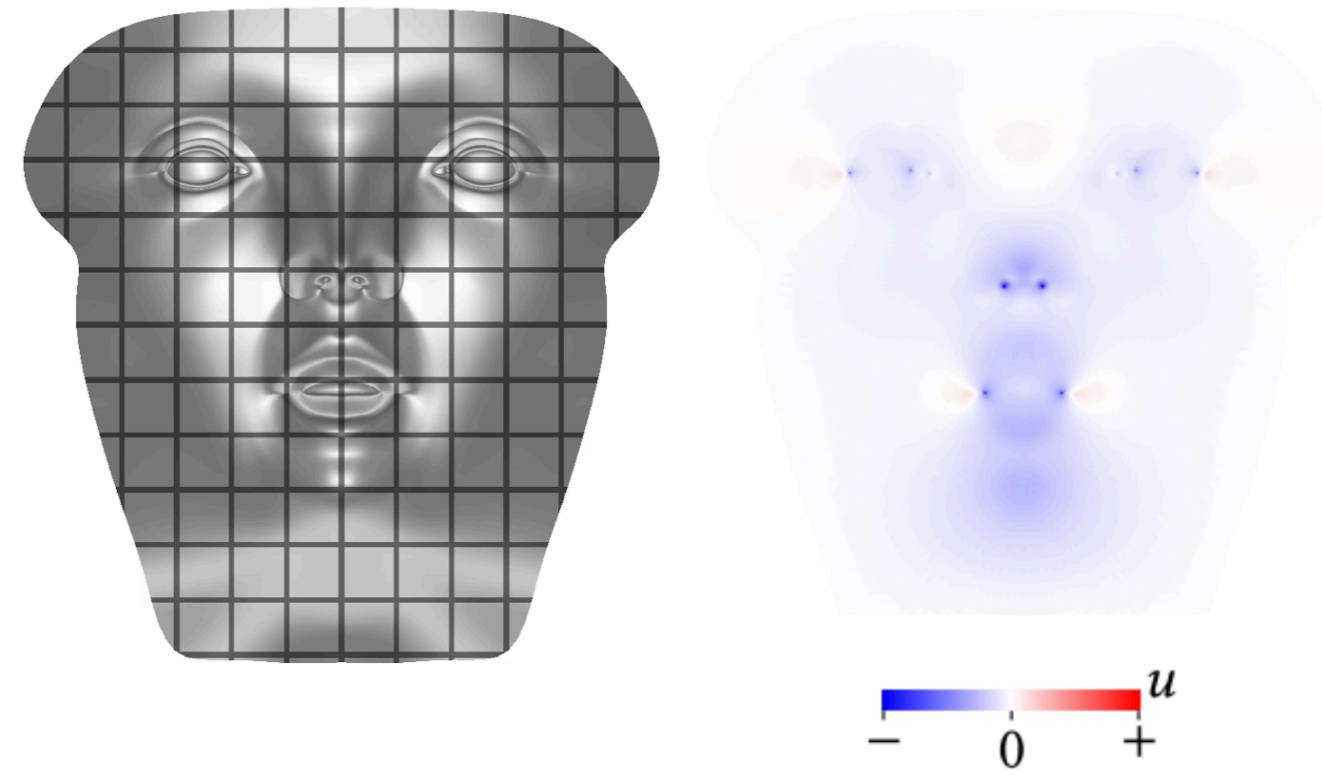
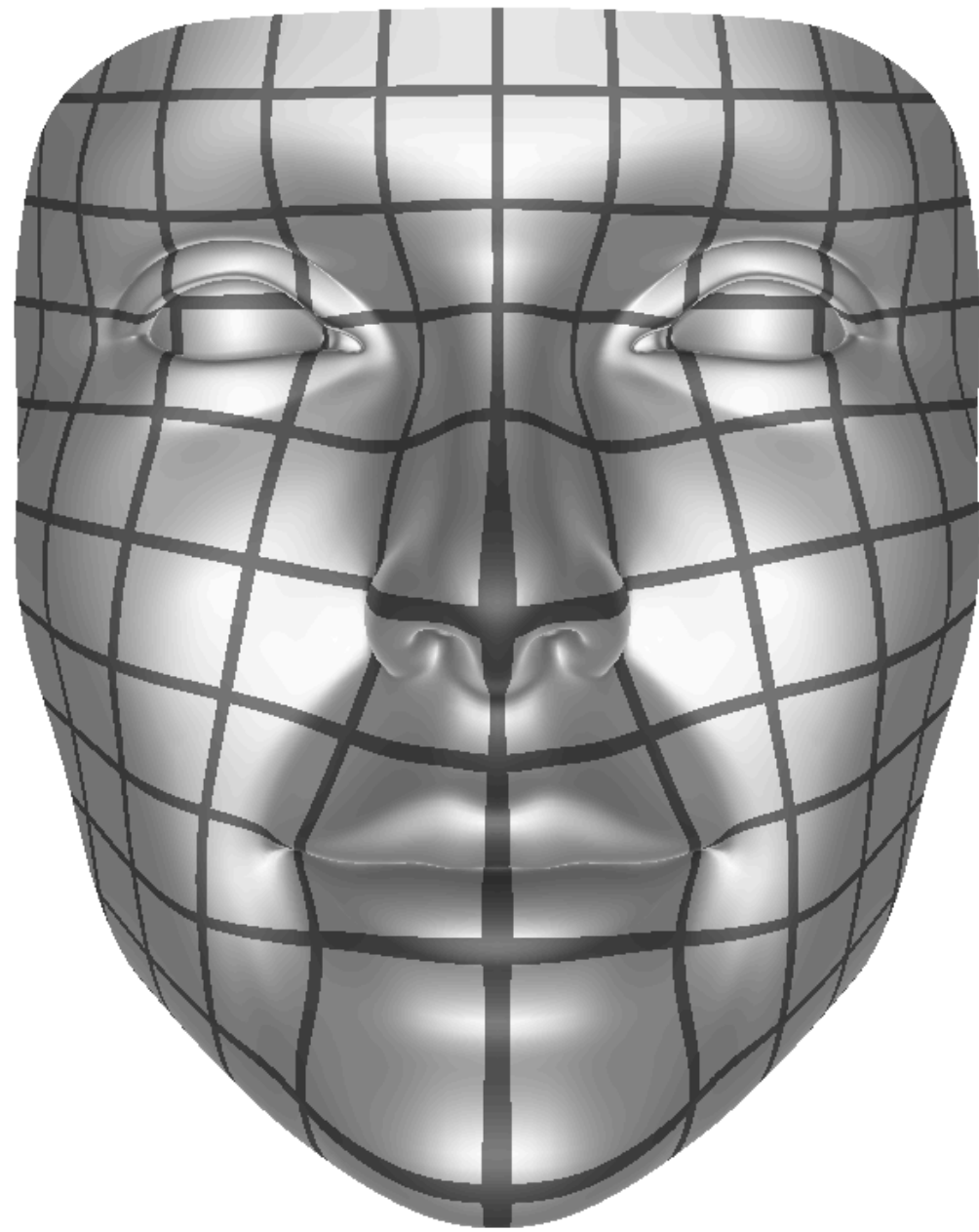
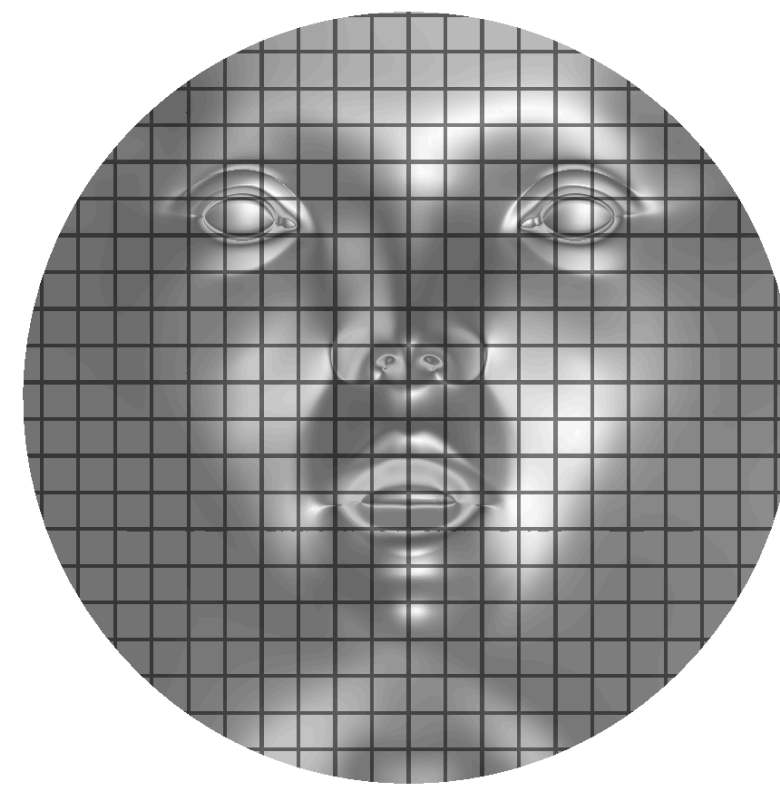


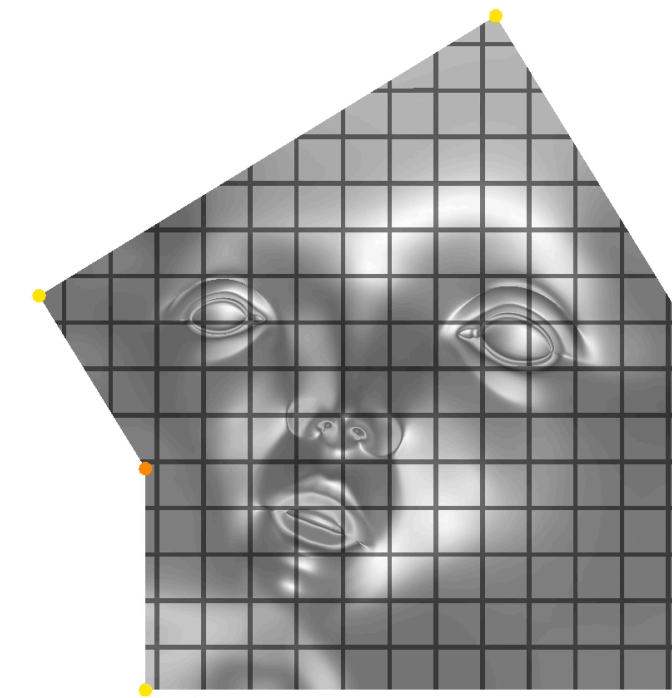
Boundary First Flattening (BFF)



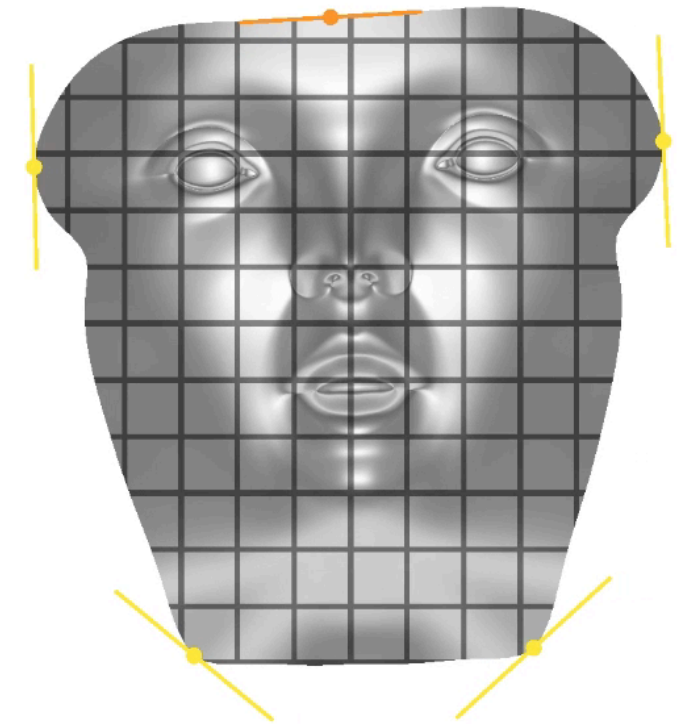
Minimal Area Distortion
(Fully Automatic)



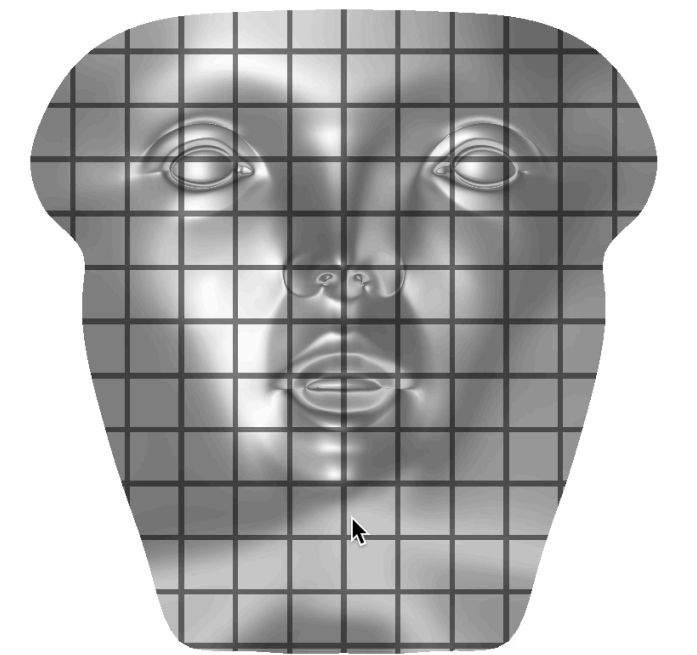
Arbitrary Target Shapes



Sharp Corners

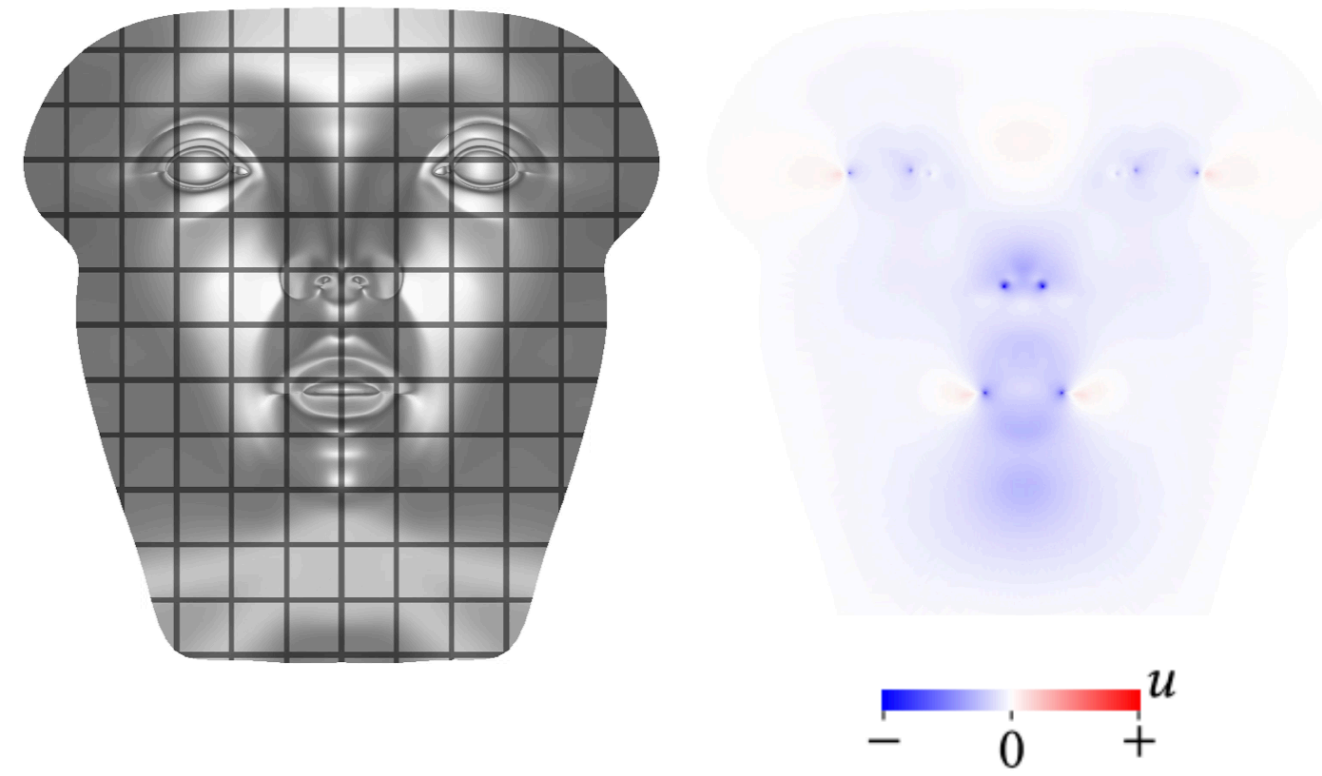
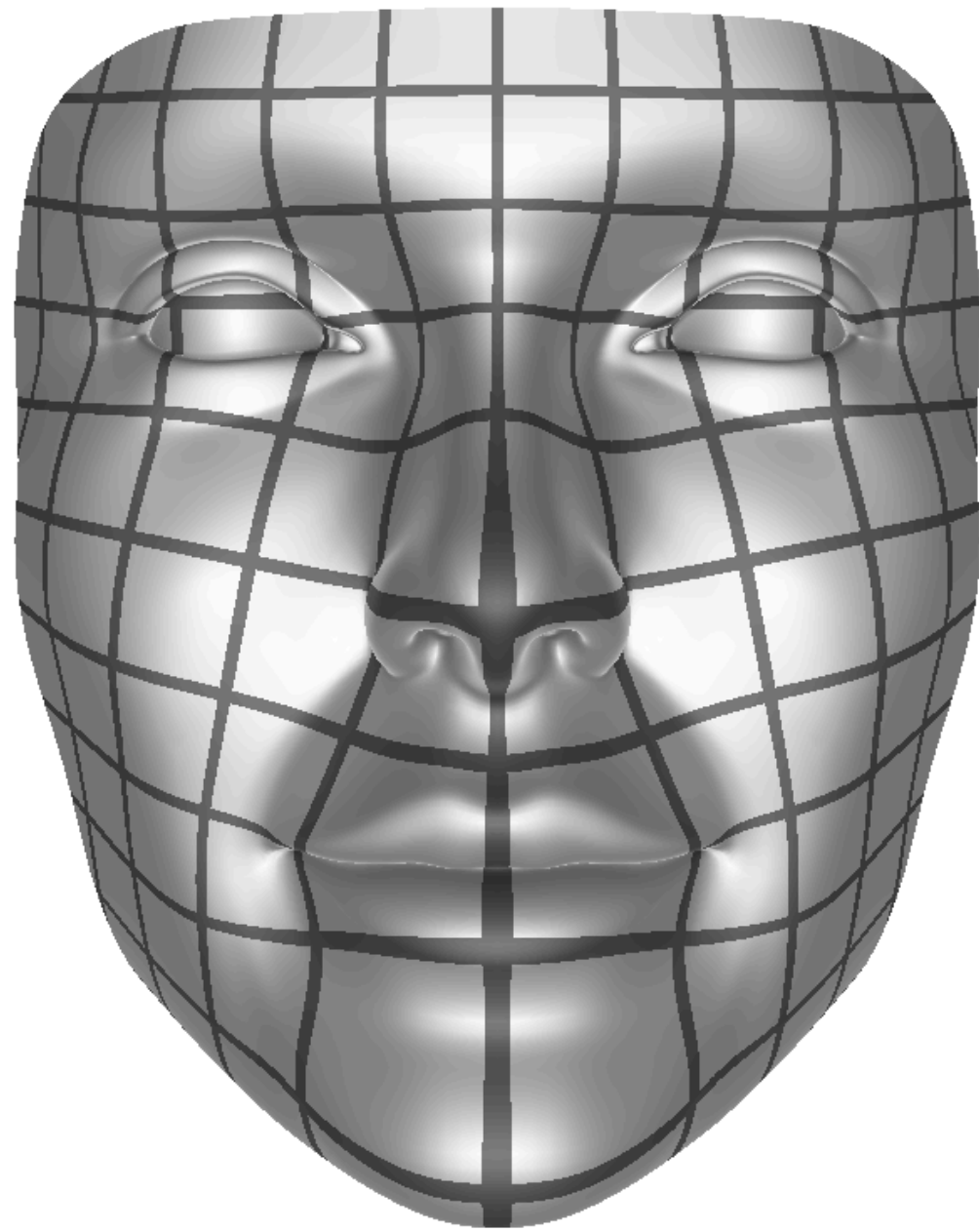


