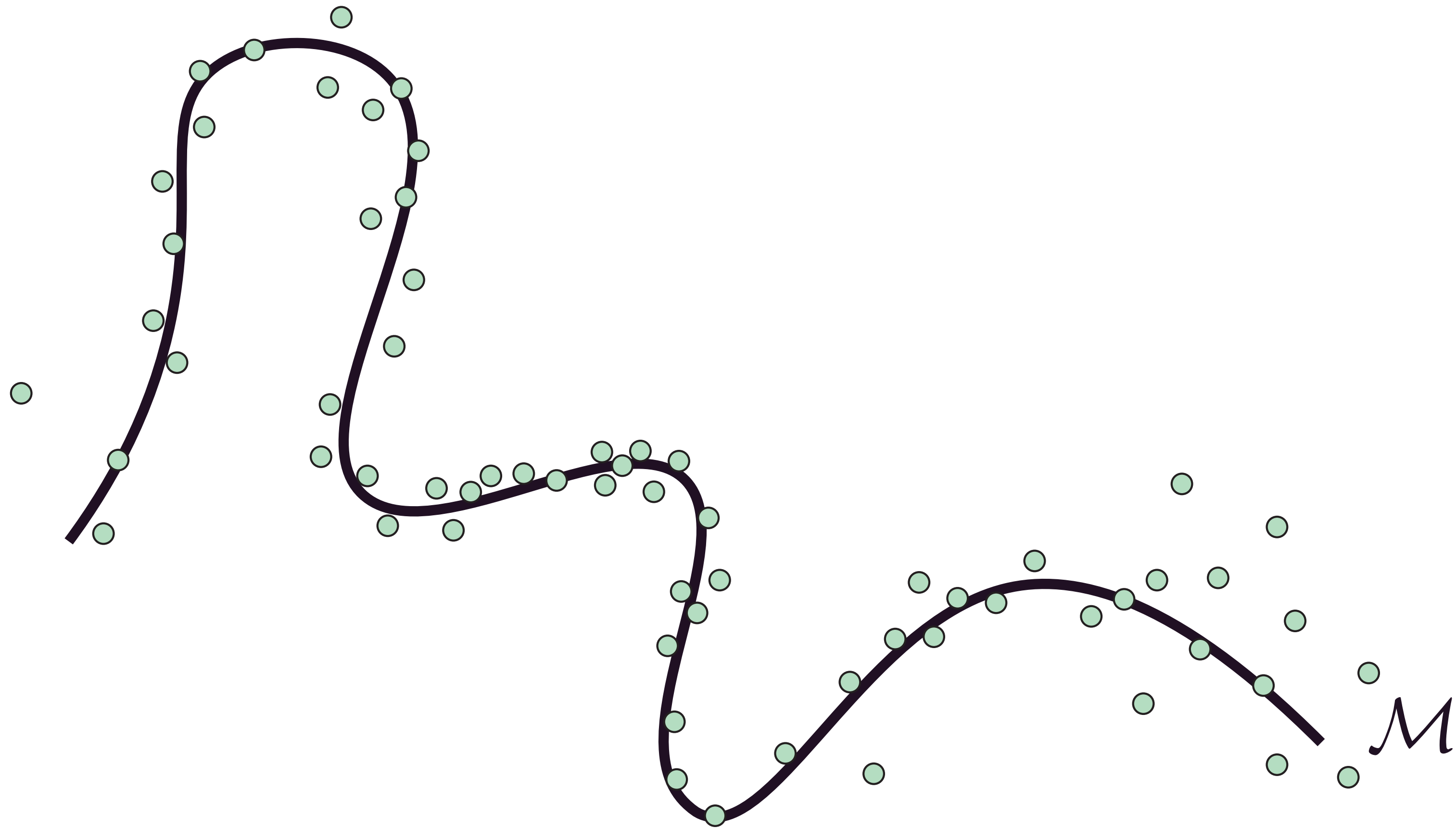




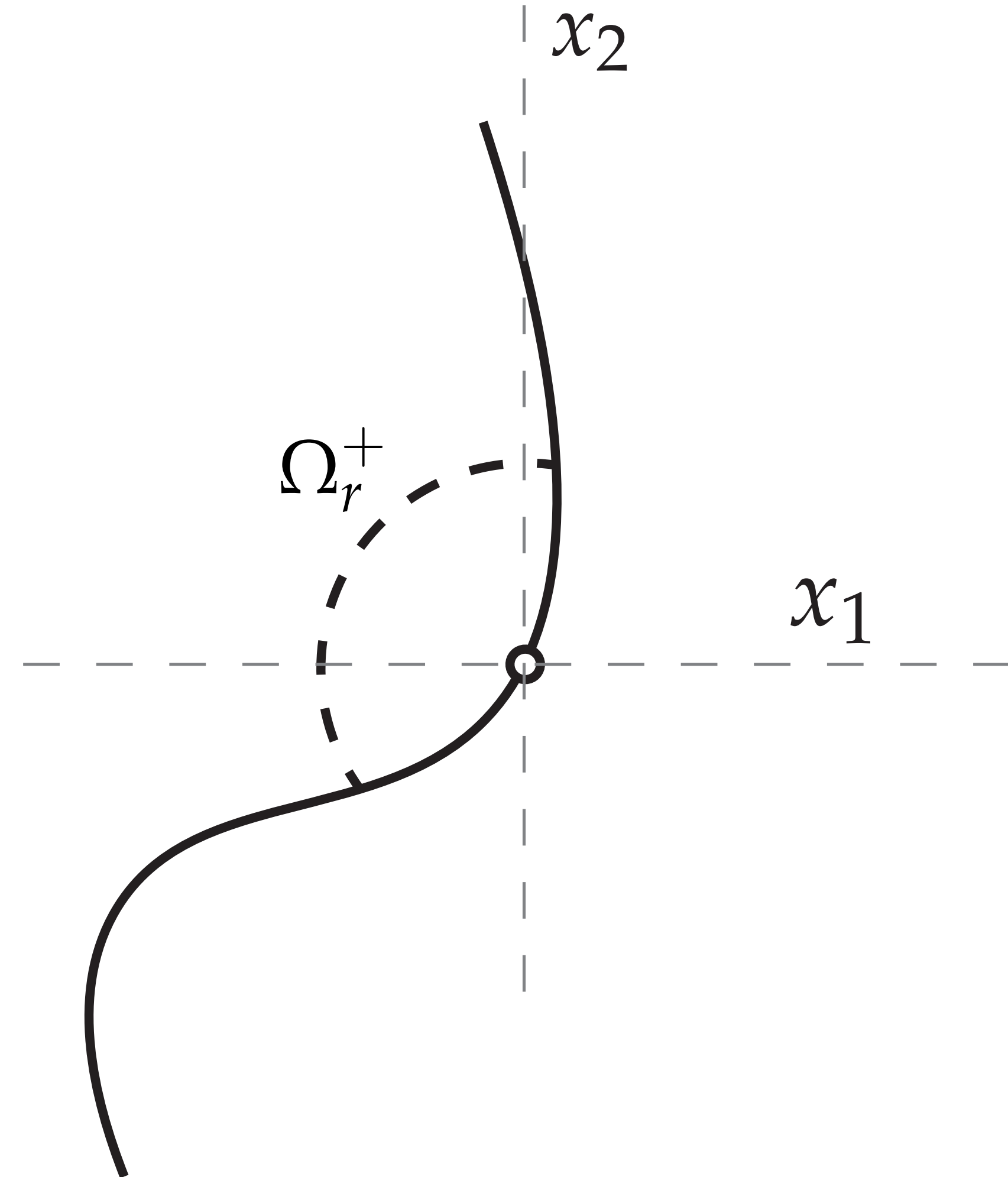
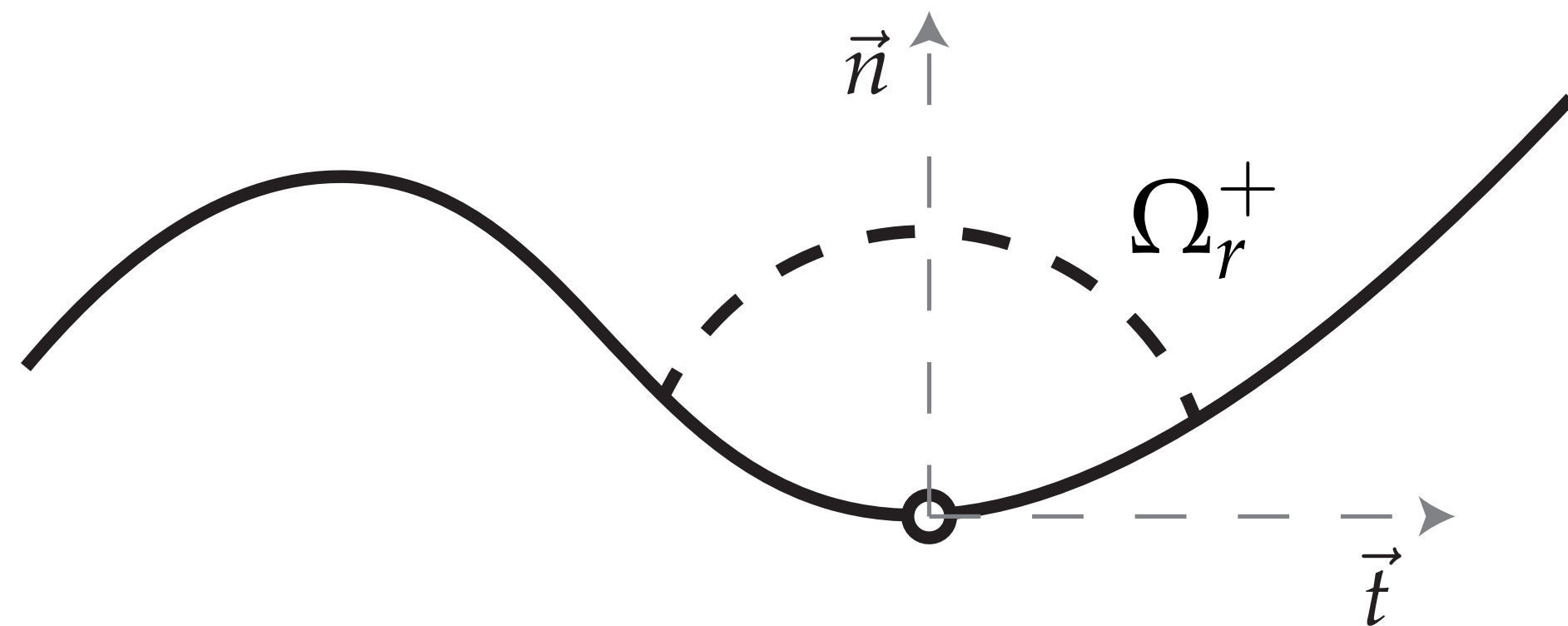
*Curvature Estimation of High Dimensional Submanifolds Based on Noisy
Observations: Some Results*

