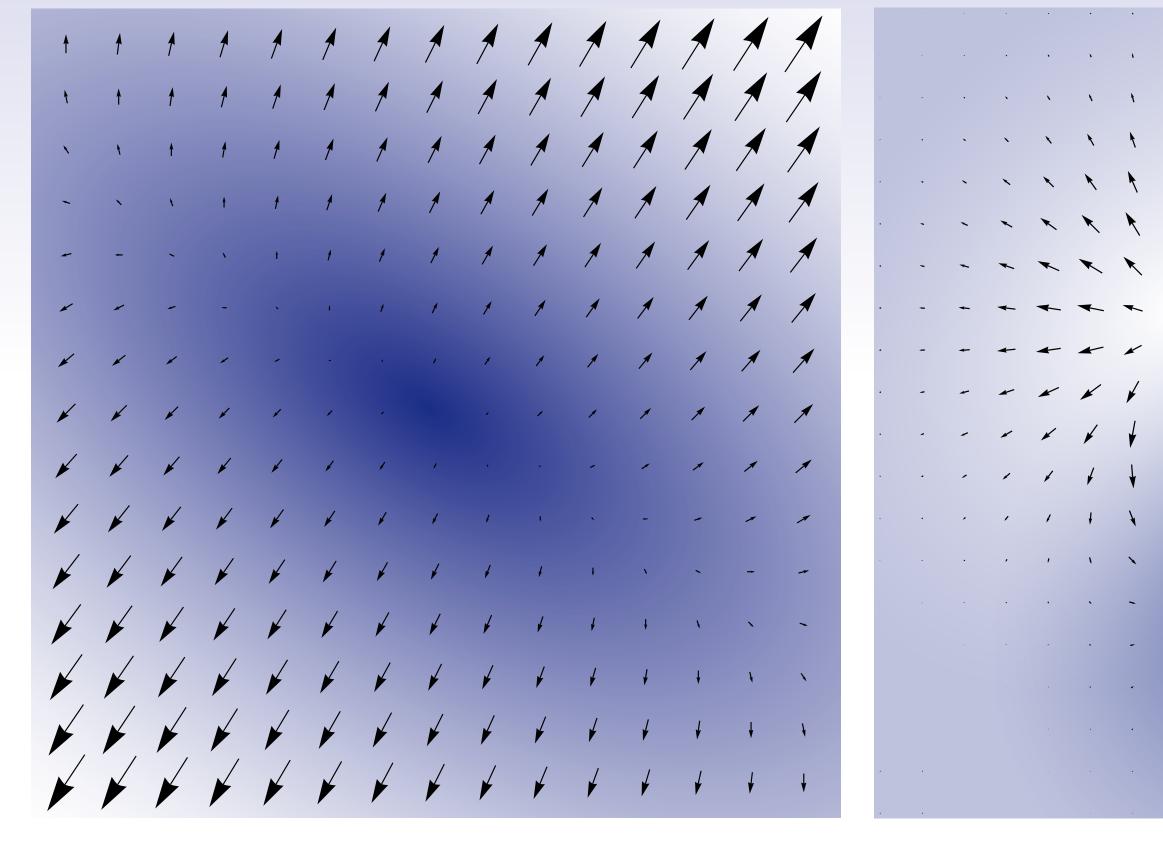
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 $\nabla \cdot X = \star d(\star X^{\flat})$

(codifferential: $\delta := \star d \star$)



Exterior vs. Vector Derivatives – Summary



grad ϕ $(d\phi)^{\sharp}$

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div X $\star d(\star X^{\flat})$