Direct Editing

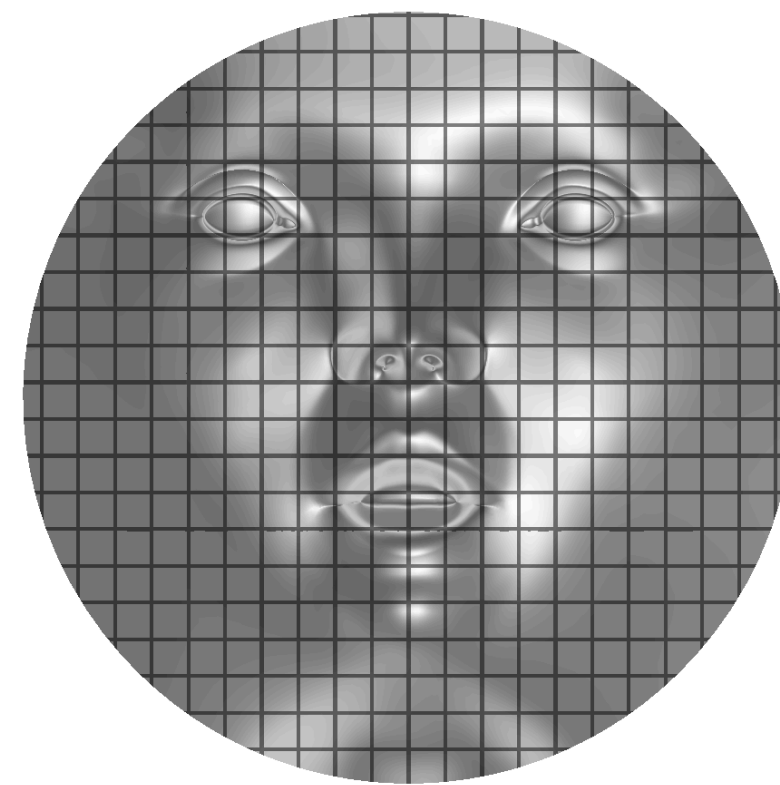


Cone Singularities

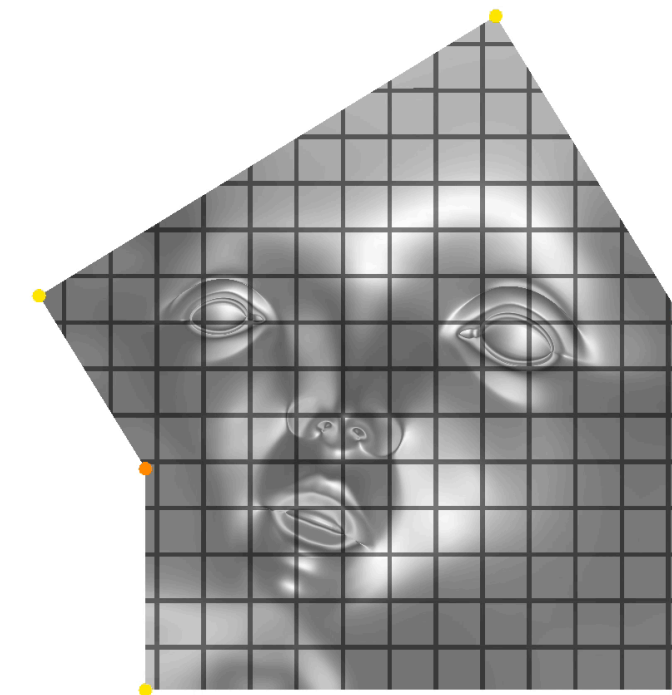
BFF: A New Paradigm for Conformal Parameterization



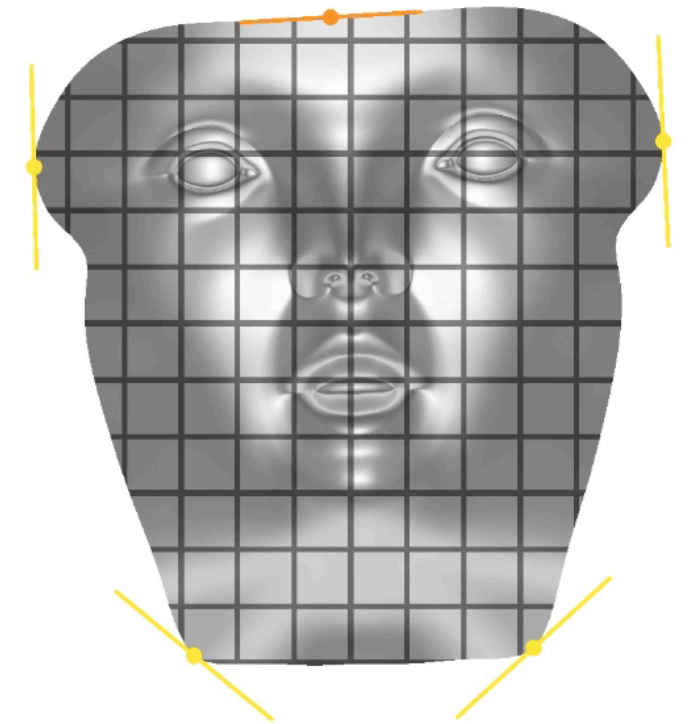
Minimal Area Distortion
(Fully Automatic)