Yousuf M. Soliman

Quick Review of Integral Invariants and Curvature Estimation

$$I(f) = \int_{\Omega_r^+} f(\mathbf{x}) \, d\mathbf{x}$$

$$f(x) = \frac{1}{2} \sum_{i=1}^m \kappa_i x_i^2 + \mathcal{O}(\|x\|^3)$$



Quick Review of Integral Invariants and Curvature Estimation

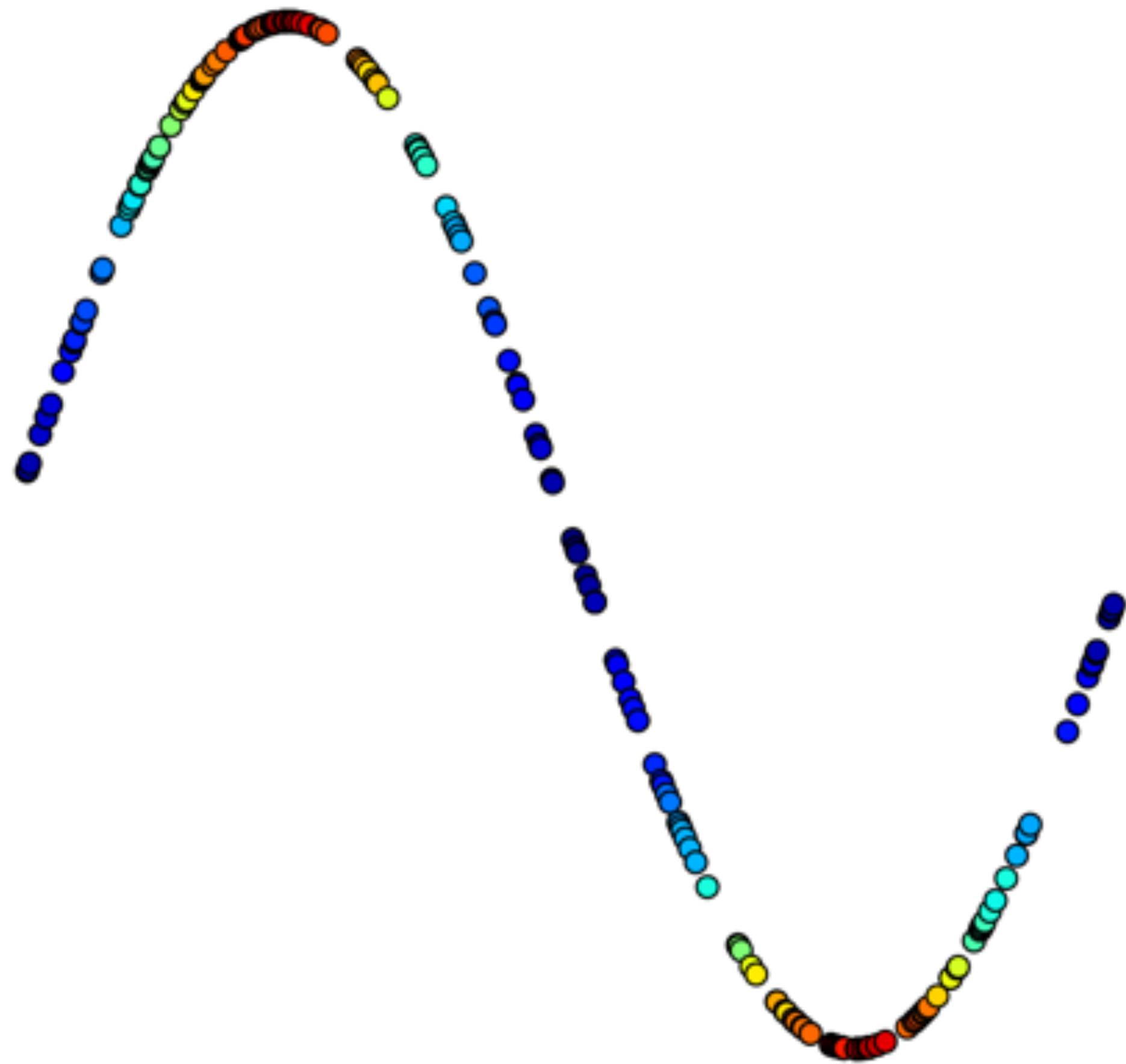
Rather than just computing $I(1)$, we can get better estimates of the curvature by computing the covariance matrix:

$$\begin{aligned}\Sigma(\Omega_r^+) &= \int_{\Omega_r^+} (\mathbf{x} - \mathbf{m})(\mathbf{x} - \mathbf{m})^\top \, d\mathbf{x} \\ &= \begin{pmatrix} I(x^2) & I(xy) \\ I(xy) & I(y^2) \end{pmatrix} - \frac{1}{\text{vol}(\Omega_r^+)} \begin{pmatrix} I(x)^2 & I(x)I(y) \\ I(x)I(y) & I(y)^2 \end{pmatrix}\end{aligned}$$

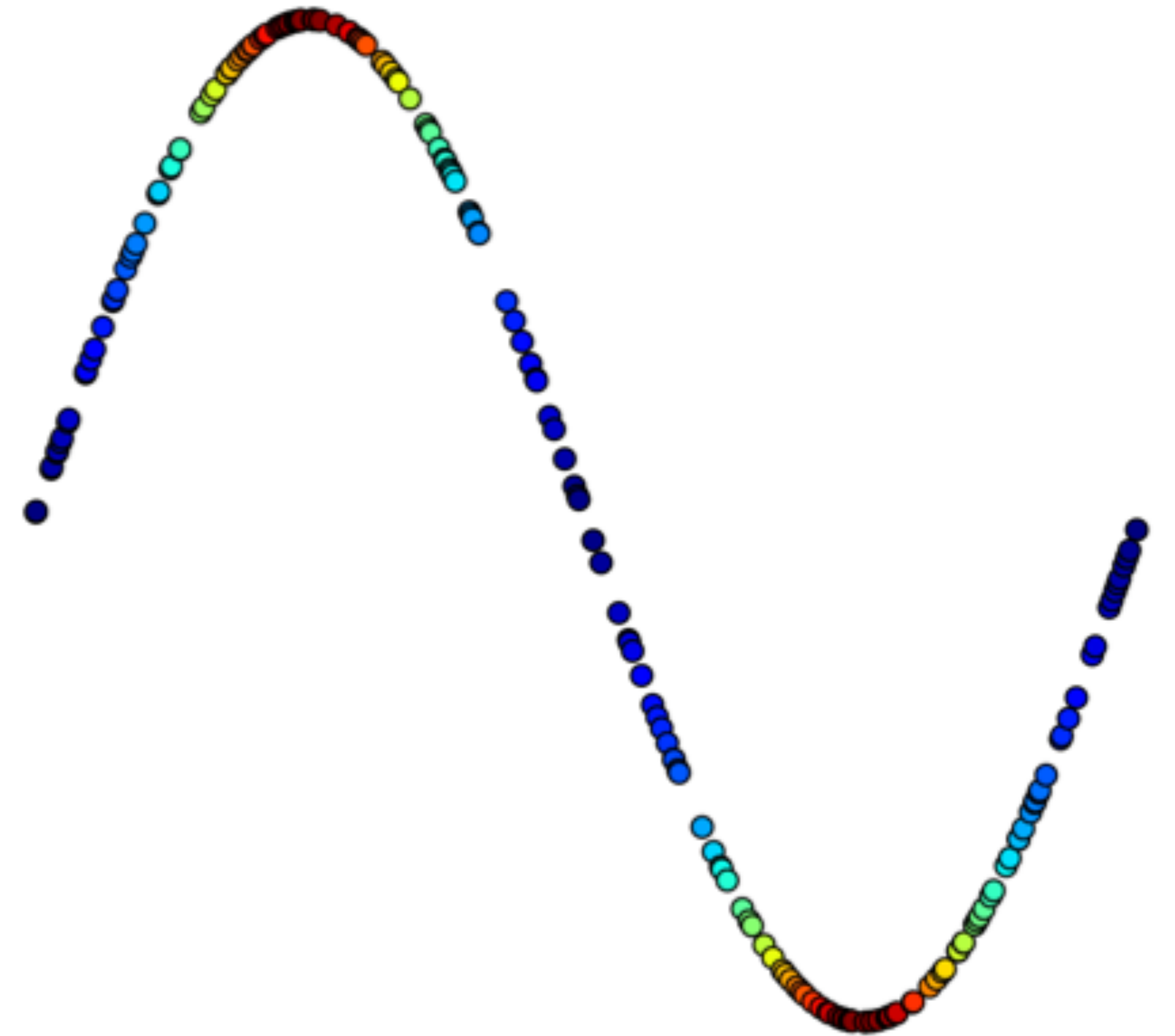
Furthermore, eigenanalysis of the covariance matrix reveals the principal curvatures