curl Y $(\star (dX^{\flat}))^{\sharp}$

Exterior Derivative

Unique *linear* map $d : \Omega^k \to \Omega^{k+1}$ such that

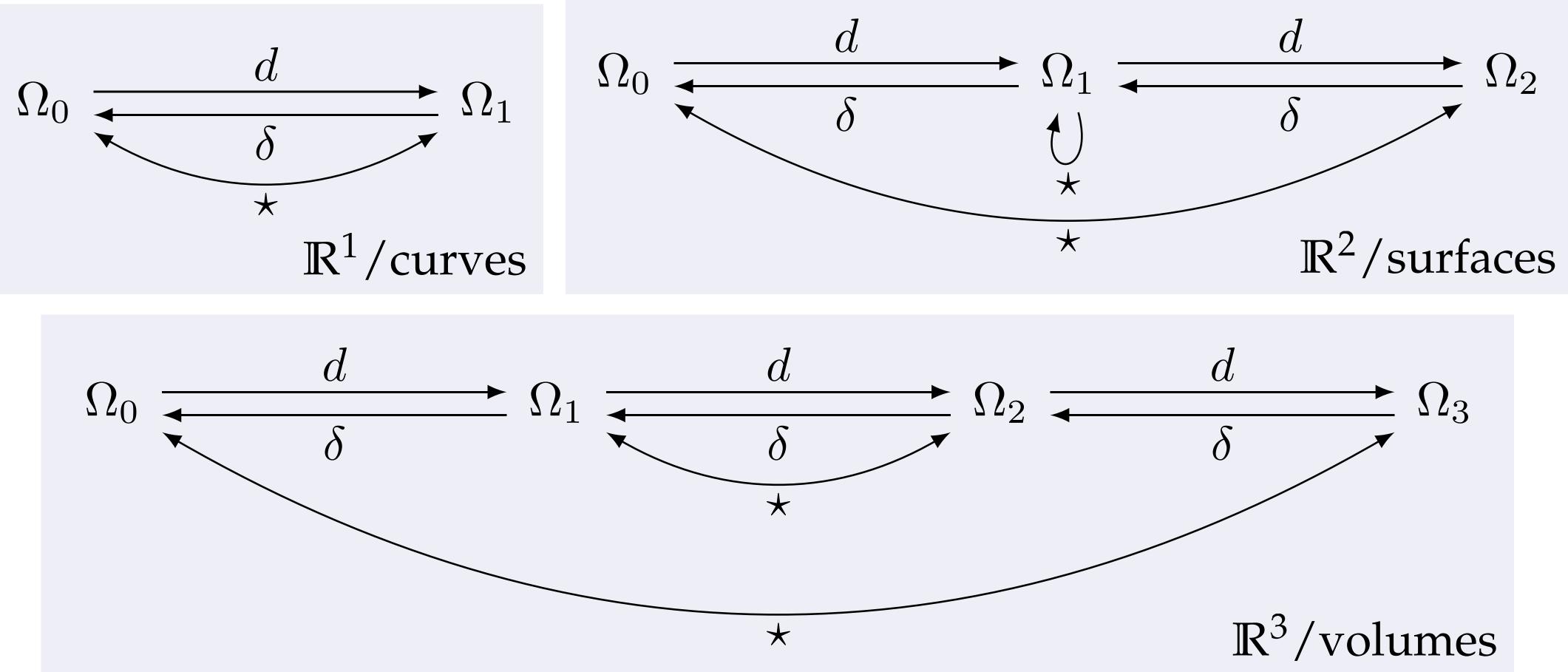
differential product rule $d \circ d = 0$ exactness

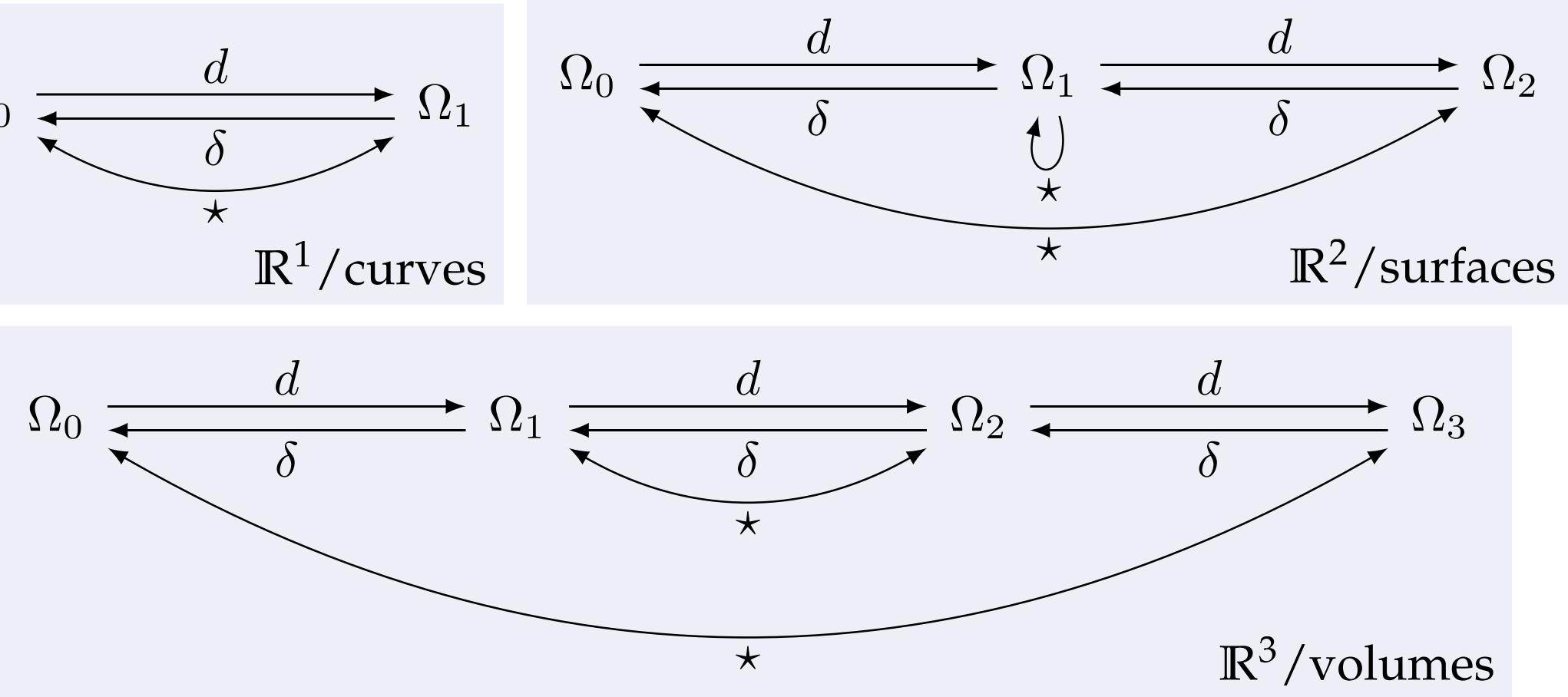
for k = 0, $d\phi(X) = D_X \phi$ $d(\alpha \wedge \beta) = d\alpha \wedge \beta + (-1)^k \alpha \wedge d\beta$