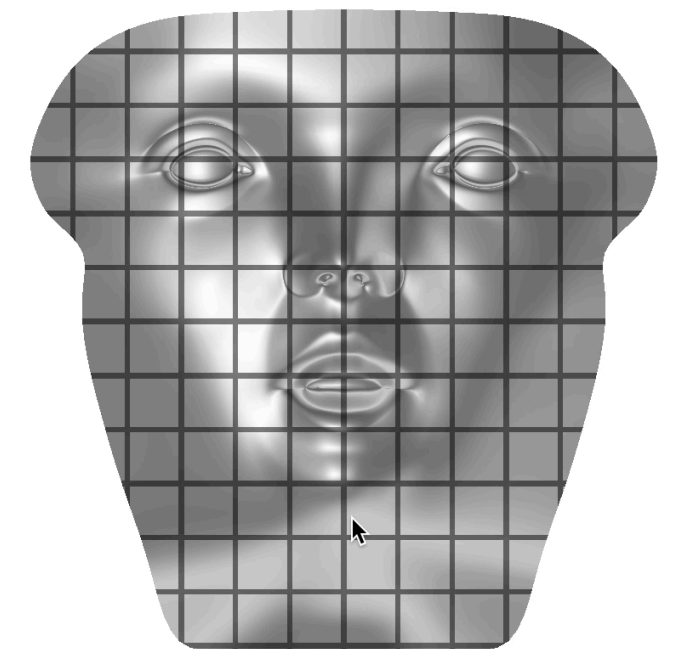
Arbitrary Target Shapes



Sharp Corners

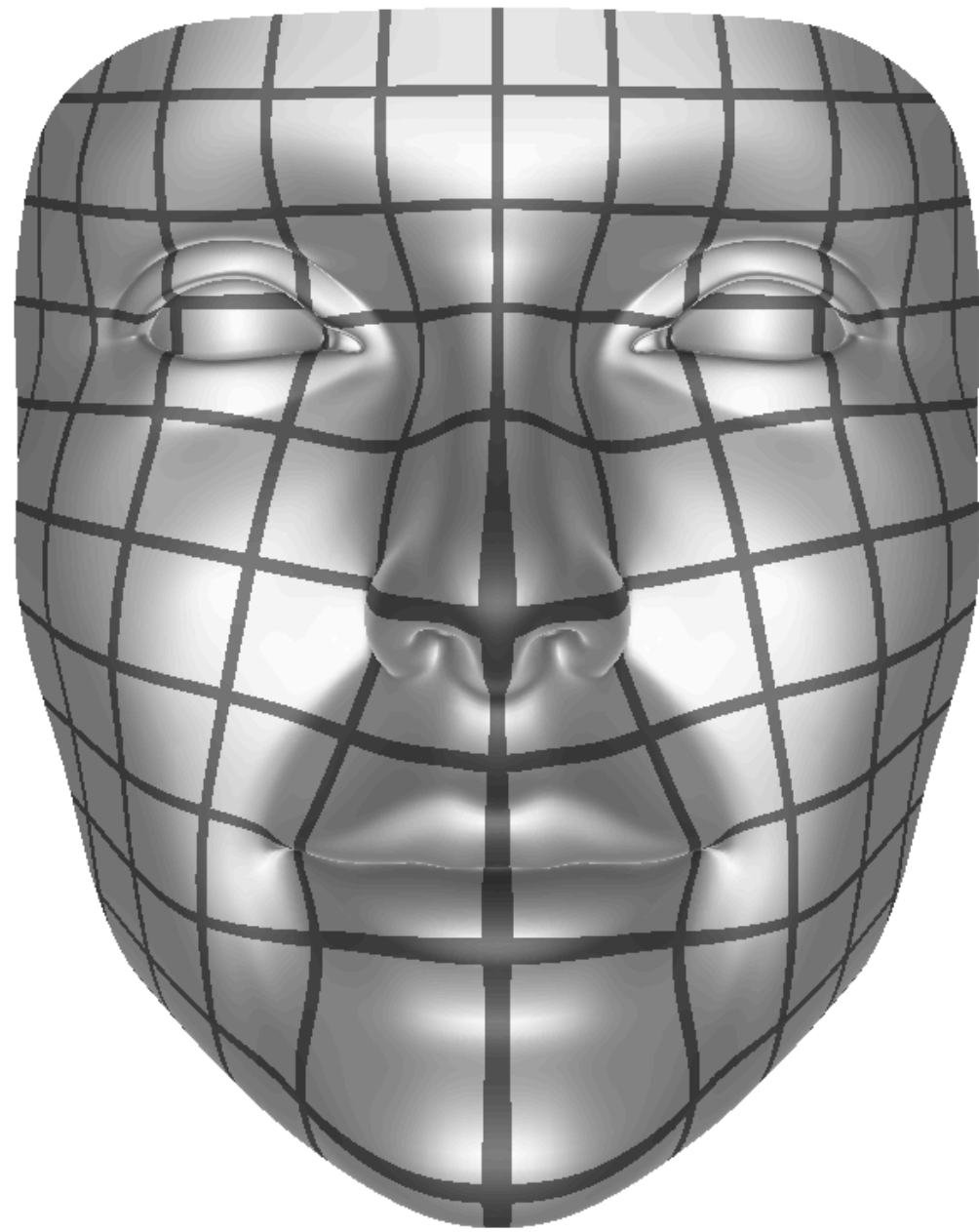


Direct Editing



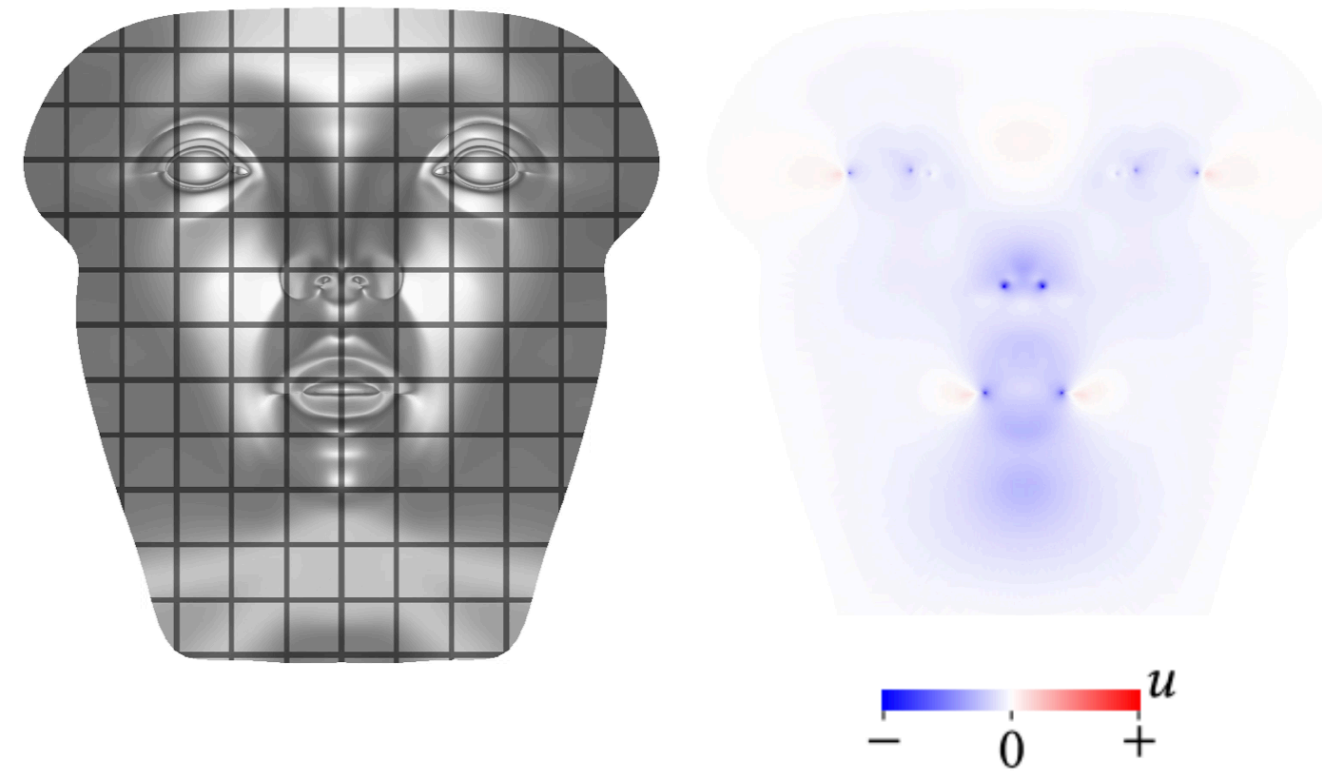
Cone Singularities

BFF: A New Paradigm for Conformal Parameterization

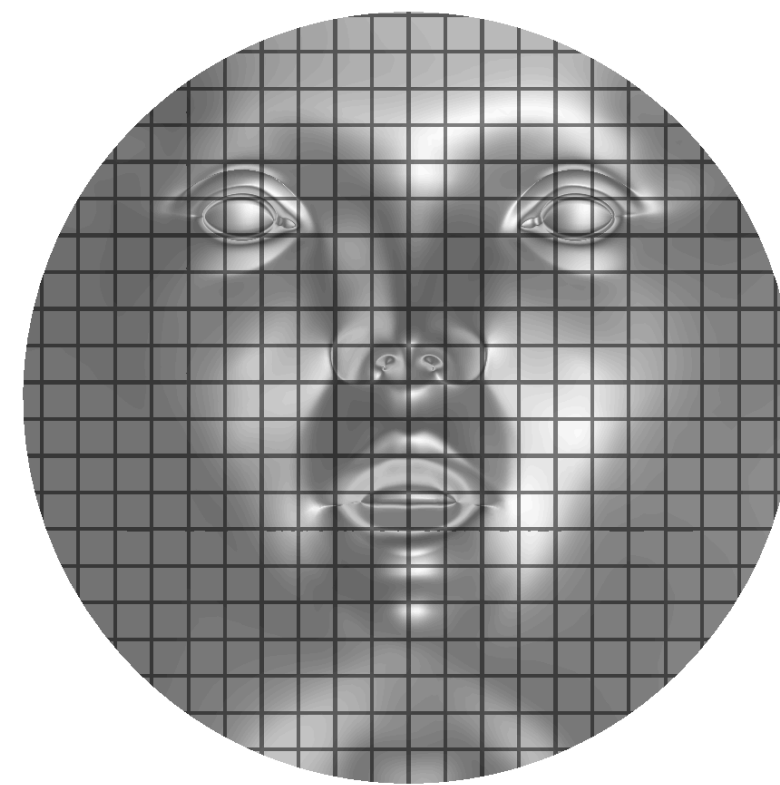


Quality of nonlinear methods

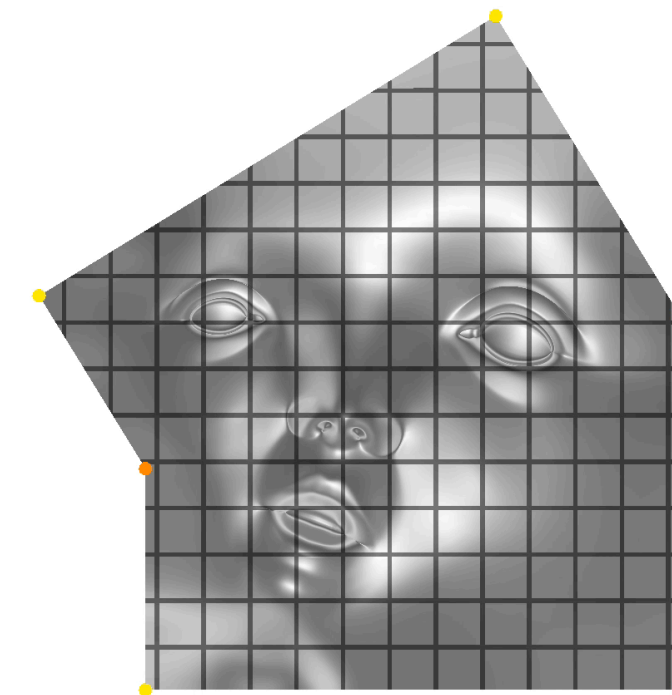
Faster than existing linear schemes



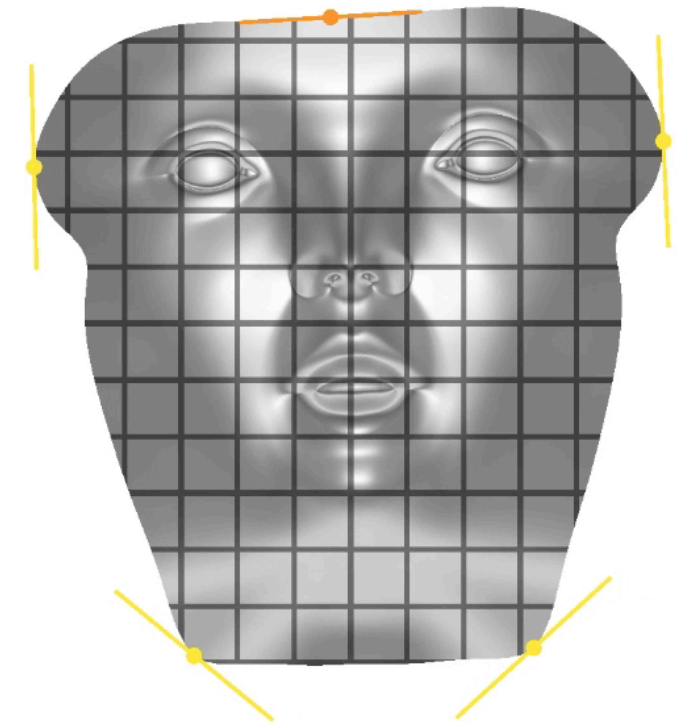
Minimal Area Distortion
(Fully Automatic)



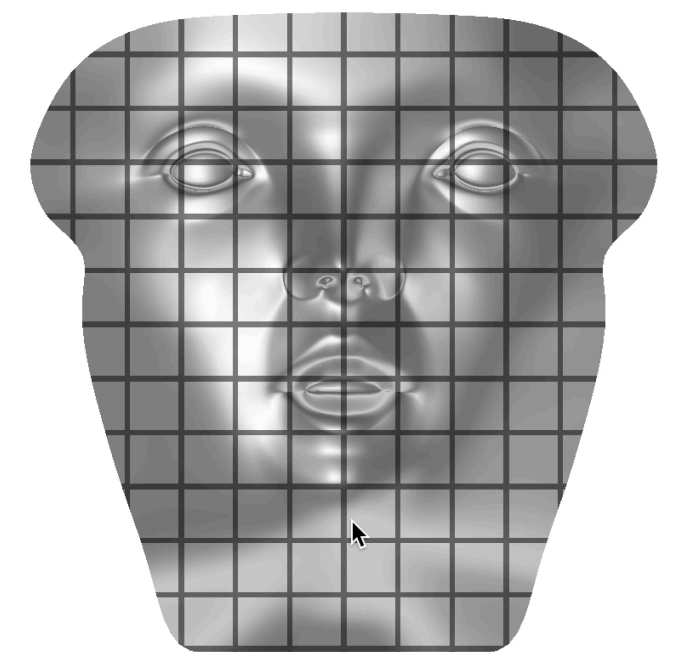
Arbitrary Target Shapes



Sharp Corners

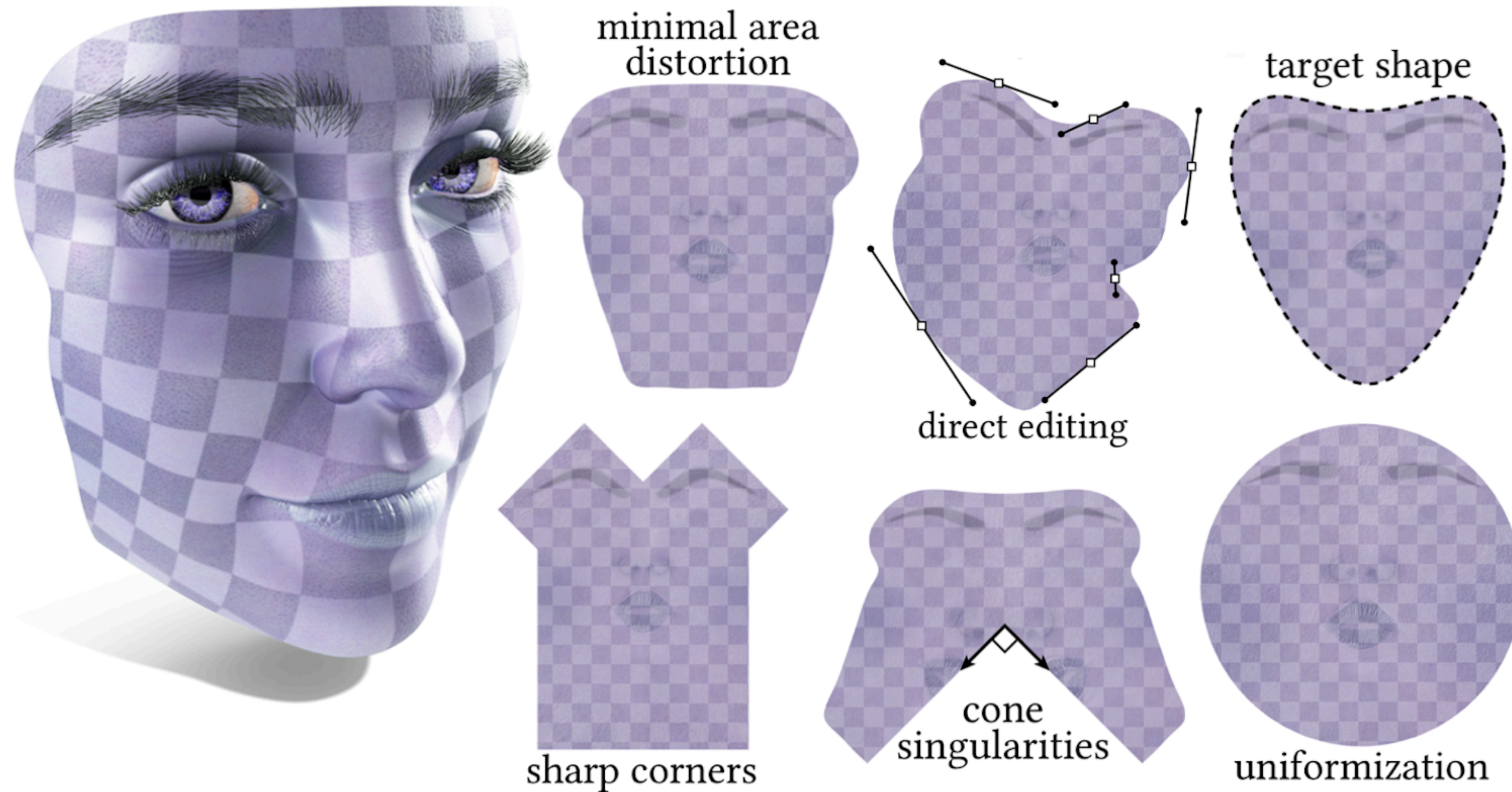


Direct Editing



Cone Singularities

Boundary First Flattening (BFF)