Initial Results: ($y = \sin x$)

$n = 200$



Estimation Using Integral Invariants

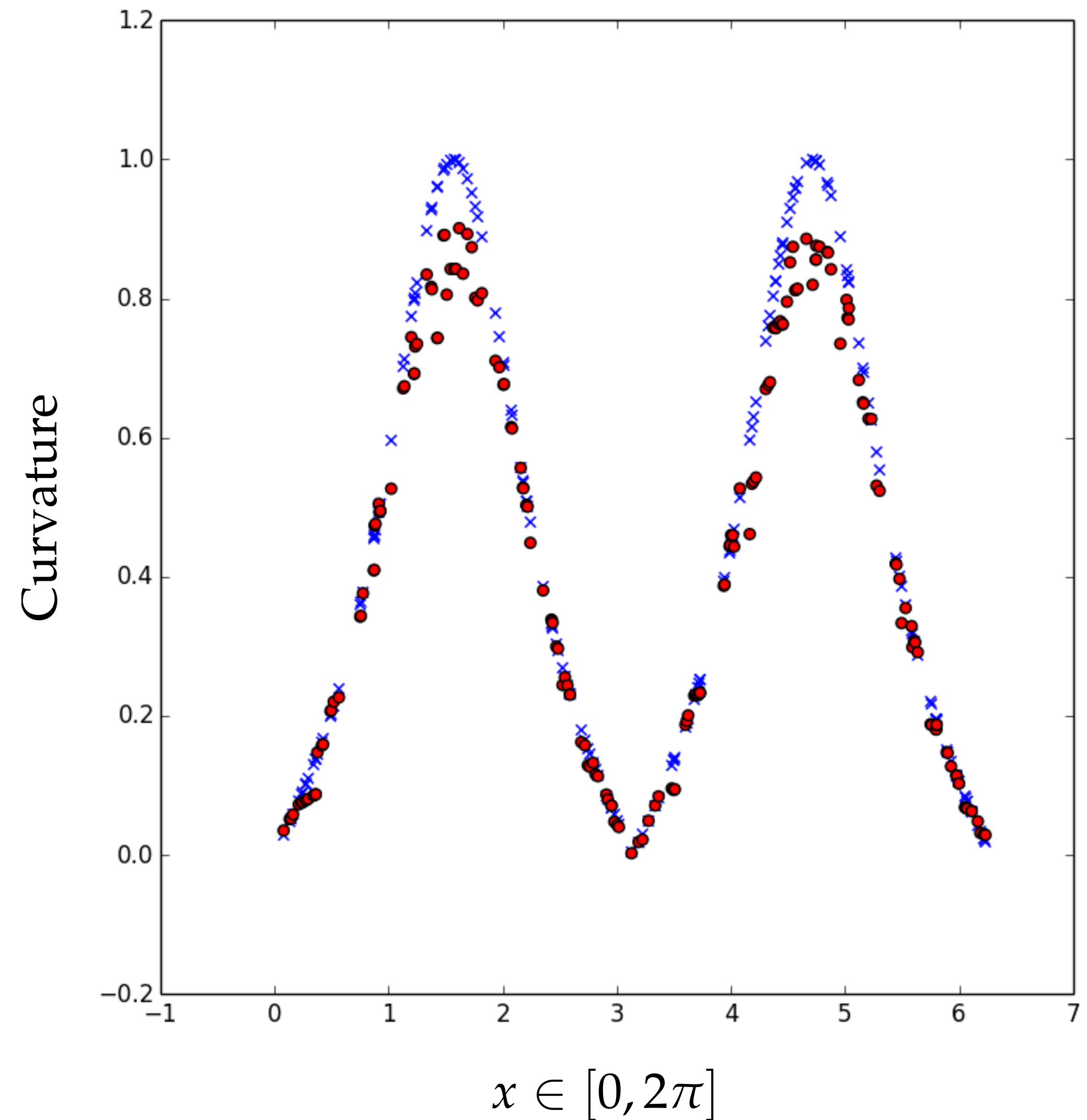


True Curvature

Initial Results: ($y = \sin x$)