Exterior Derivative – Summary

Exterior Calculus – Diagram View

• Taking a step back, we can draw many of the operators seen so far as diagrams:





Ω_k —differential *k*-forms

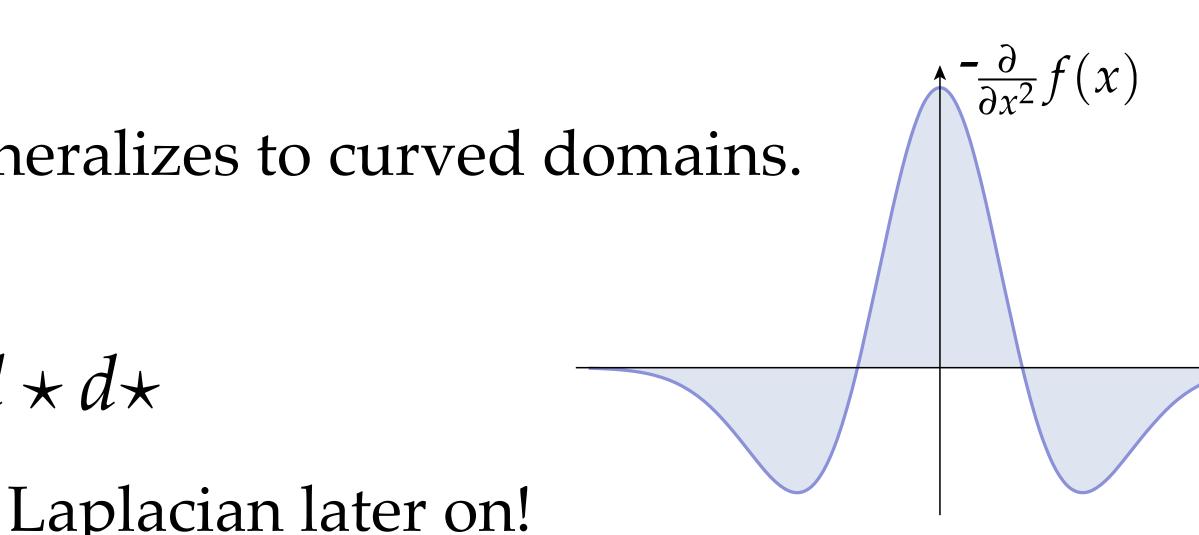
Laplacian

- Can now compose operators to get other operators
- E.g., *Laplacian* from vector calculus:

$$\Delta := \operatorname{div} \circ \operatorname{grad}$$

- Can express exact same operator via exterior calculus: $\Lambda = \star d \star d$
- ...except that this expression easily generalizes to curved domains.
- Can also generalize to *k*-forms:
 - $\Delta := \star d \star d + d \star d \star$