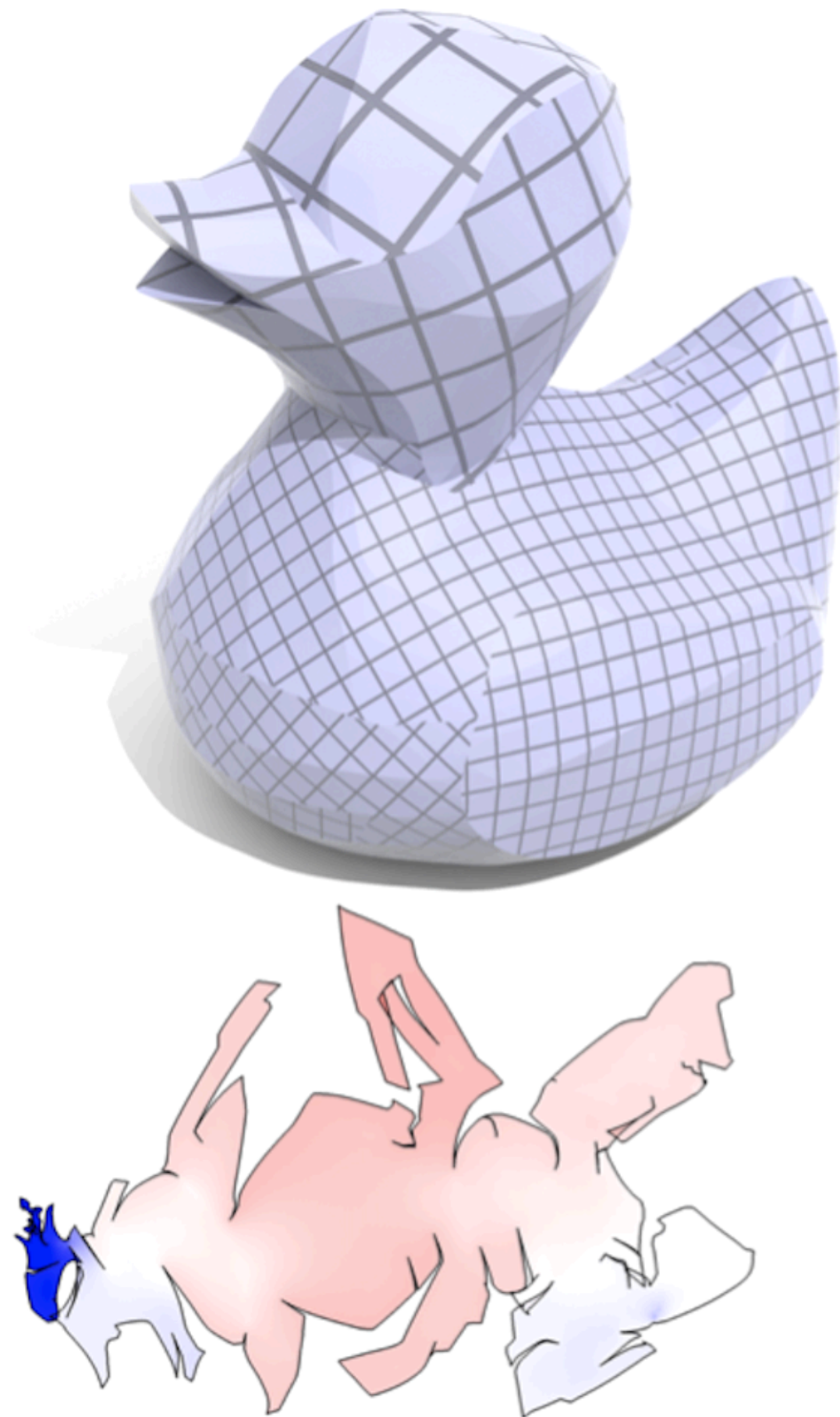
Full Control Over
Target Shape

Real Time/
Scalable

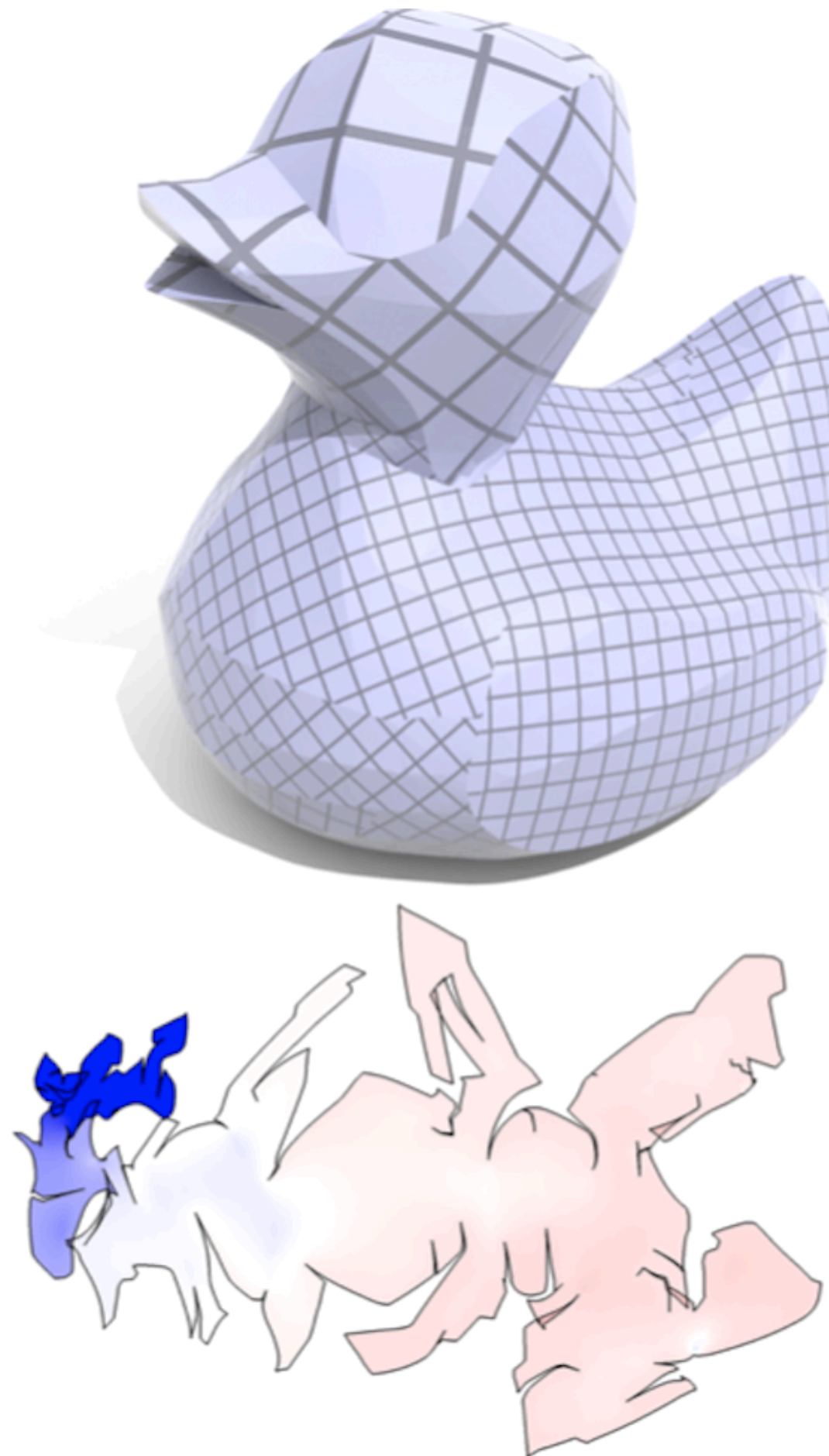
Robust

BFF is Robust

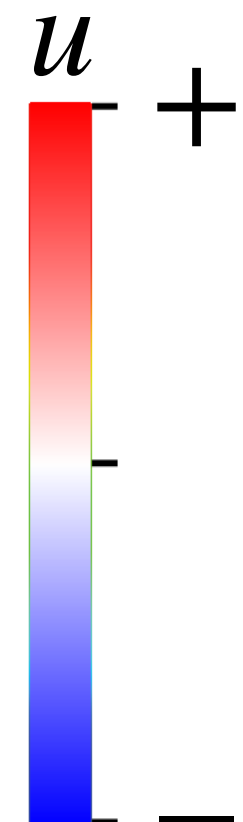
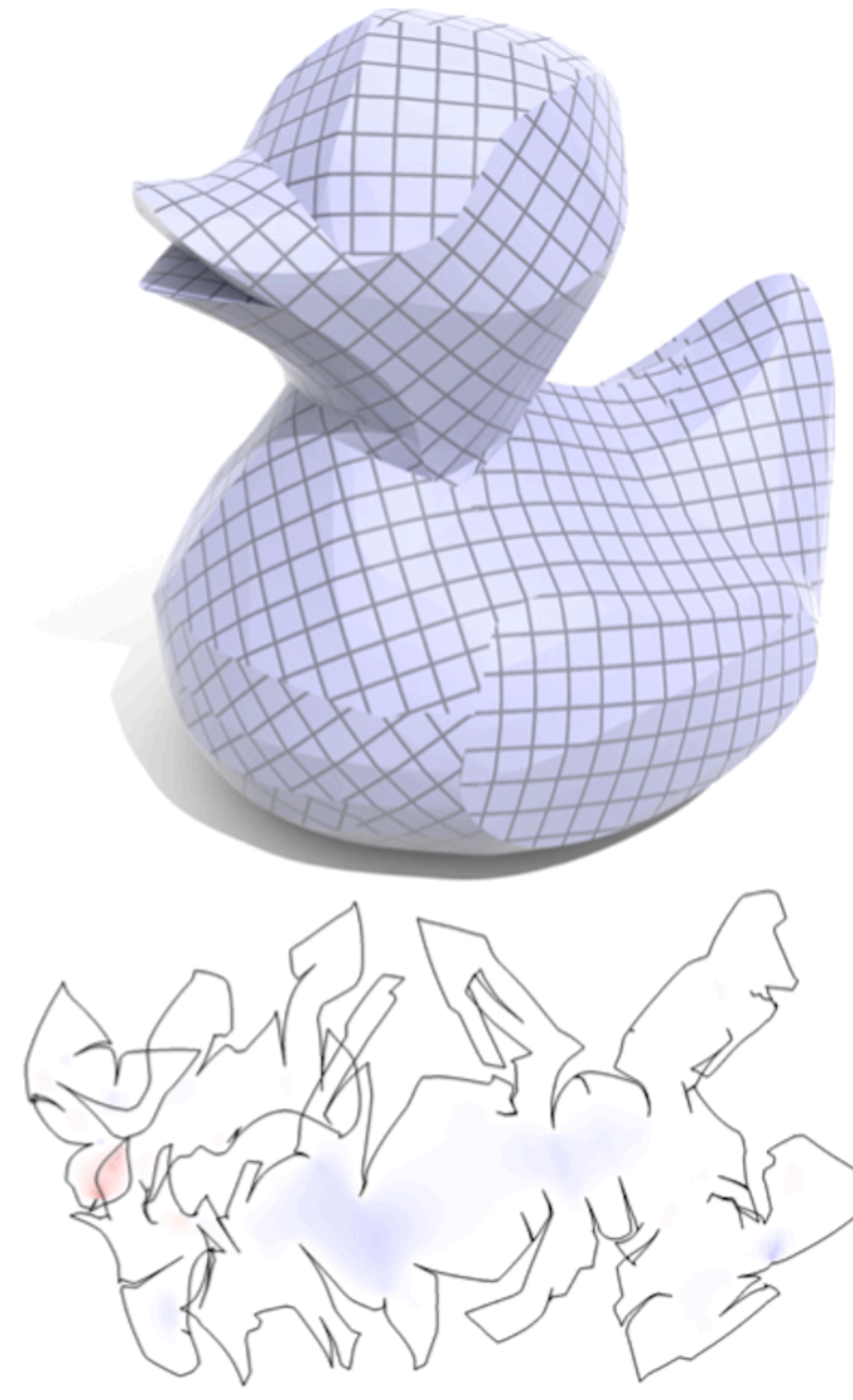
Spectral Conformal (SCP)
[Mullen et al 2008]



Angle Based (ABF)
[Zayer et al 2008]

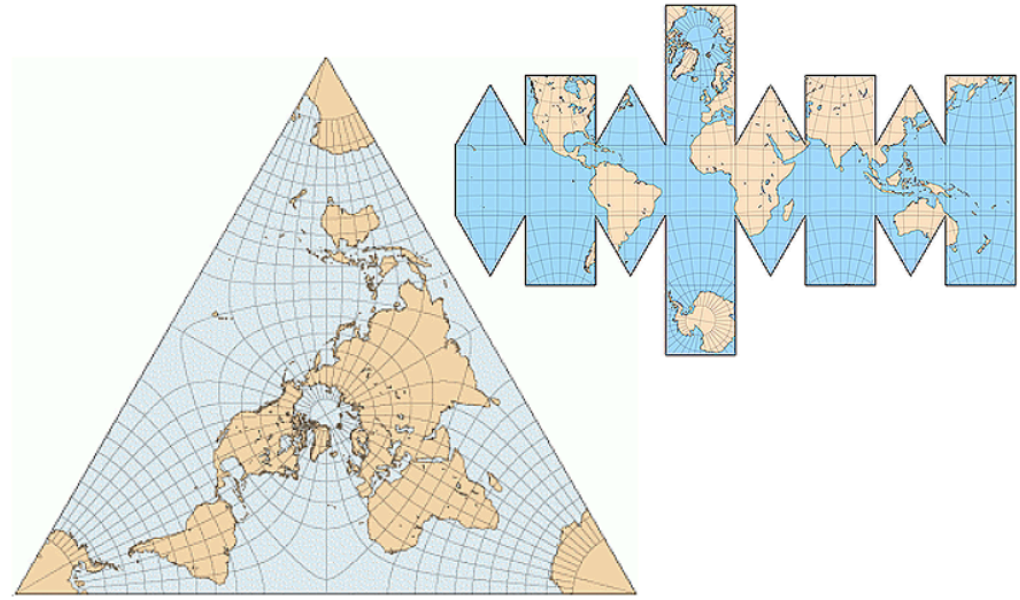


Boundary First (BFF)
[Sawhney et al 2017]

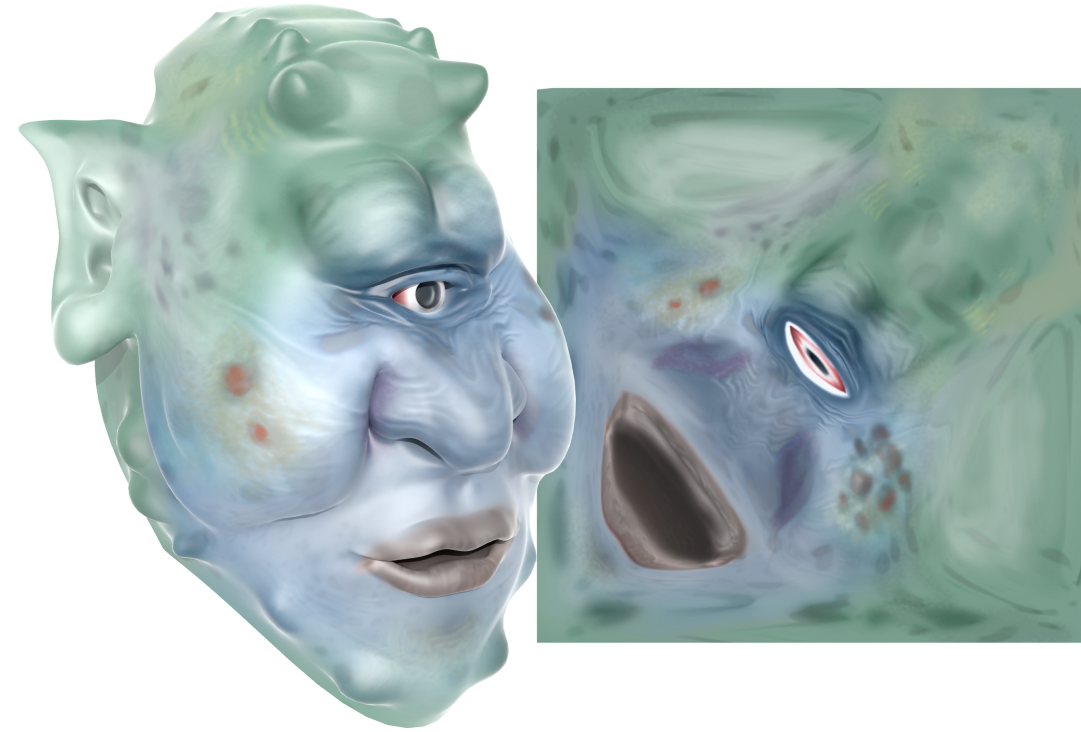


MOTIVATION

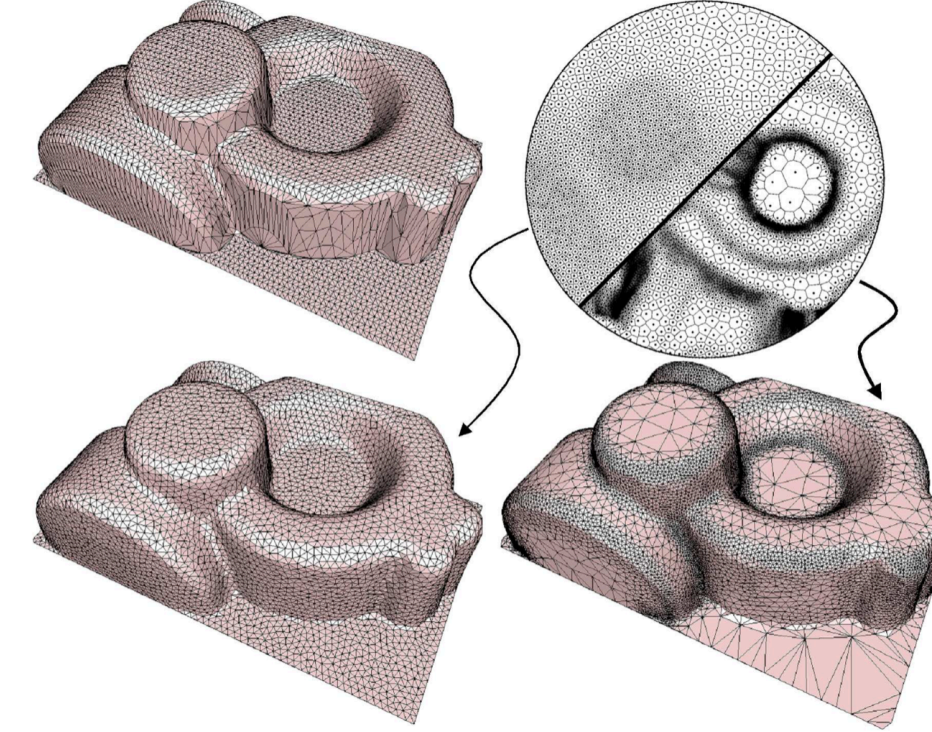
Conformal Flattening Applications



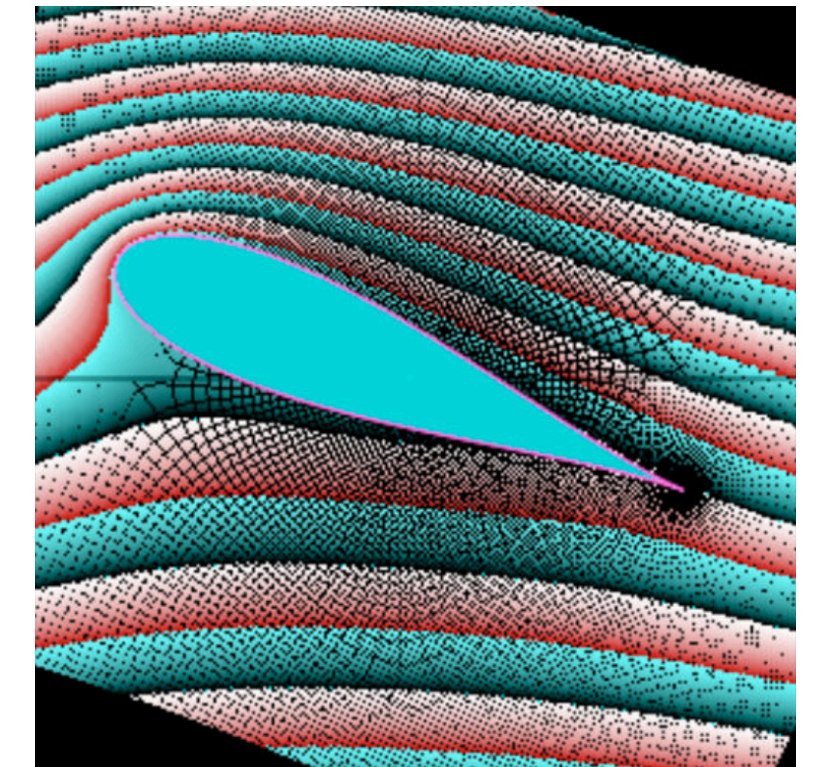
Cartography



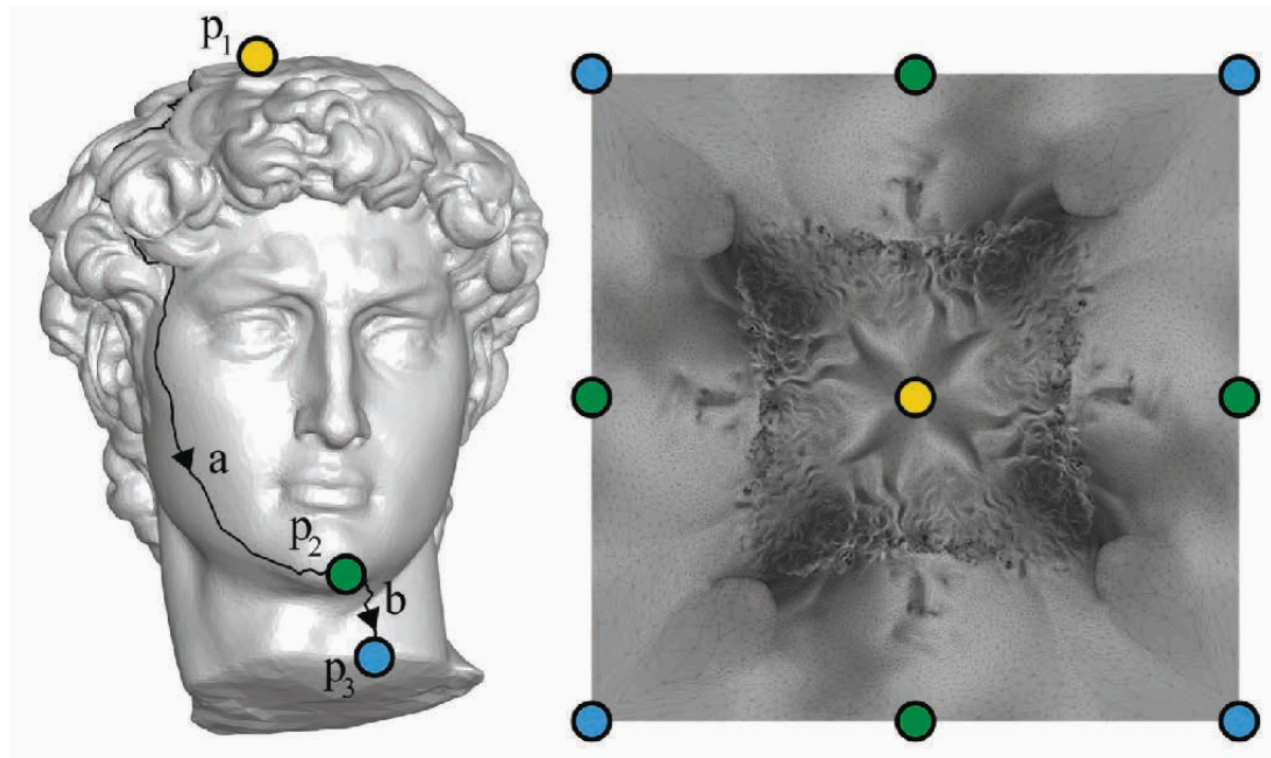
Texture Mapping



Remeshing



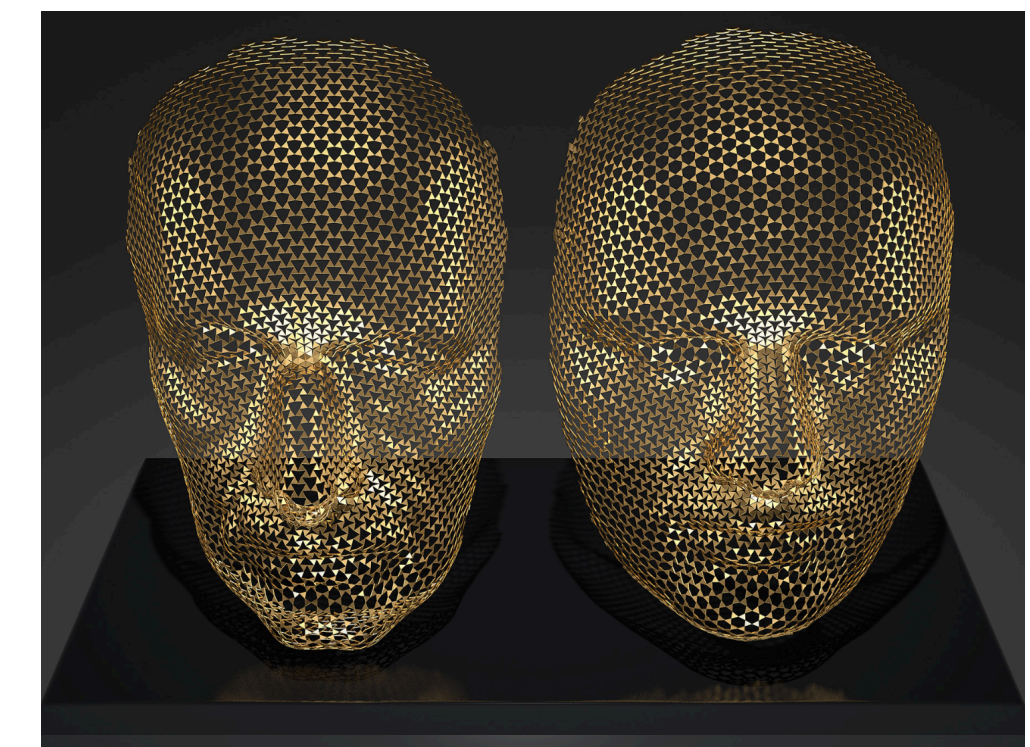
Physical Simulation



Machine Learning



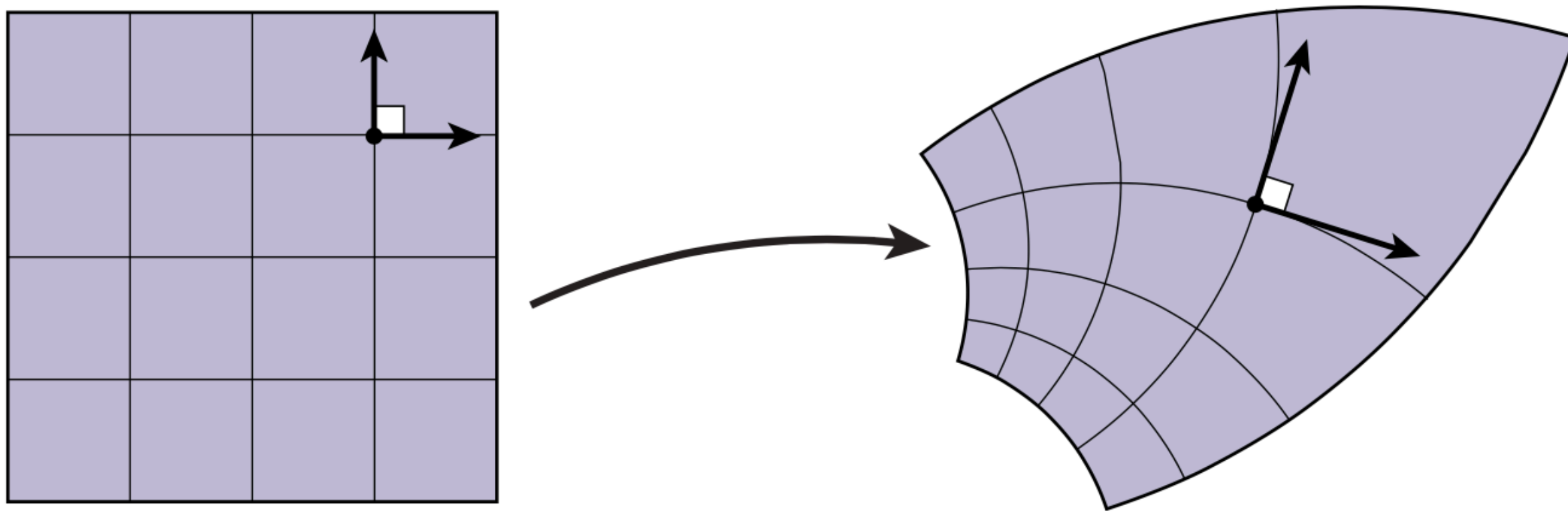
Computational Design



3D Fabrication

Why Conformal?