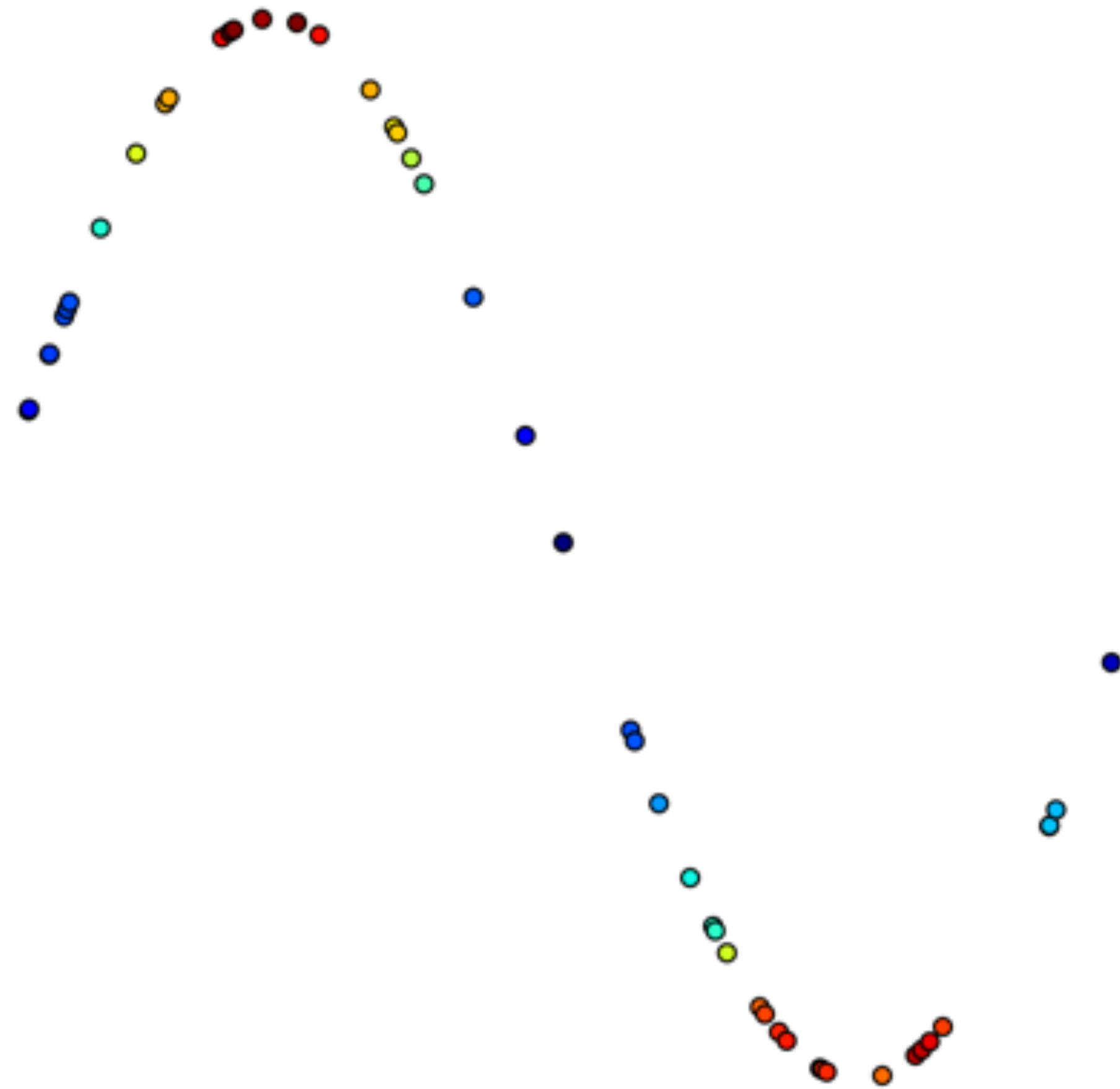
mse ≈ 0.00148

average percent error: $\approx 6\%$



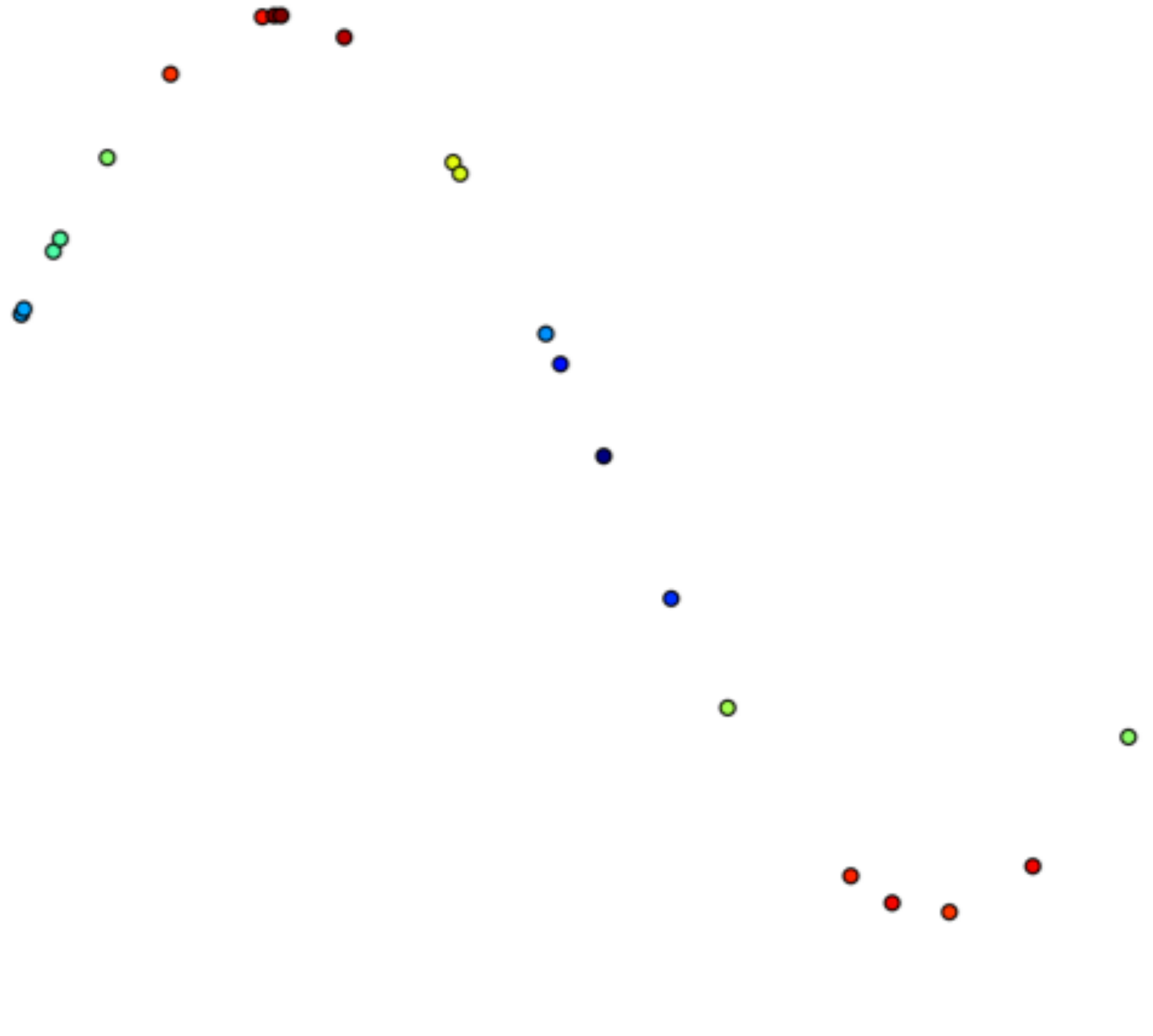
Effects of Sparsity

$n = 50$



$\approx 16\%$ error

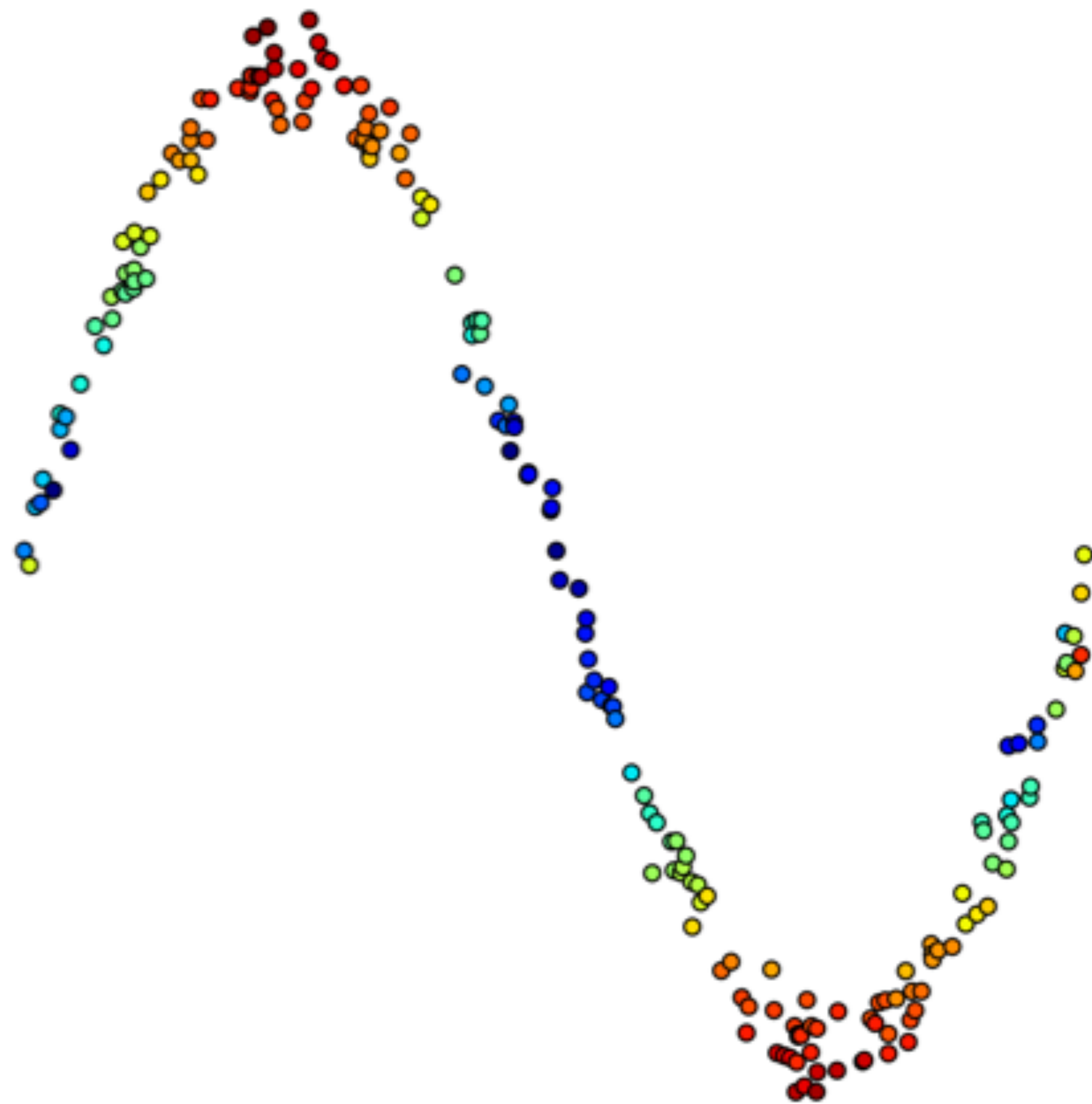
$n = 25$



$\approx 27\%$ error

Effects of Noise

$$\varepsilon_i \sim \mathcal{N}(0, 0.05)$$