• Will have **much** more to say about the Laplacian later on!





f(x)



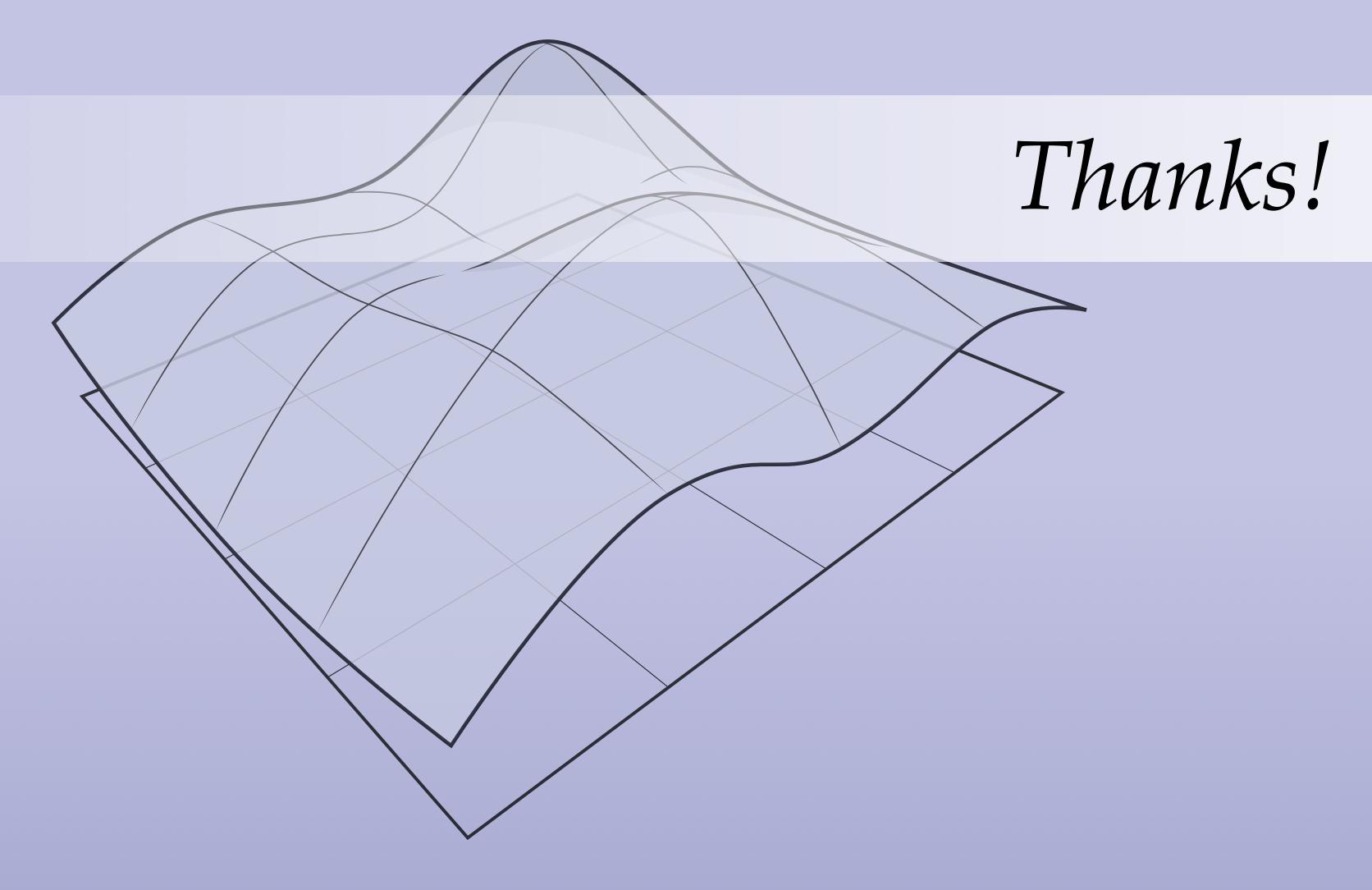
Exterior Derivative - Summary

- Exterior derivative d used to differentiate k-forms
 - 0-form: "gradient"
 - 1-form: "curl"
 - 2-form: "divergence" (codifferential δ)
 - and more...
- Natural product rule
- d of d is zero
 - Analogy: curl of gradient
 - More general picture (soon!) via *Stokes' theorem*









DISCRETE DIFFERENTIAL GEOMETRY AN APPLIED INTRODUCTION