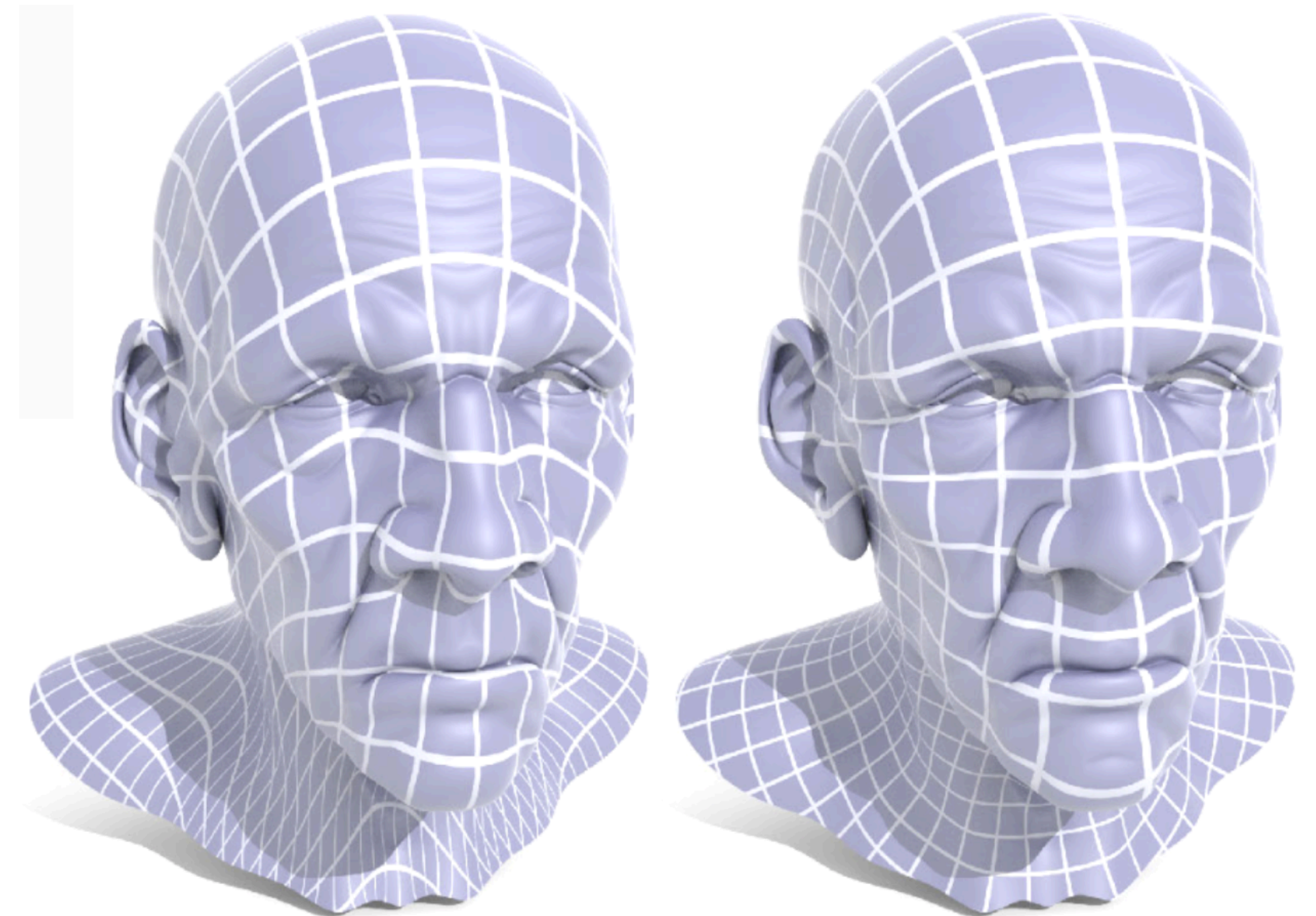
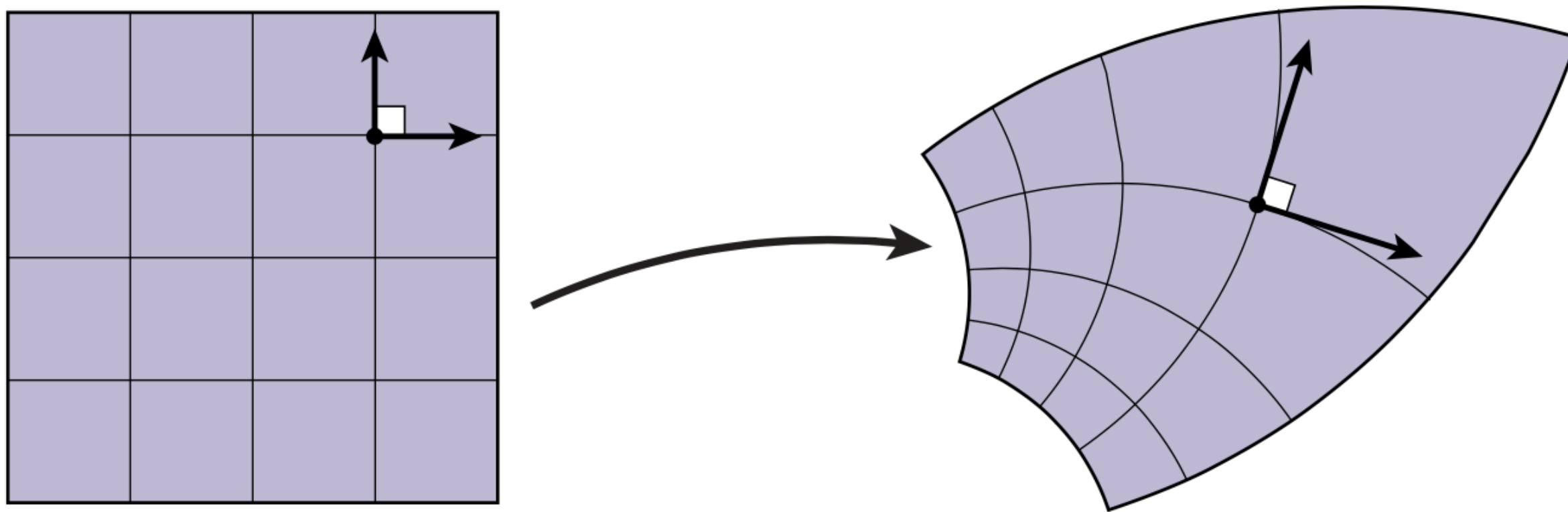
Why so much interest in maps that preserve angles?



Why Conformal?

Why so much interest in maps that preserve angles?

QUALITY: Often comparable to nonlinear schemes



SLIM + PARDISO
[Rabinovich et al 2016]

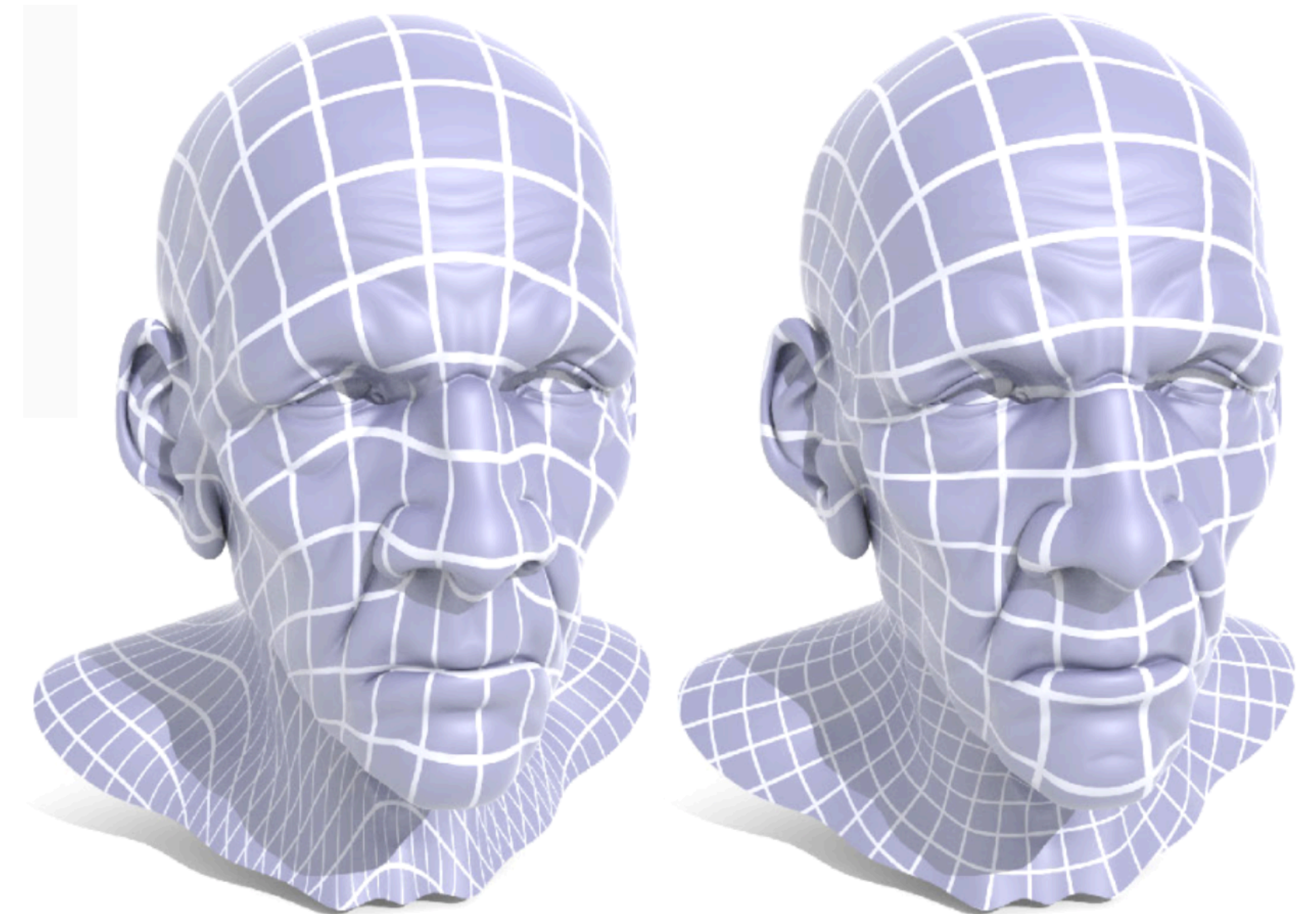
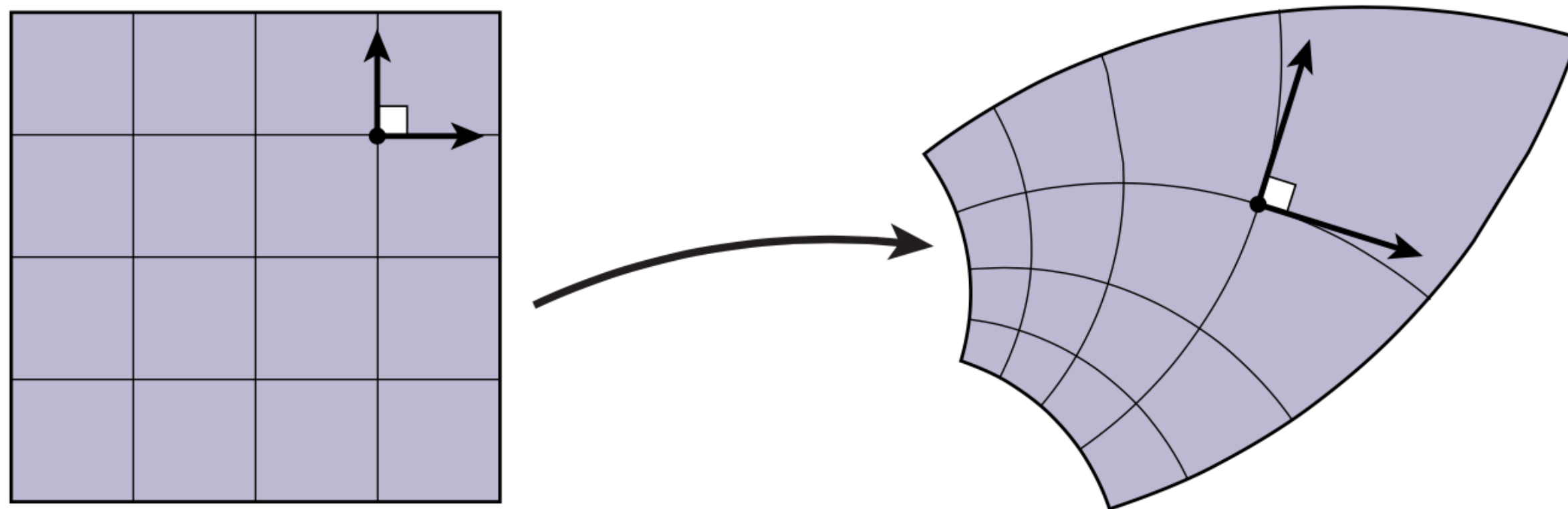
BFF
[Sawhney & Crane 2017]

Why Conformal?

Why so much interest in maps that preserve angles?

QUALITY: Often comparable to nonlinear schemes

EFFICIENCY: Often only one sparse factorization!



SLIM + PARDISO
[Rabinovich et al 2016]
15.9s

BFF
[Sawhney & Crane 2017]
0.12s **(126x faster)**

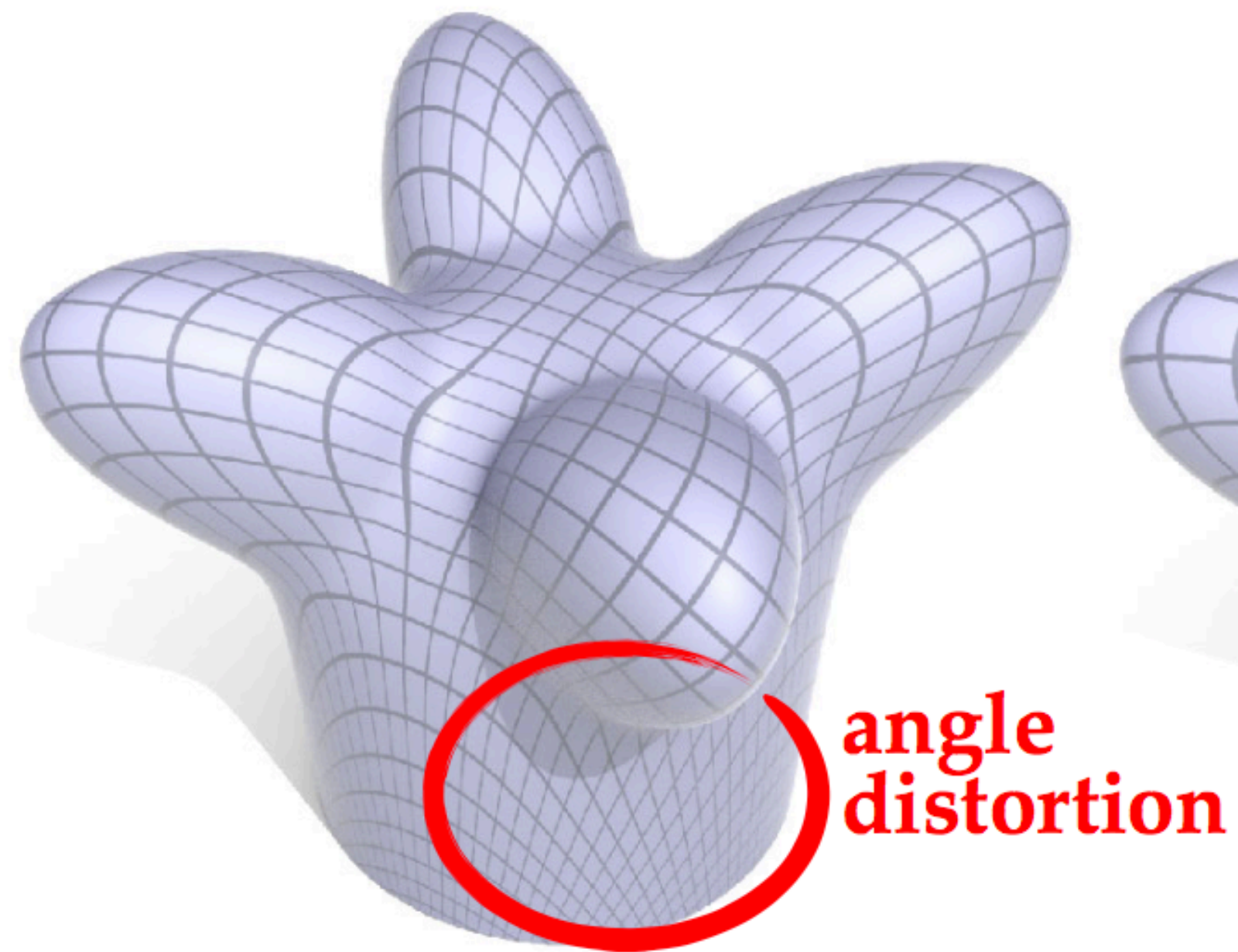
Why Conformal?