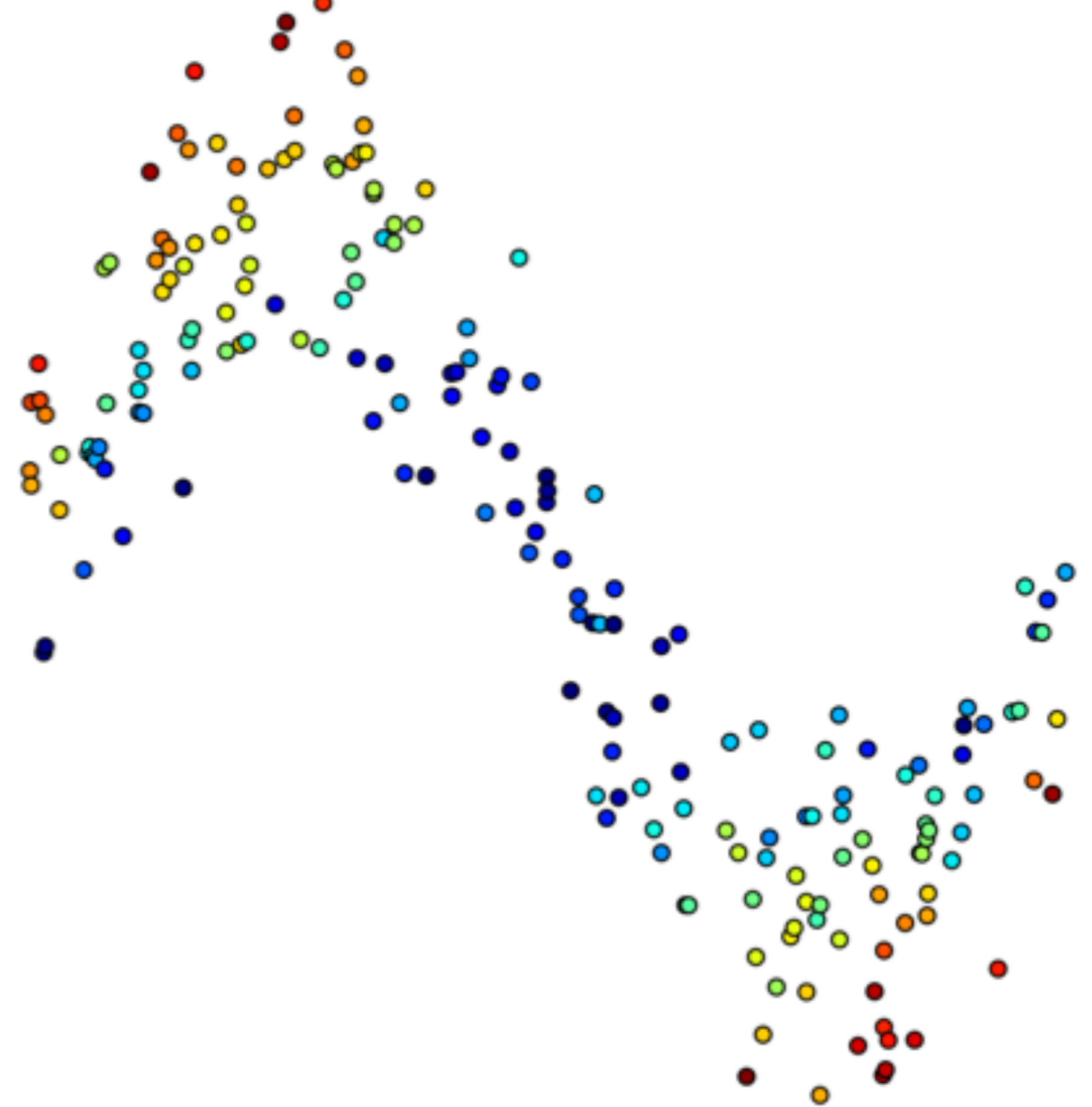


$\approx 52\%$ error

$$y_i = \sin x_i + \varepsilon_i$$

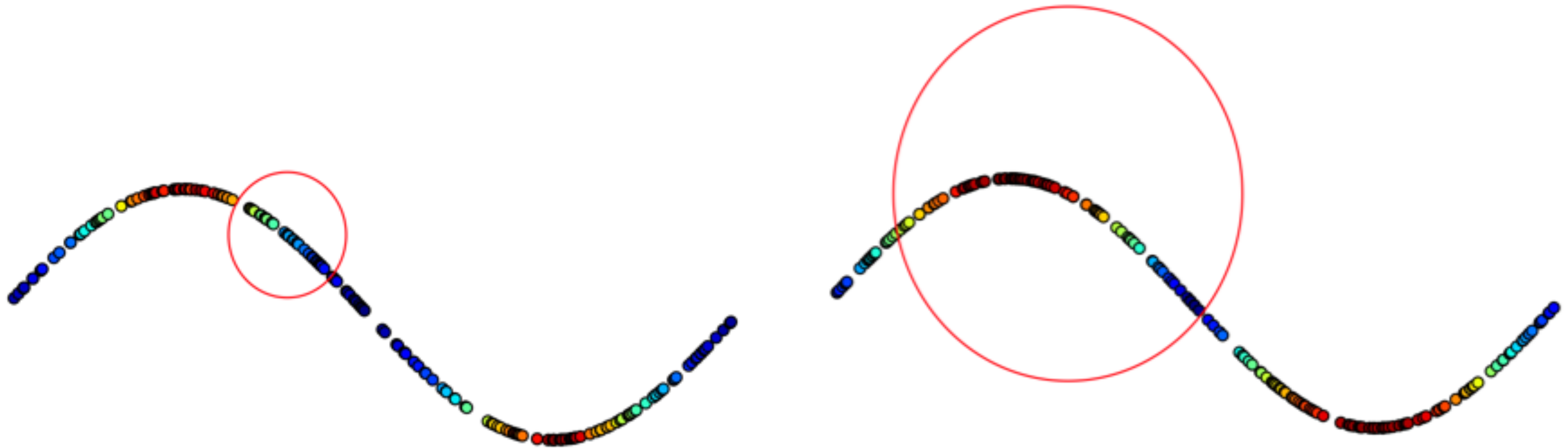
$n = 200$

$$\varepsilon_i \sim \mathcal{N}(0, 0.25)$$



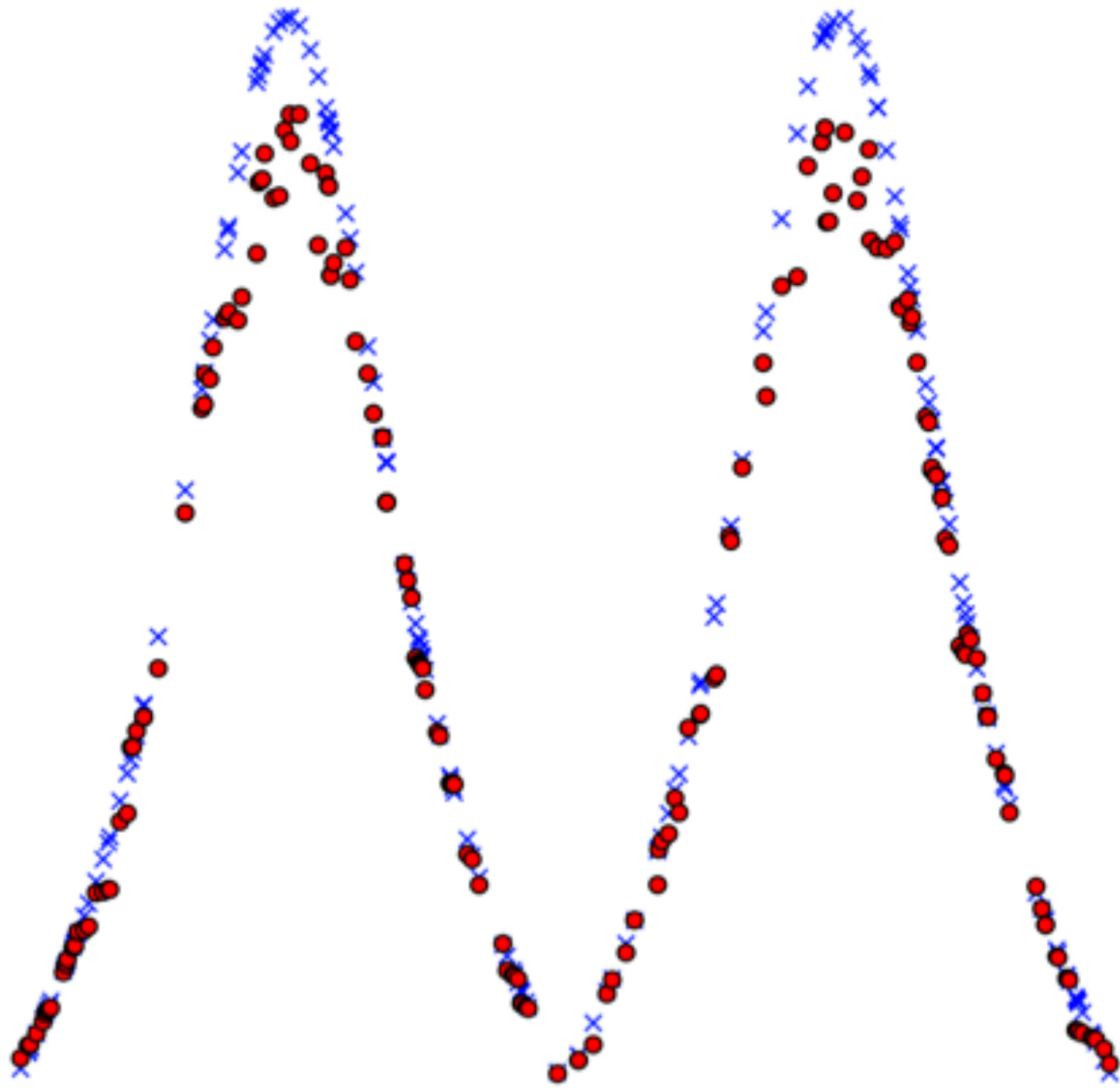
$\approx 112\%$ error

Effects of Smoothing

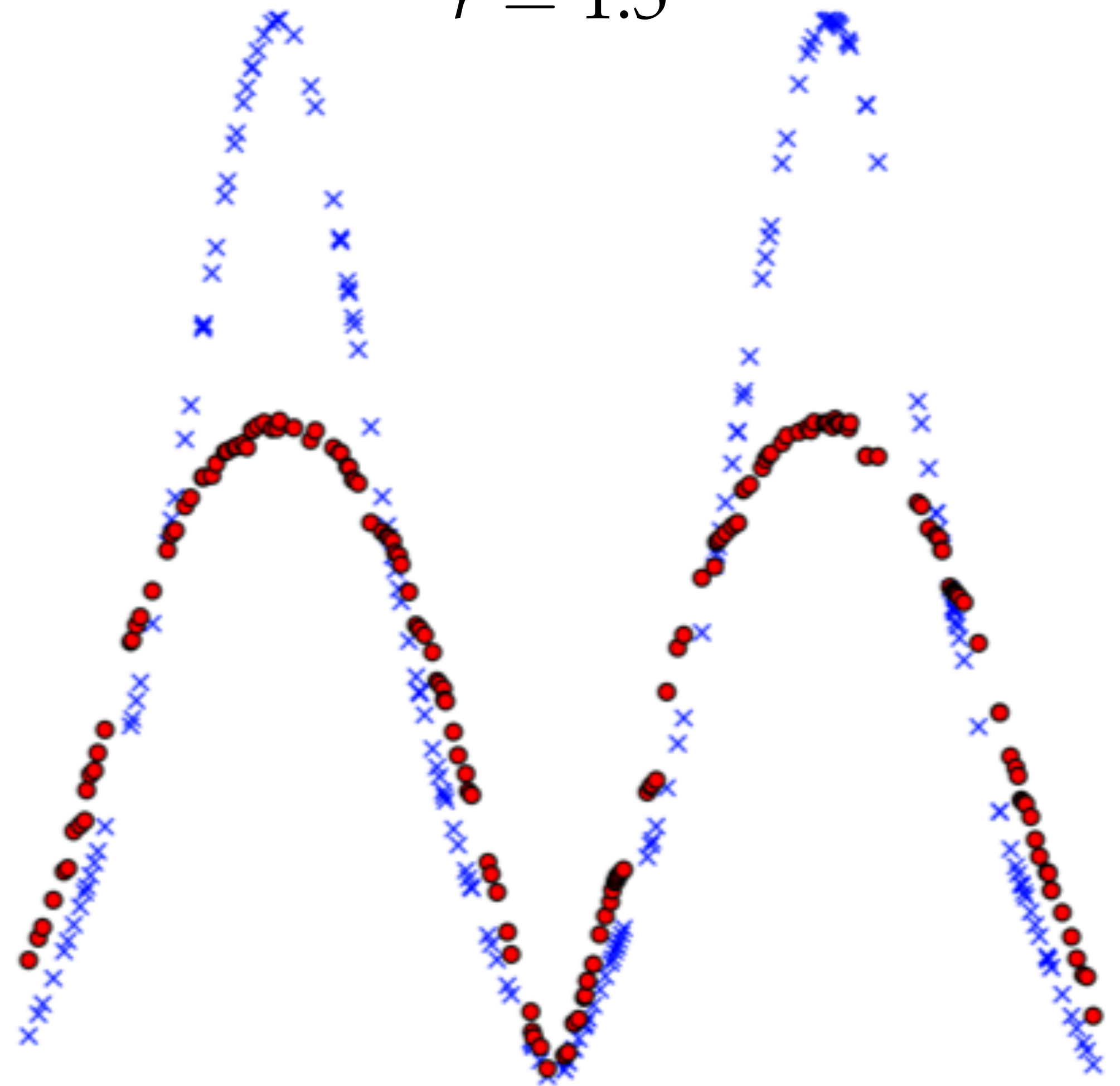


Effects of Smoothing

$r = 0.5$



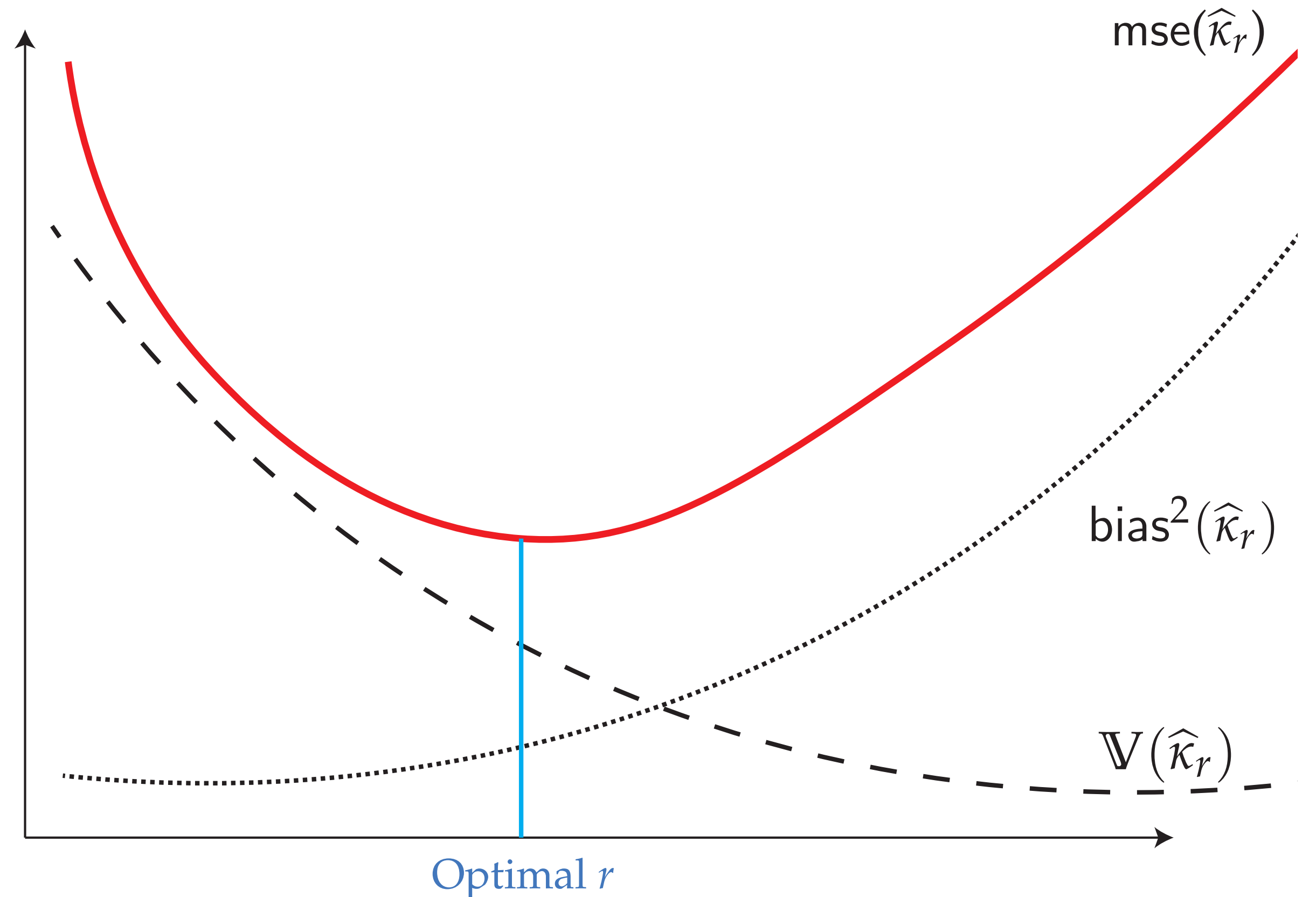
$r = 1.5$



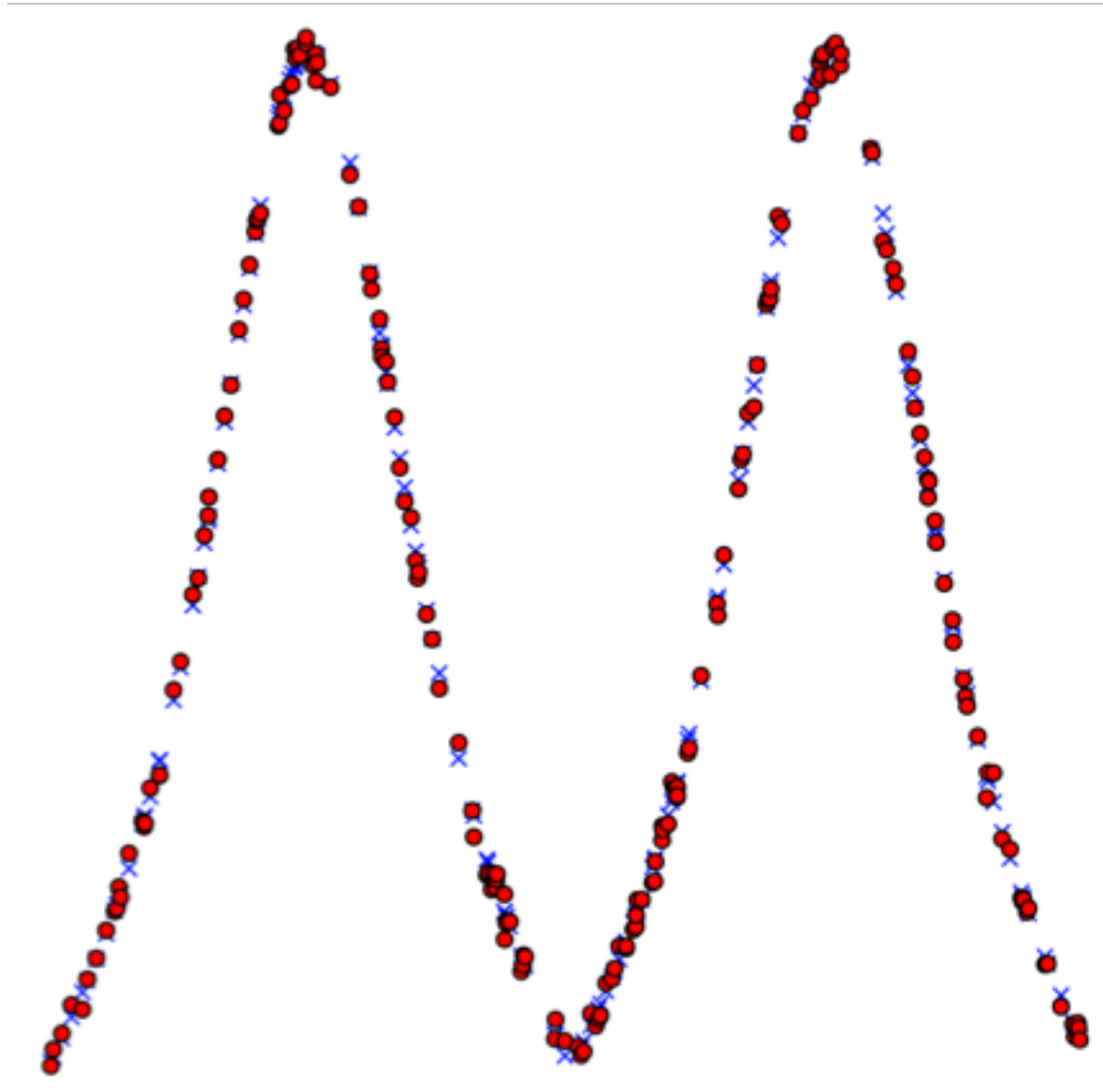
Choosing the Right Scale Using Nonparametric Bootstrap

- Compute an initial estimate $\hat{\kappa}_r$
- Draw n samples with replacement from the empirical distribution