What about other energies like ARAP, Symmetric Dirichlet, ...?

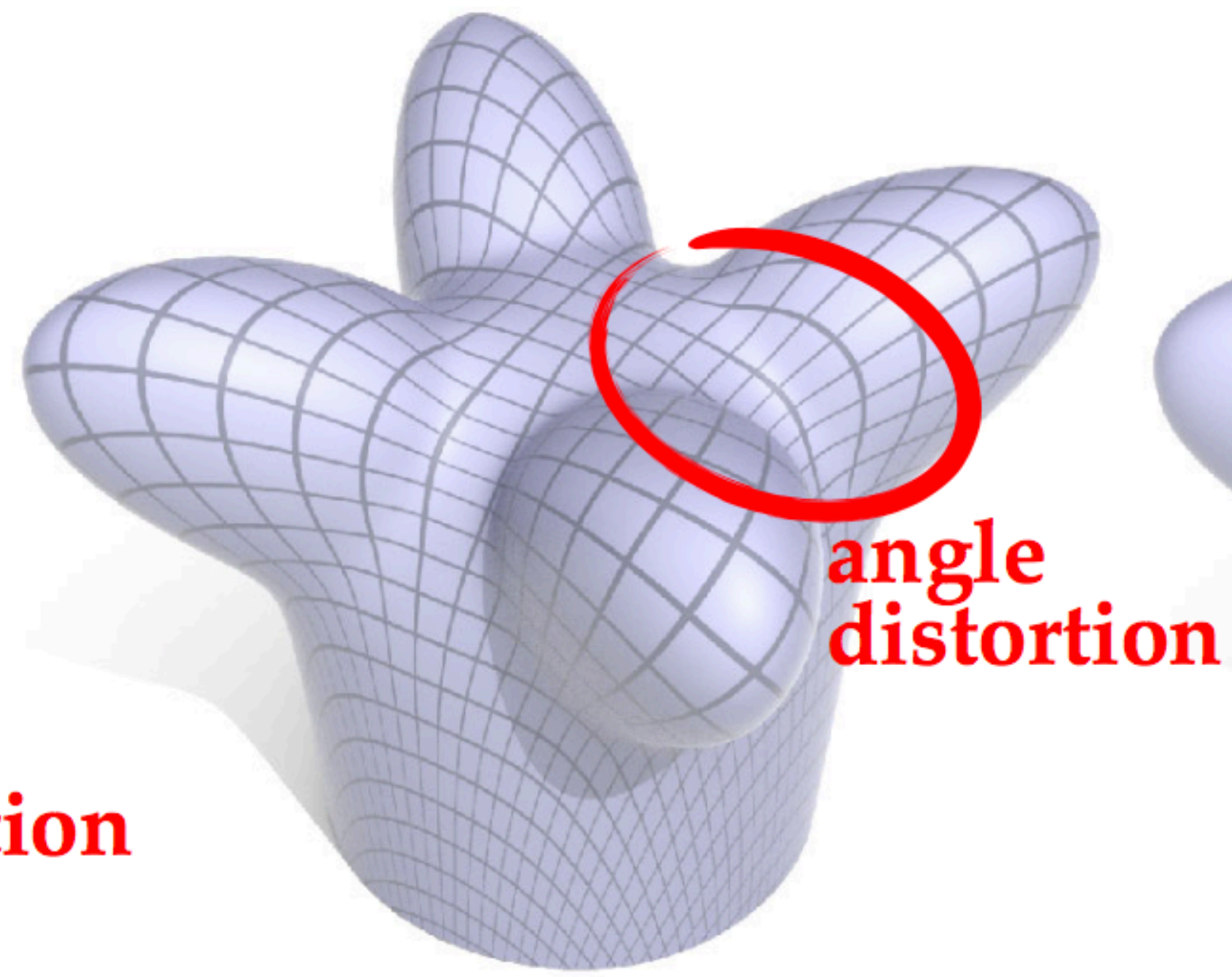
Why Conformal?

What about other energies like ARAP, Symmetric Dirichlet, ...?

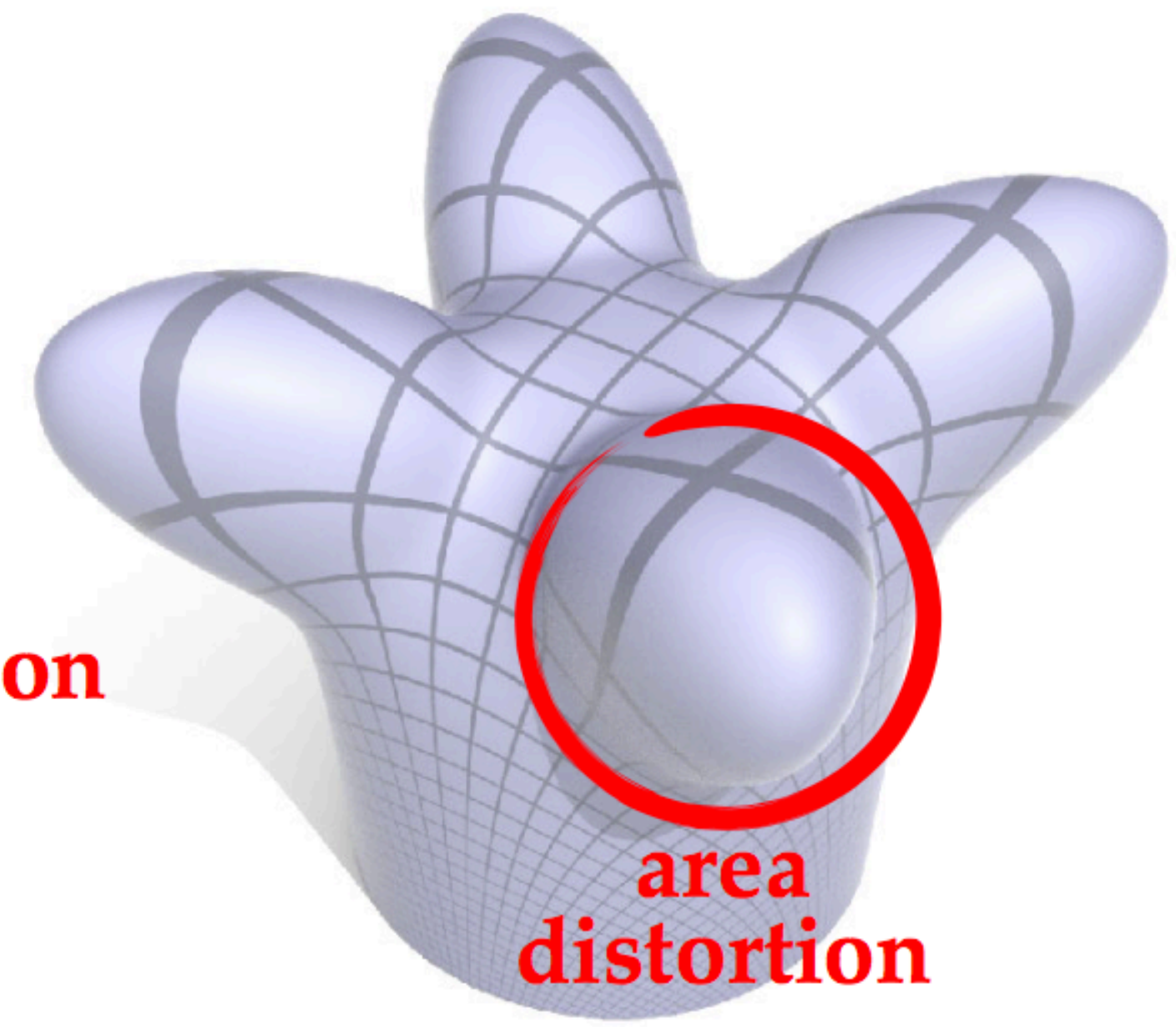
Distortion is inevitable



As Rigid As Possible



Symmetric Dirichlet



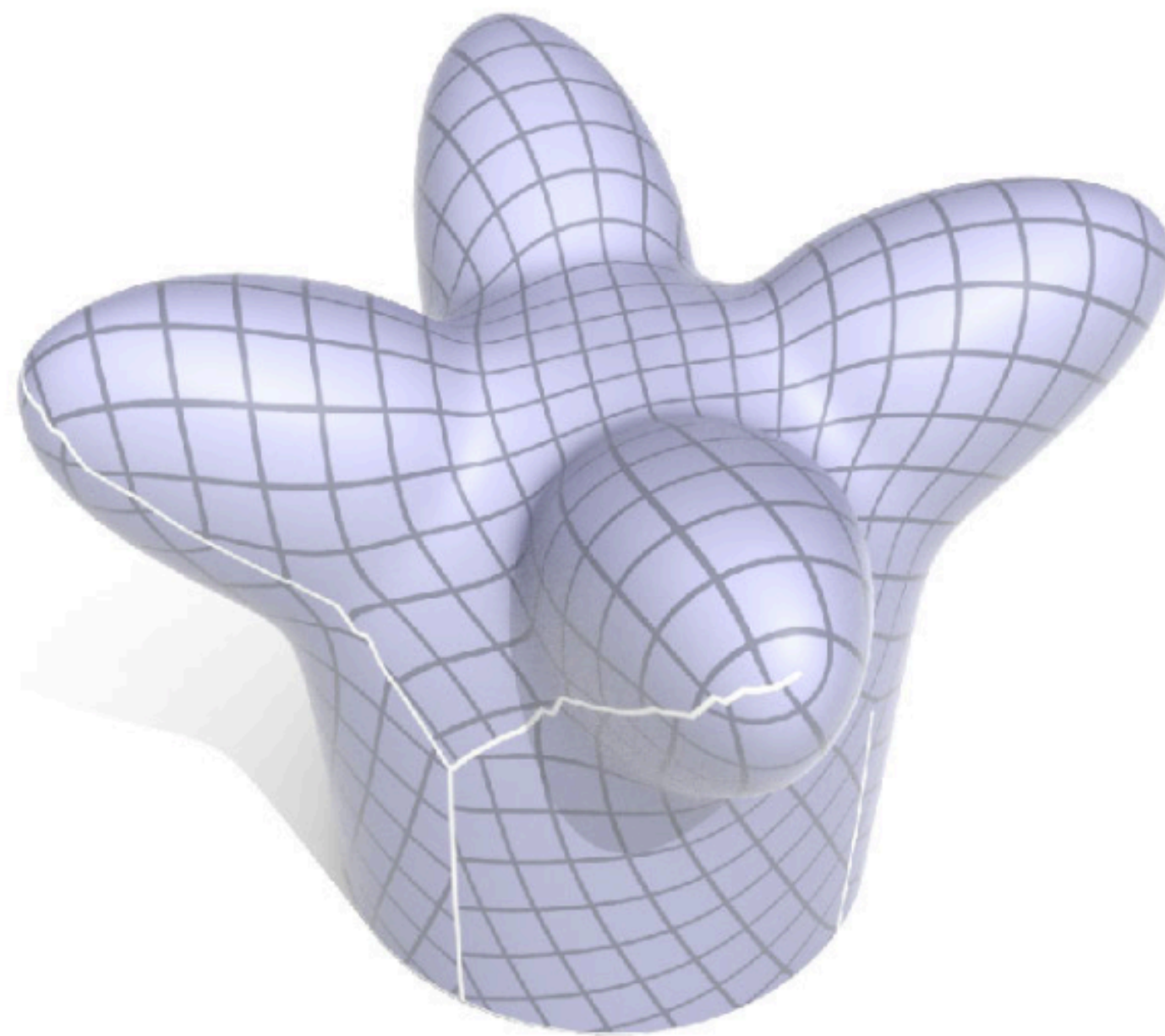
Conformal

Why Conformal?

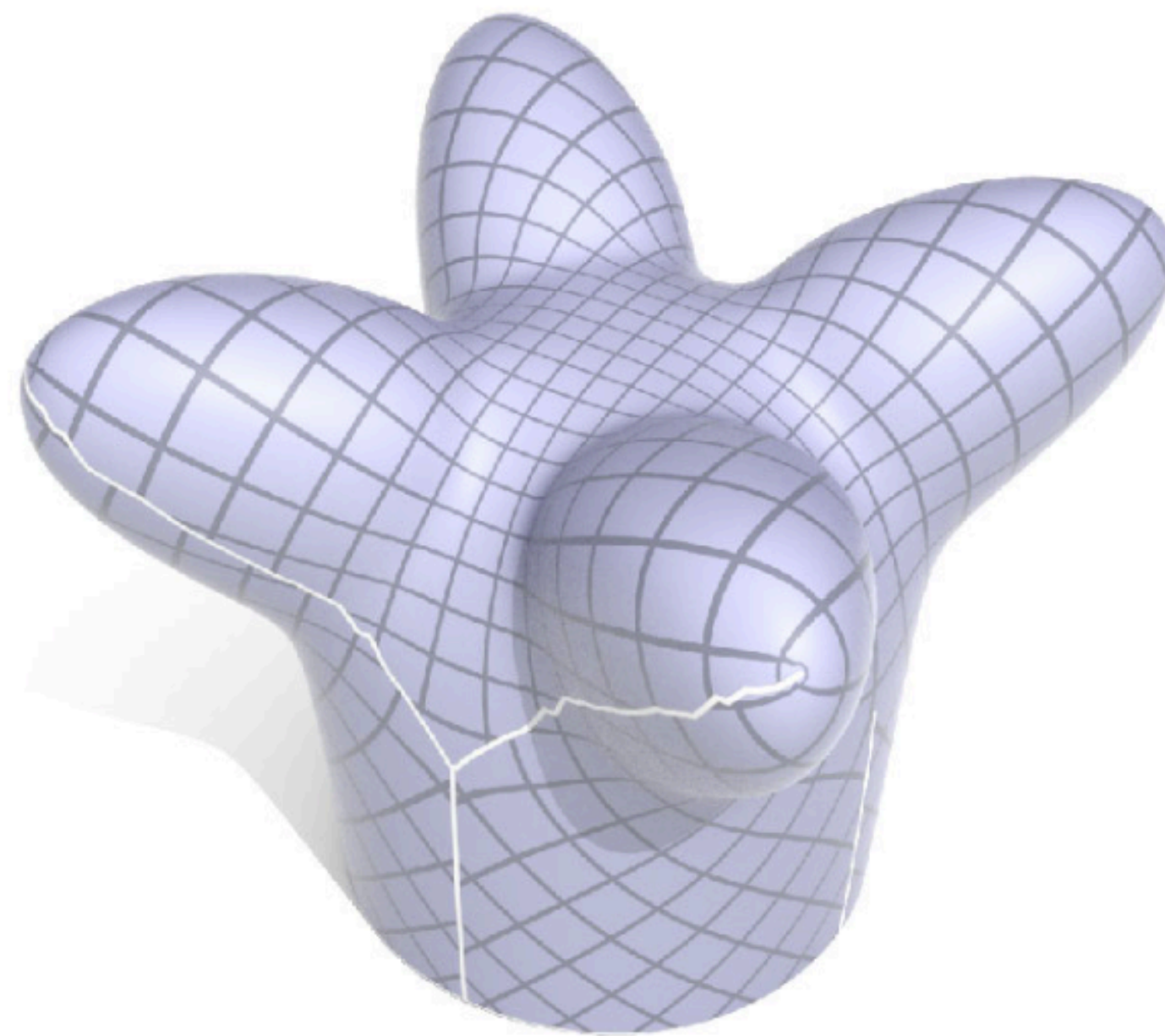
What about other energies like ARAP, Symmetric Dirichlet, ...?