- Compute $\hat{\kappa}_r^*$ with this new sample
- Repeat B times
- Compute the estimated MSE of $\hat{\kappa}_r$
- Choose the scale r that minimizes the MSE of $\hat{\kappa}_r$

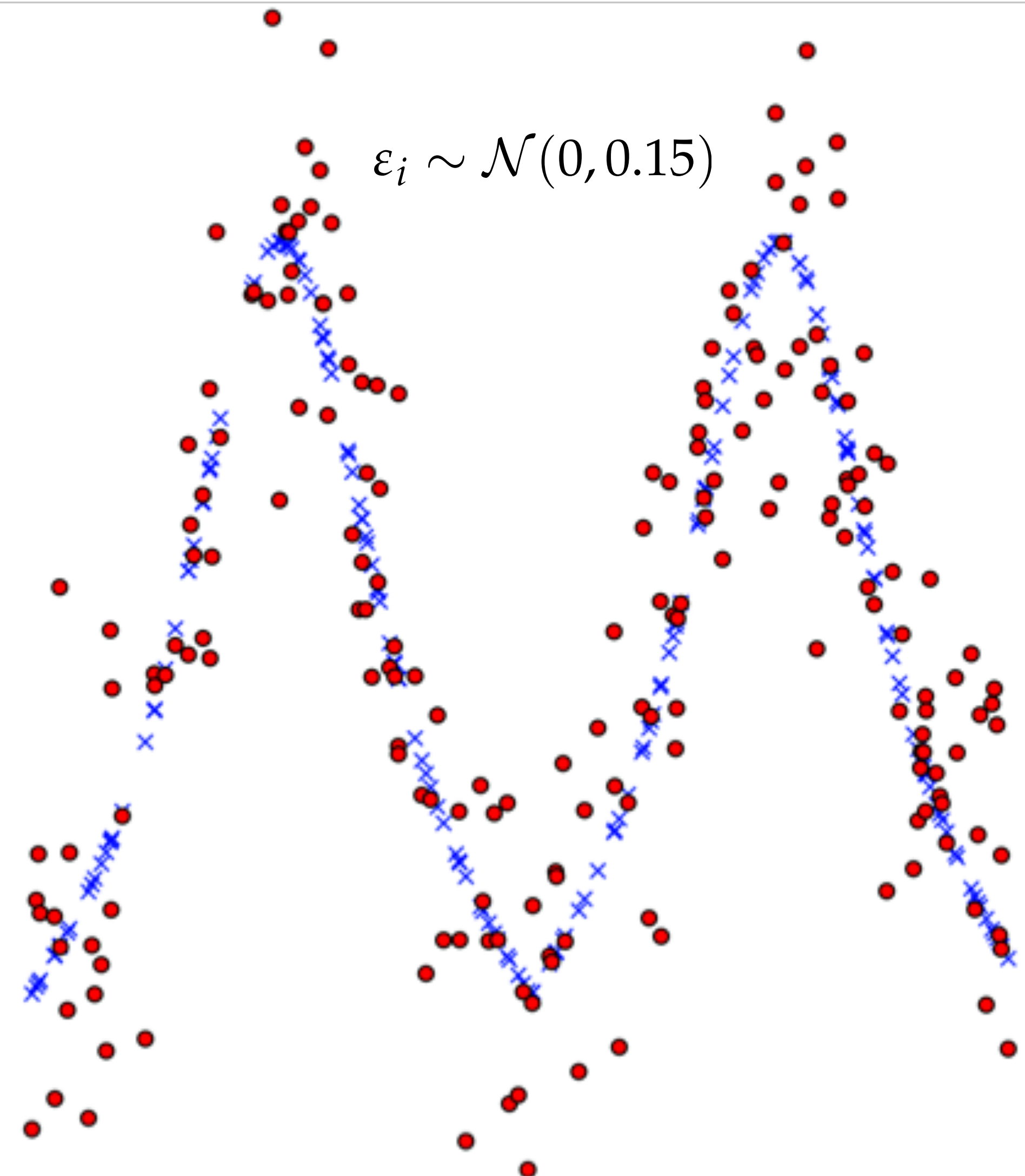
$$\text{mse} = \mathbb{E}(\hat{\kappa}_r - \kappa)^2$$



Choosing the Right Scale Using Nonparametric Bootstrap

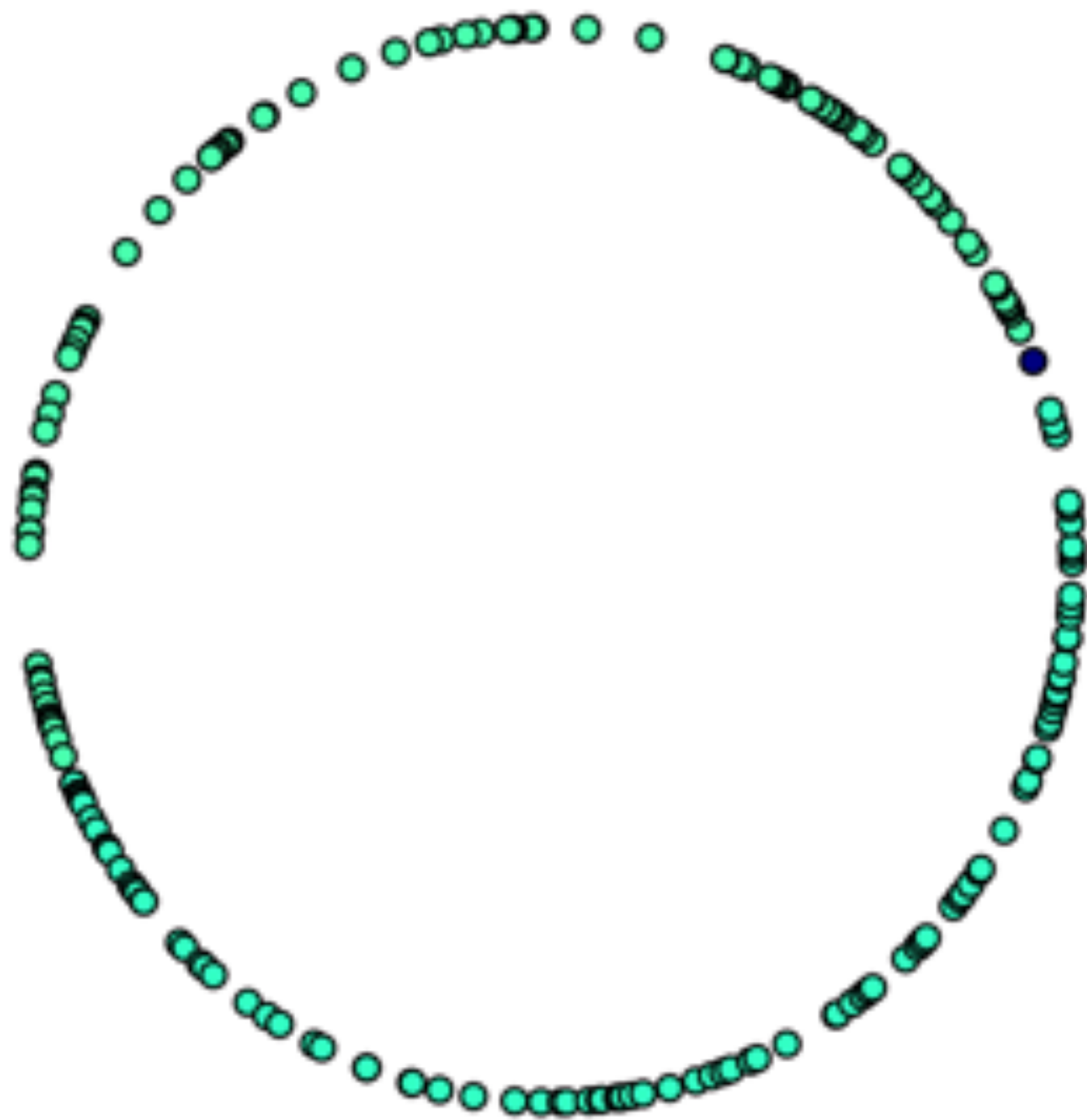


$\approx 0.01\%$ error in the noiseless case

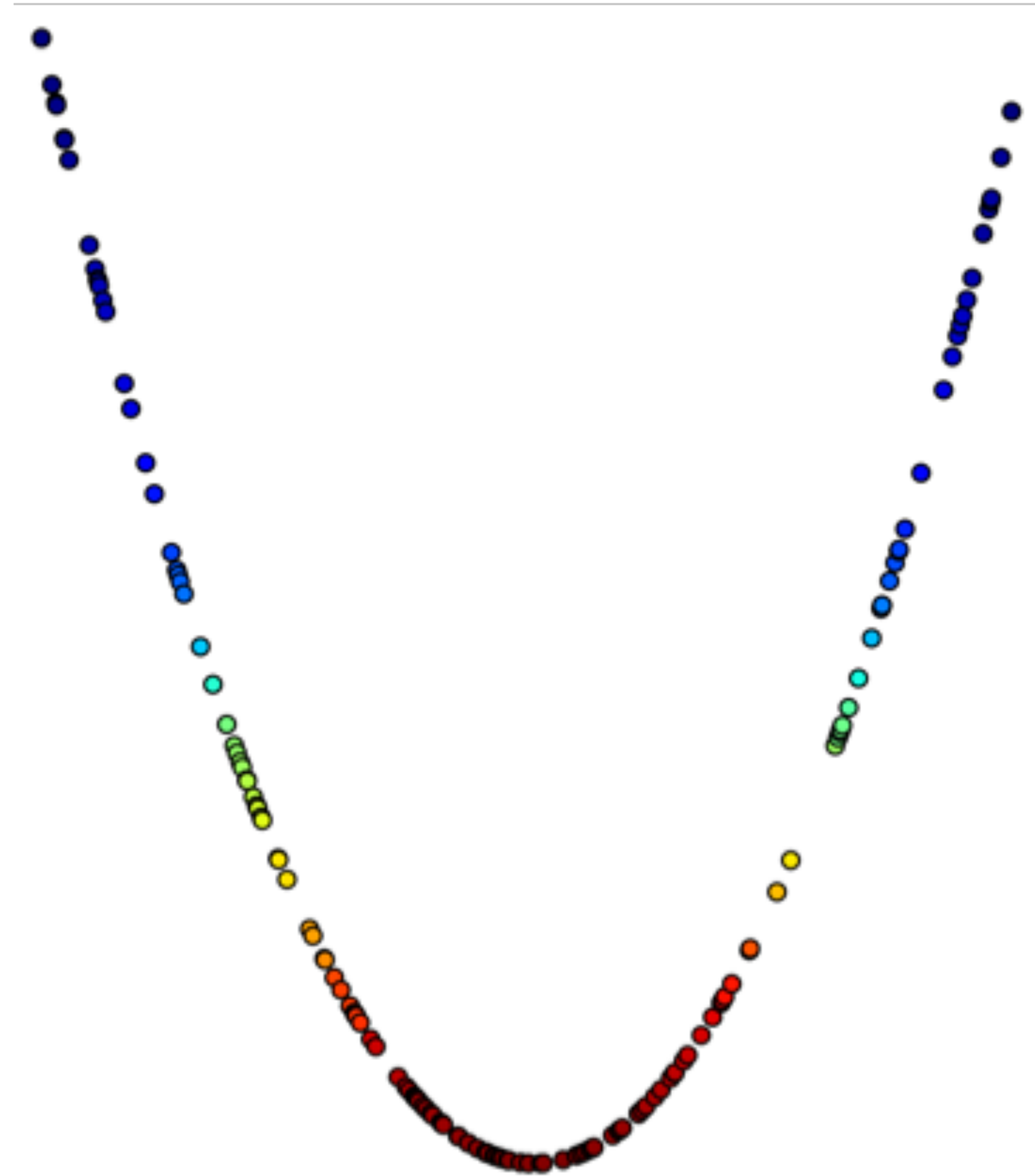


$\approx 28\%$ error in the noisy case

Some Other Functions

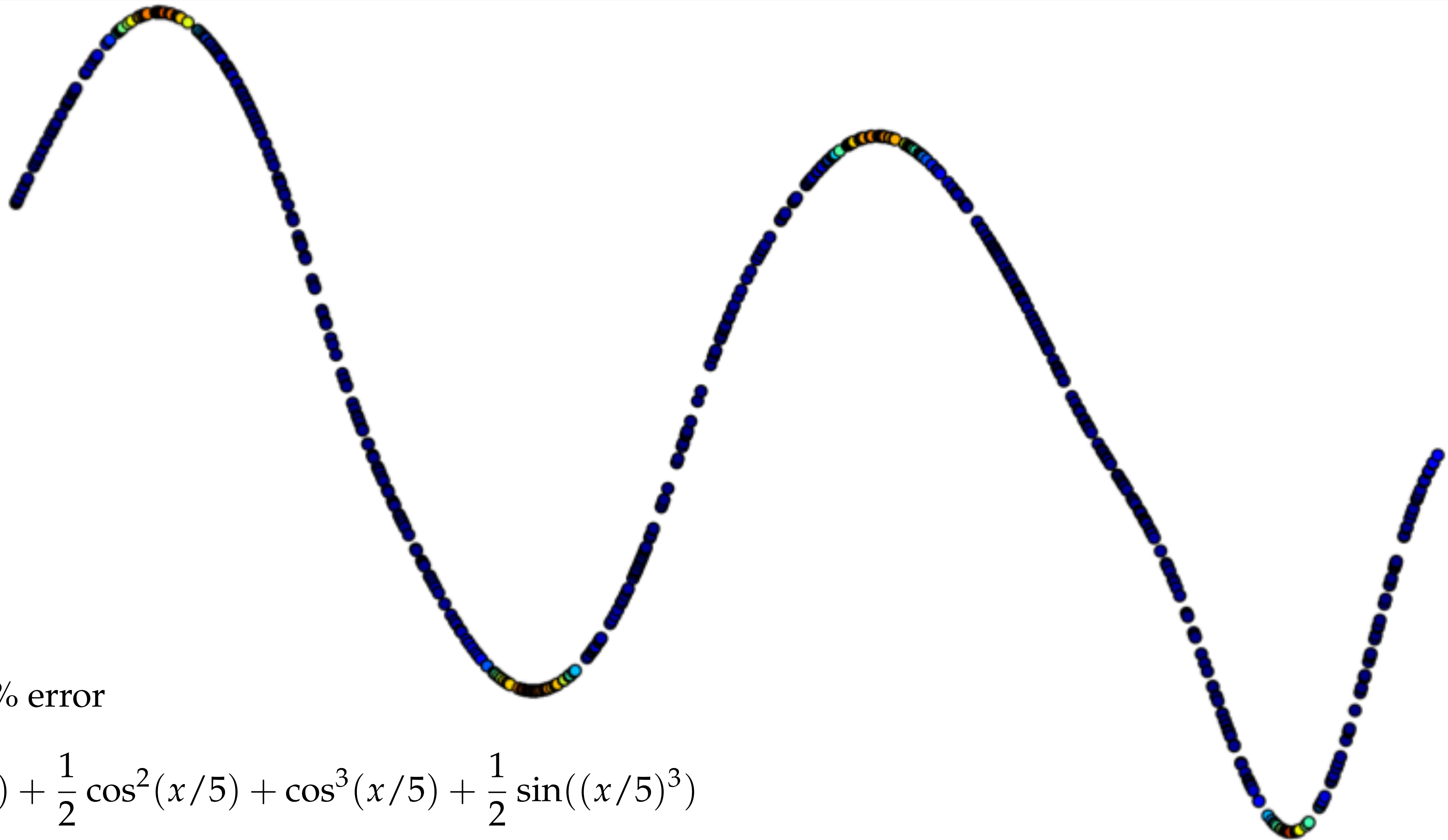


S^1



$f(x) = x^2$

Some Other Functions



≈ 2% error

$$y = 5 \sin(x) + \frac{1}{2} \cos^2(x/5) + \cos^3(x/5) + \frac{1}{2} \sin((x/5)^3)$$

Problems

- Didn't have time for full theoretical analysis
- I'm having trouble with computing numerical integrals bounded by a set of data points in arbitrary dimensions
- Didn't code other techniques to compare them
- Edge Cases