Distortion is inevitable

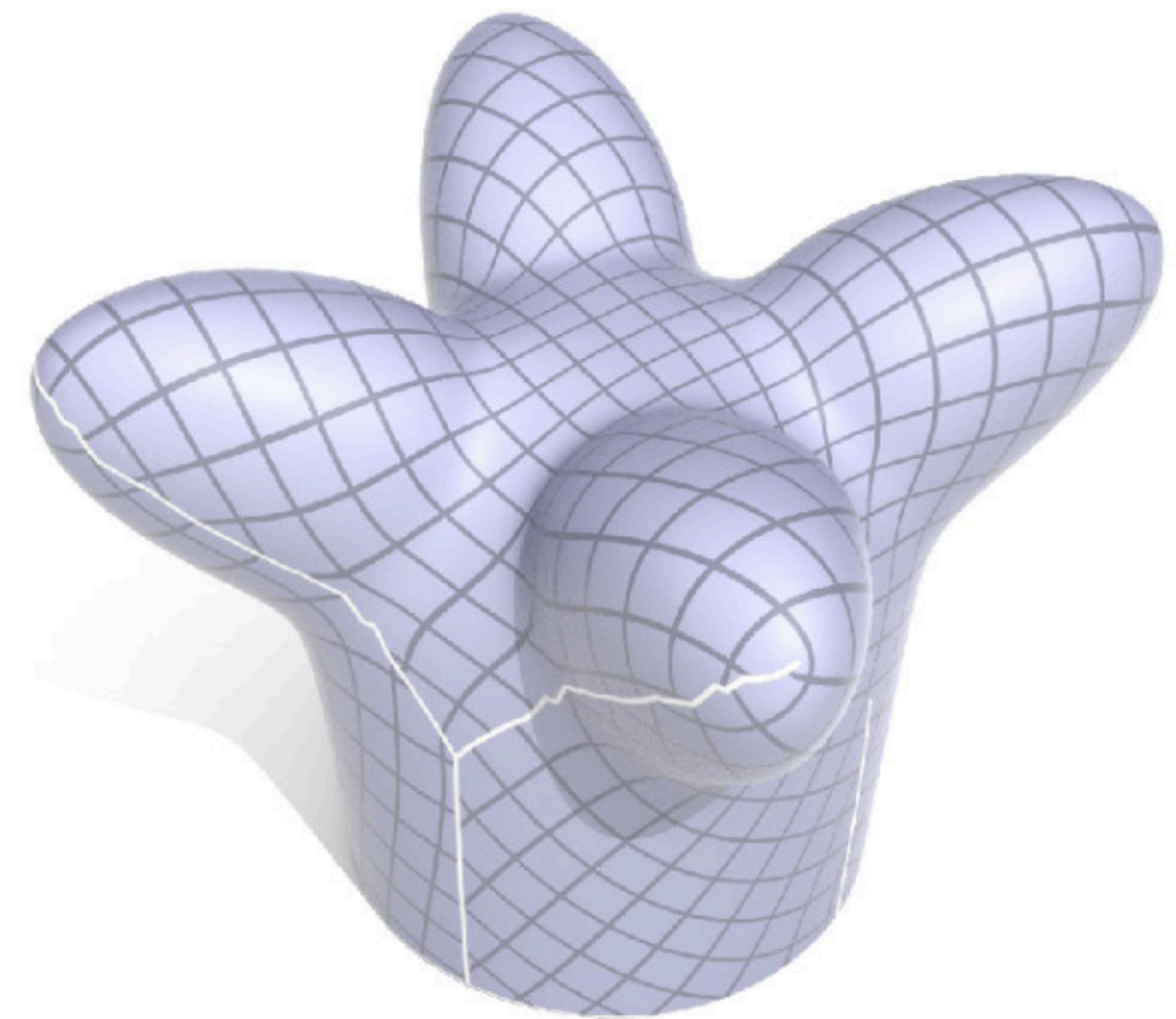
Choice of cuts is far more important, with conformal energies much cheaper to minimize



As Rigid As Possible



Symmetric Dirichlet



Conformal

Problems

Current linear conformal methods have two major shortcomings:

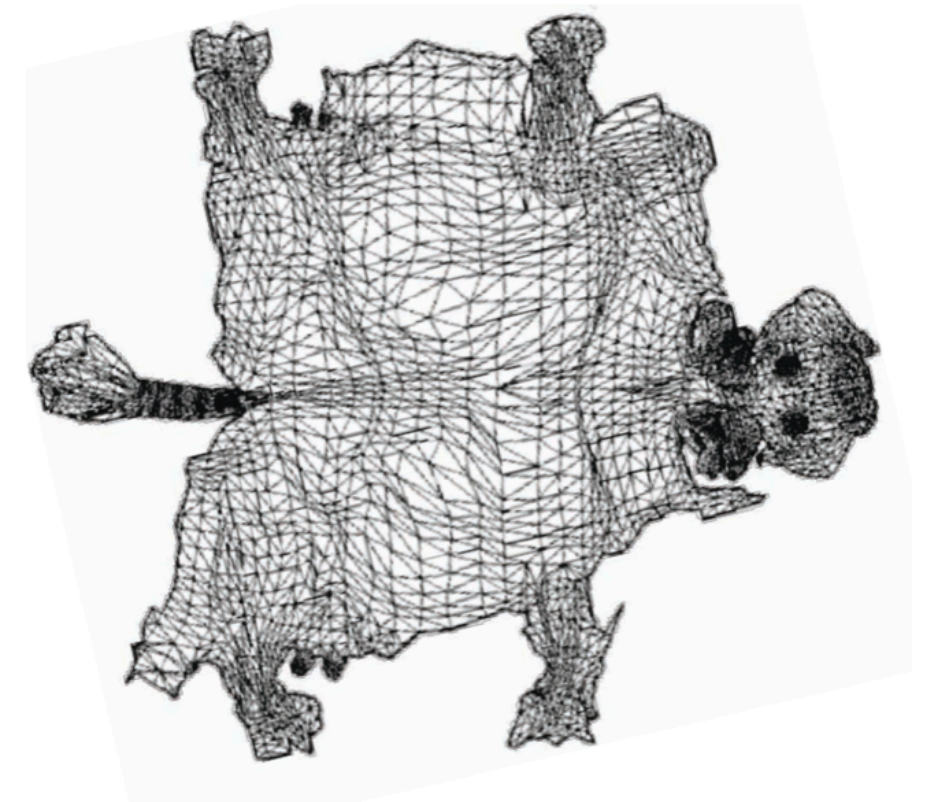
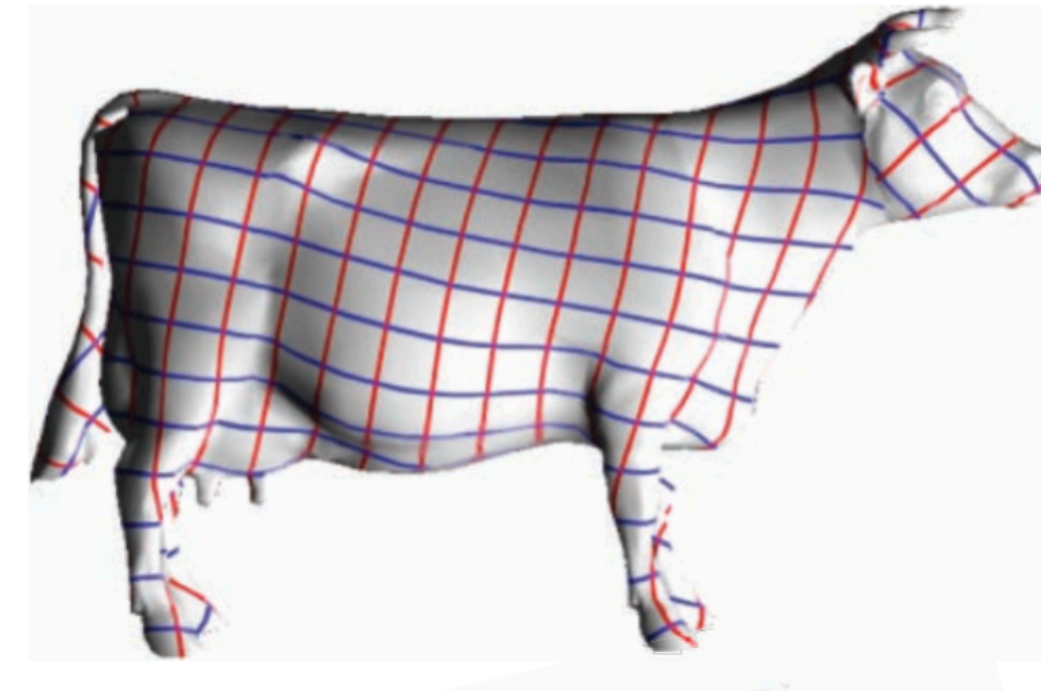
Problems

Current linear conformal methods have two major shortcomings:

NO BOUNDARY CONTROL

User obtains a single, automatic flattening

Must "take it or leave it," irrespective of quality



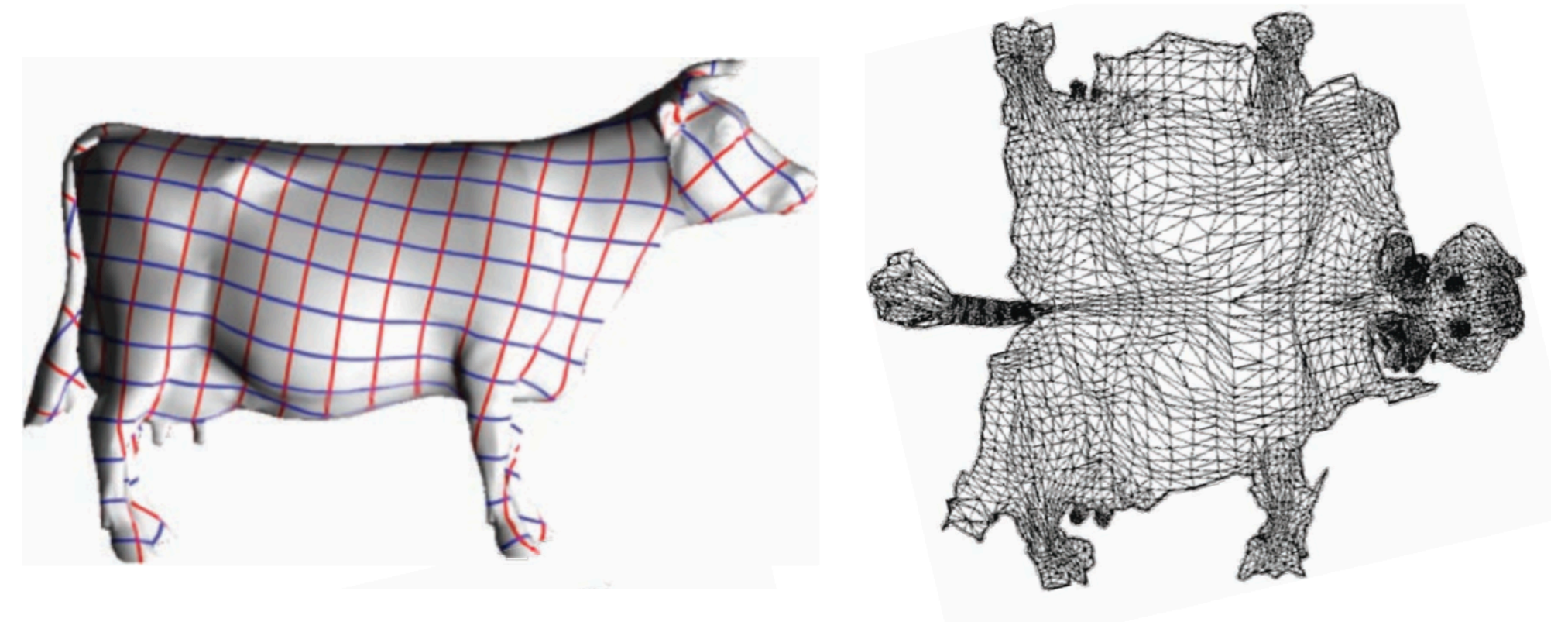
Problems

Current linear conformal methods have two major shortcomings:

NO BOUNDARY CONTROL

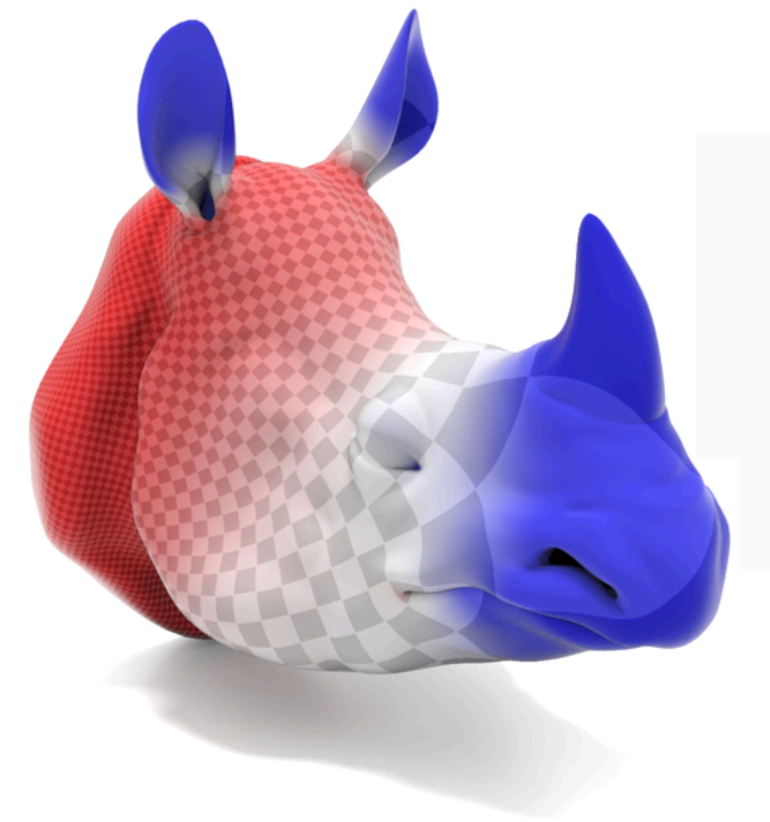
User obtains a single, automatic flattening

Must "take it or leave it," irrespective of quality



SCALE DISTORTION

Conformal maps can scale arbitrarily



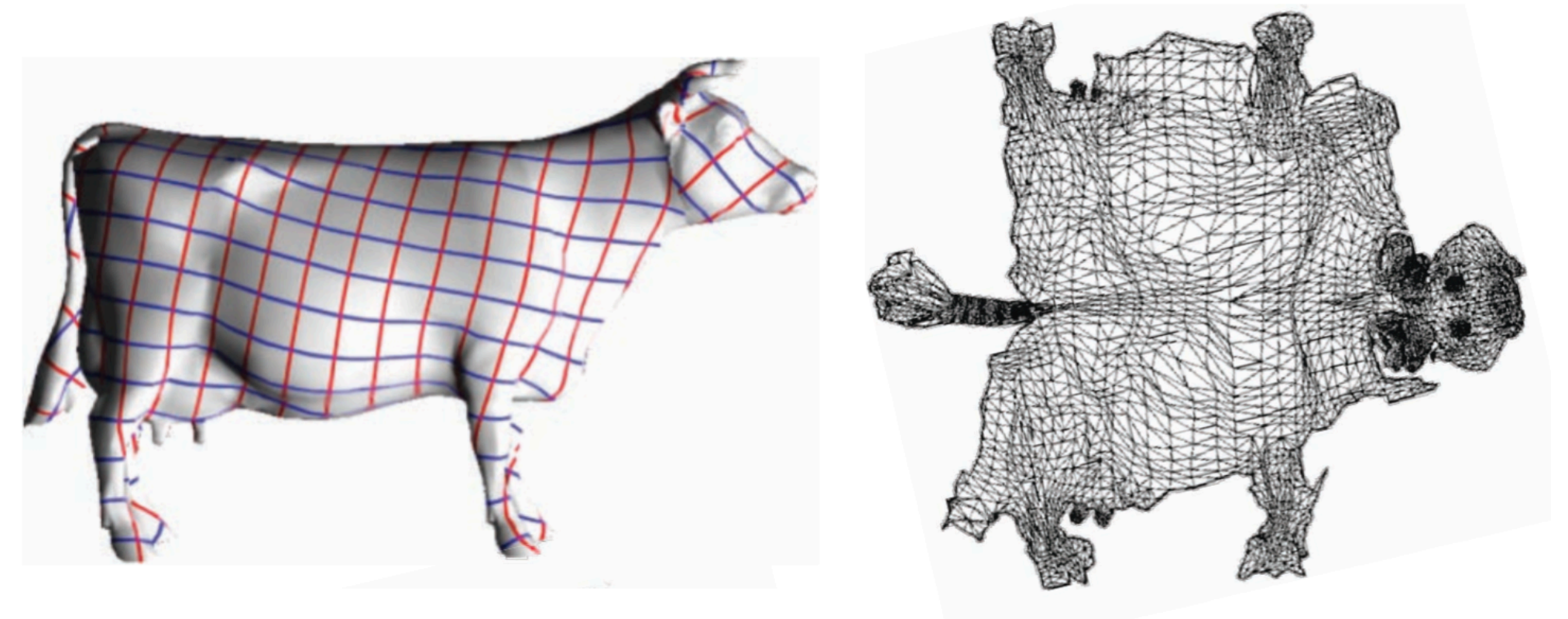
Problems

Current linear conformal methods have two major shortcomings:

NO BOUNDARY CONTROL

User obtains a single, automatic flattening

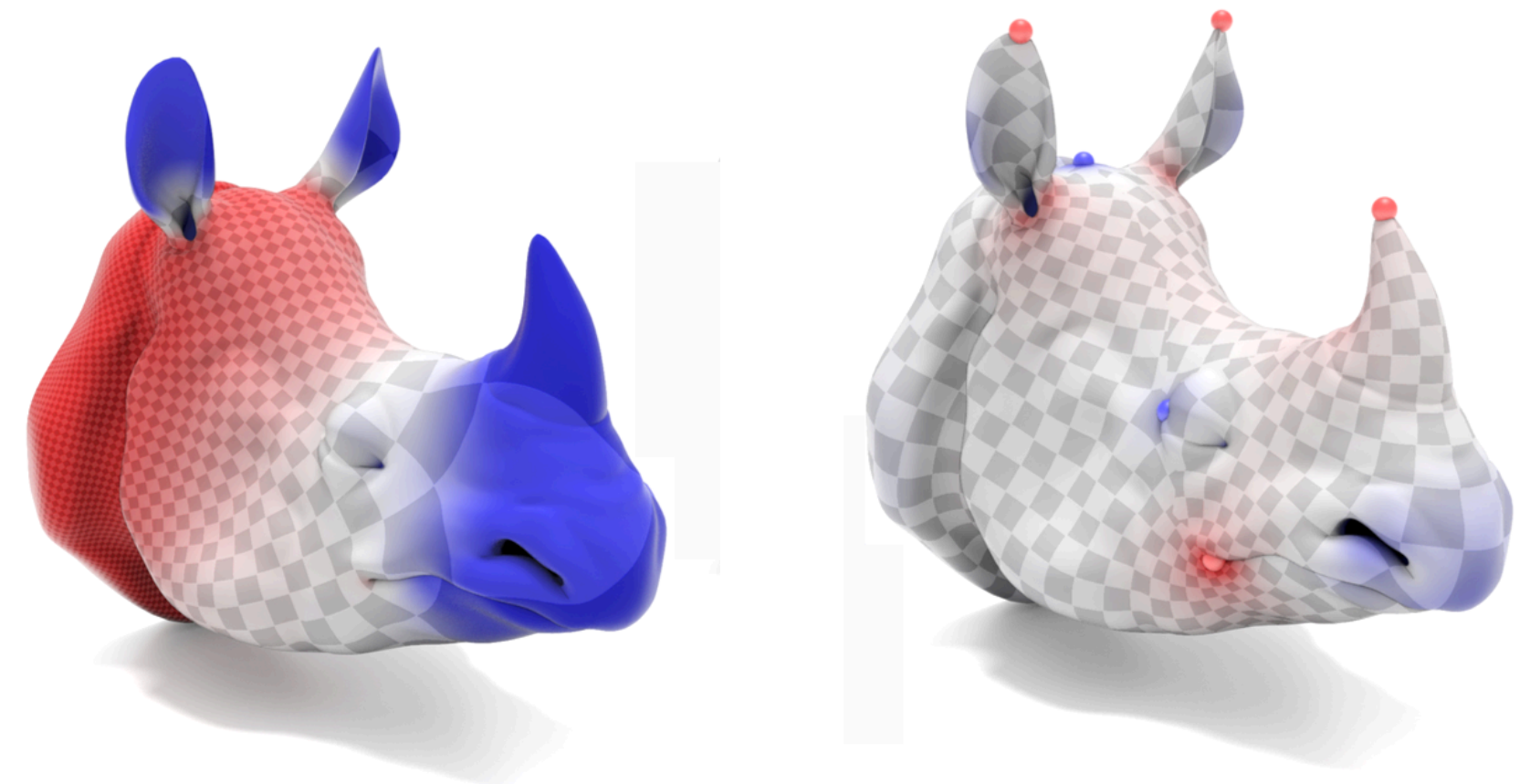
Must "take it or leave it," irrespective of quality



SCALE DISTORTION

Conformal maps can scale arbitrarily

Cone singularities mitigate scale distortion



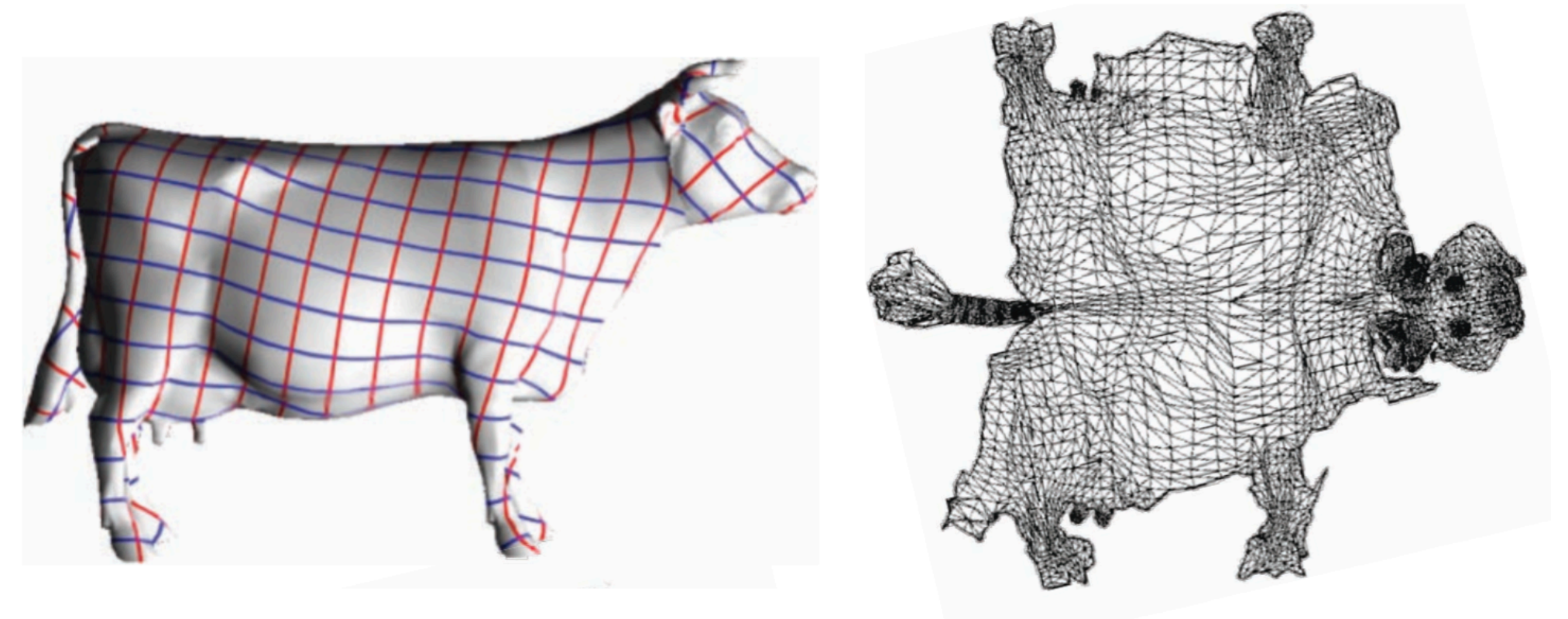
Problems

Current linear conformal methods have two major shortcomings:

NO BOUNDARY CONTROL

User obtains a single, automatic flattening

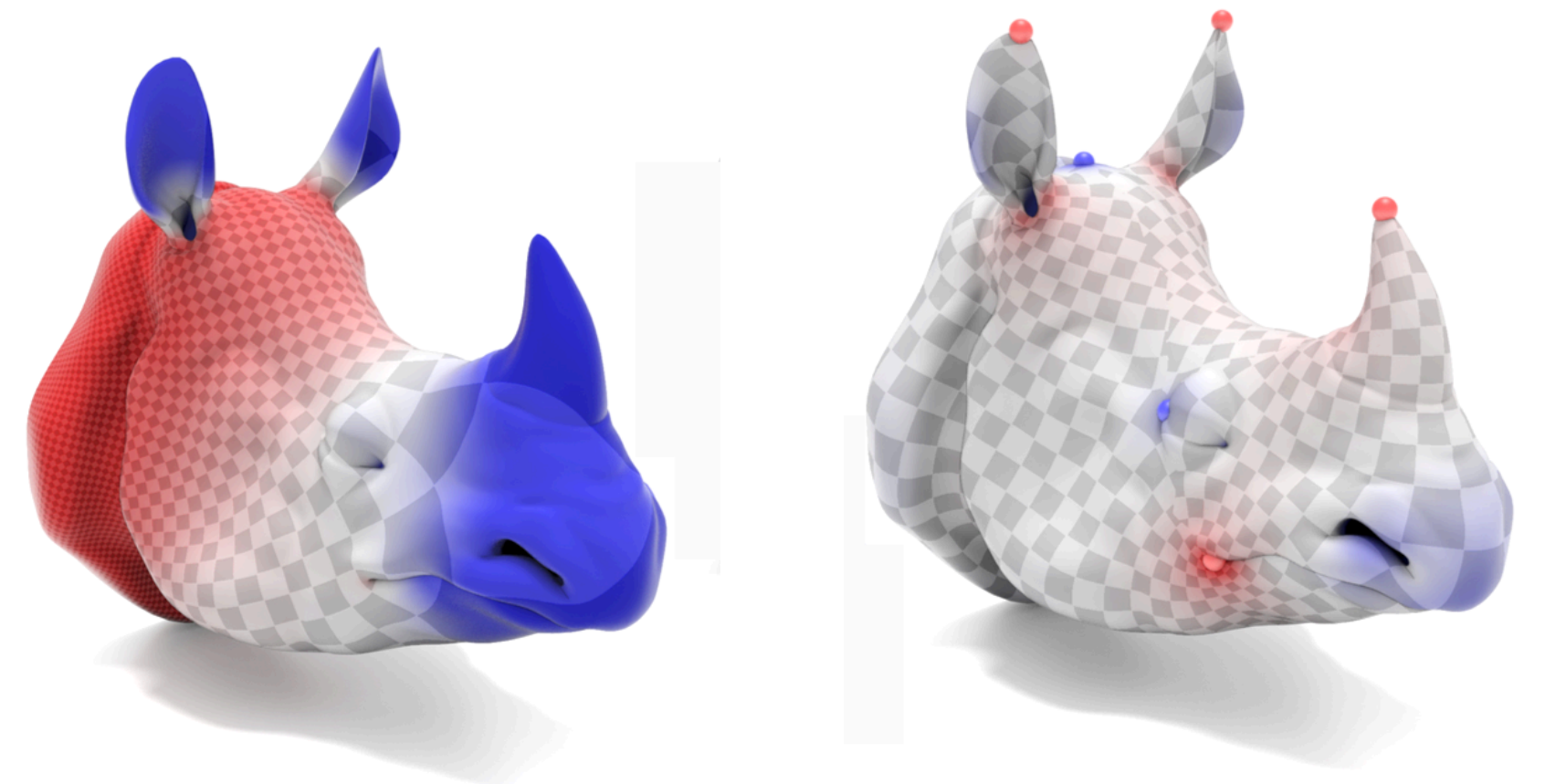
Must "take it or leave it," irrespective of quality



SCALE DISTORTION

Conformal maps can scale arbitrarily

Cone singularities mitigate scale distortion







Optimal Cone Singularities for Conformal Flattening
[Soliman et al 2018]

RELATED WORK

“Free” Boundary Methods





ALGORITHM
Least Squares Conformal Maps (LSCM)
Spectral Conformal Parameterization (SCP)
Angle Based Flattening (ABF)
Linear Angle Based Flattening (LinABF)*

“Free” Boundary Methods

ALGORITHM	BOUNDARY CONTROL
Least Squares Conformal Maps (LSCM)	
Spectral Conformal Parameterization (SCP)	
Angle Based Flattening (ABF)	
Linear Angle Based Flattening (LinABF)*	

*can be modified to provide boundary control

“Free” Boundary Methods

ALGORITHM	BOUNDARY CONTROL
Least Squares Conformal Maps (LSCM)	
Spectral Conformal Parameterization (SCP)	
Angle Based Flattening (ABF)	
Linear Angle Based Flattening (LinABF)*	

Minimize discrete energy without explicit boundary constraints

*can be modified to provide boundary control

“Free” Boundary Conditions are Meaningless

Solution has no meaningful interpretation in the smooth setting!

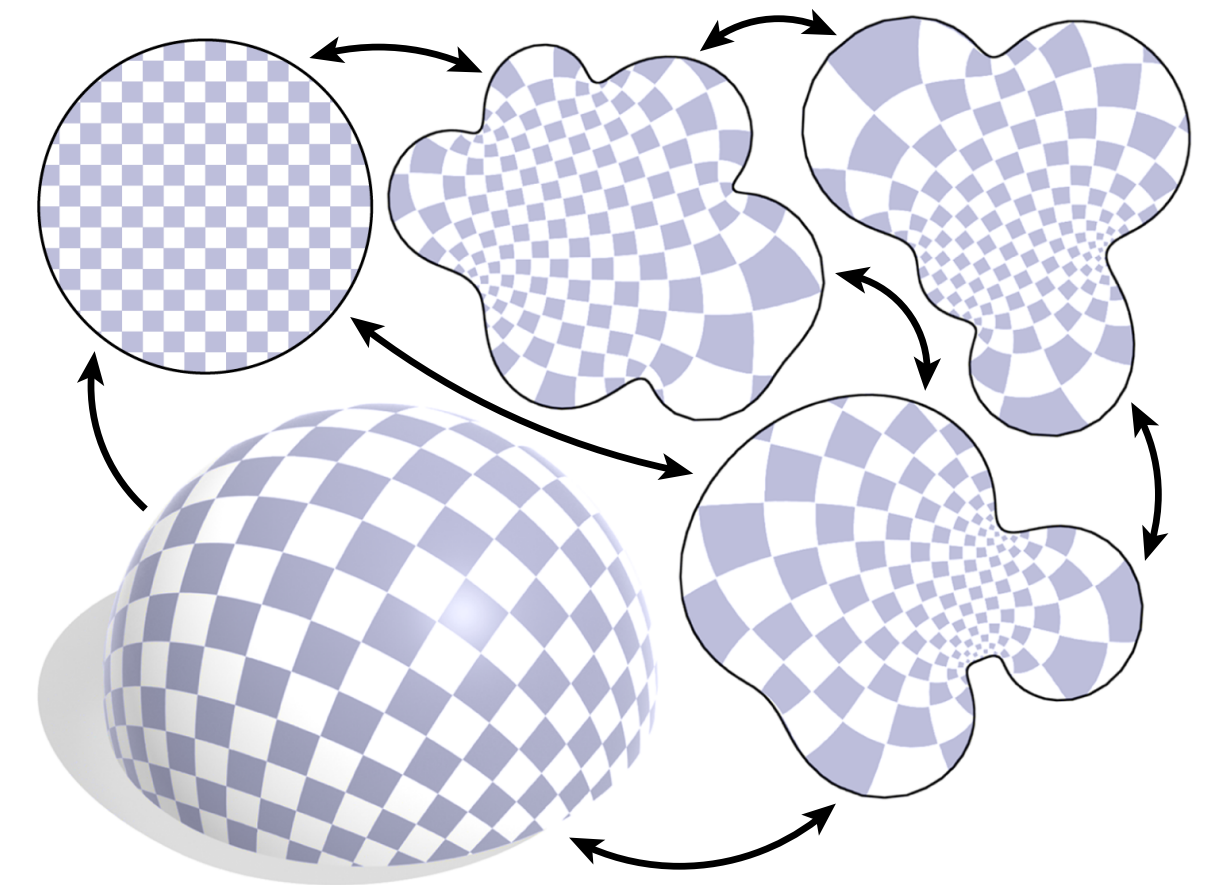
“Free” Boundary Conditions are Meaningless

Solution has no meaningful interpretation in the smooth setting!

SMOOTH SETTING

Enormous space of perfect conformal flattenings

Obtained by flattening and then applying in-plane maps



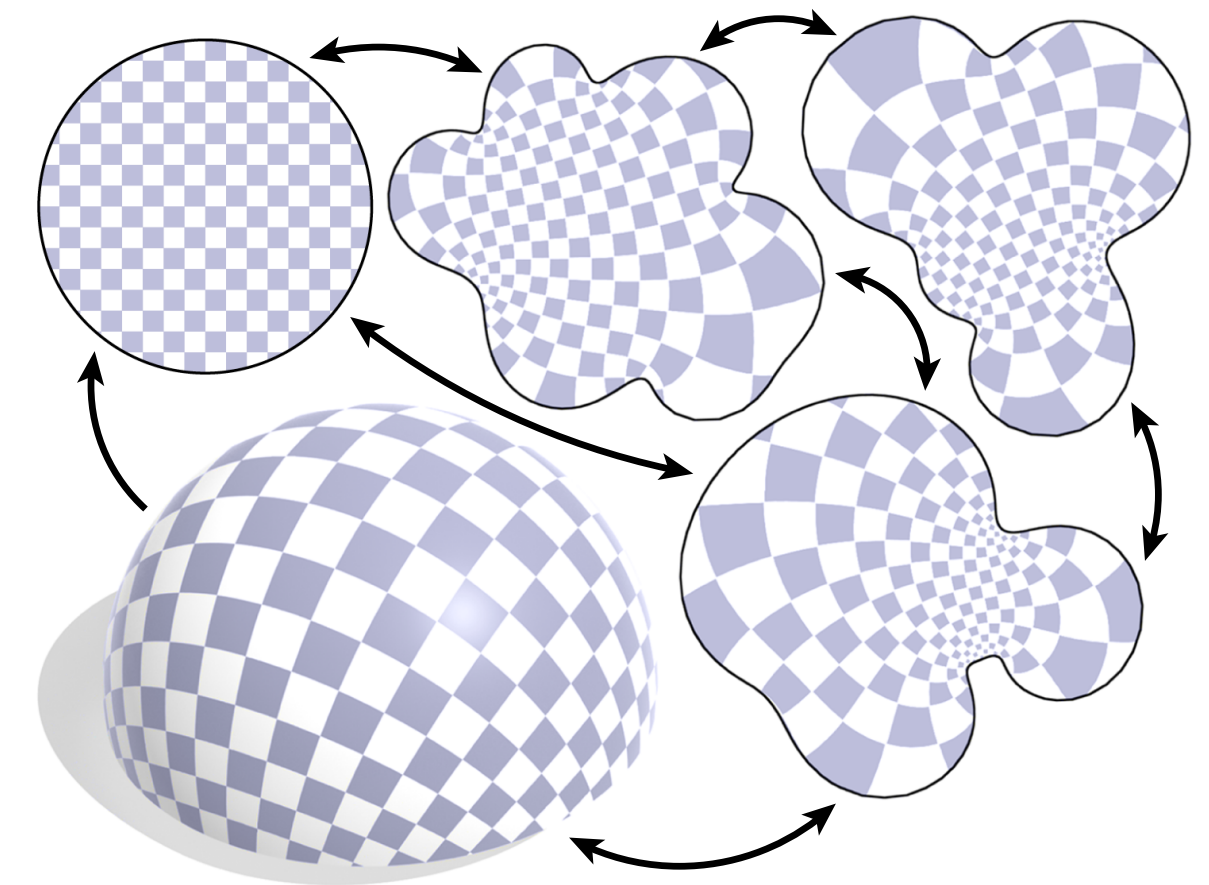
“Free” Boundary Conditions are Meaningless

Solution has no meaningful interpretation in the smooth setting!

SMOOTH SETTING

Enormous space of perfect conformal flattenings

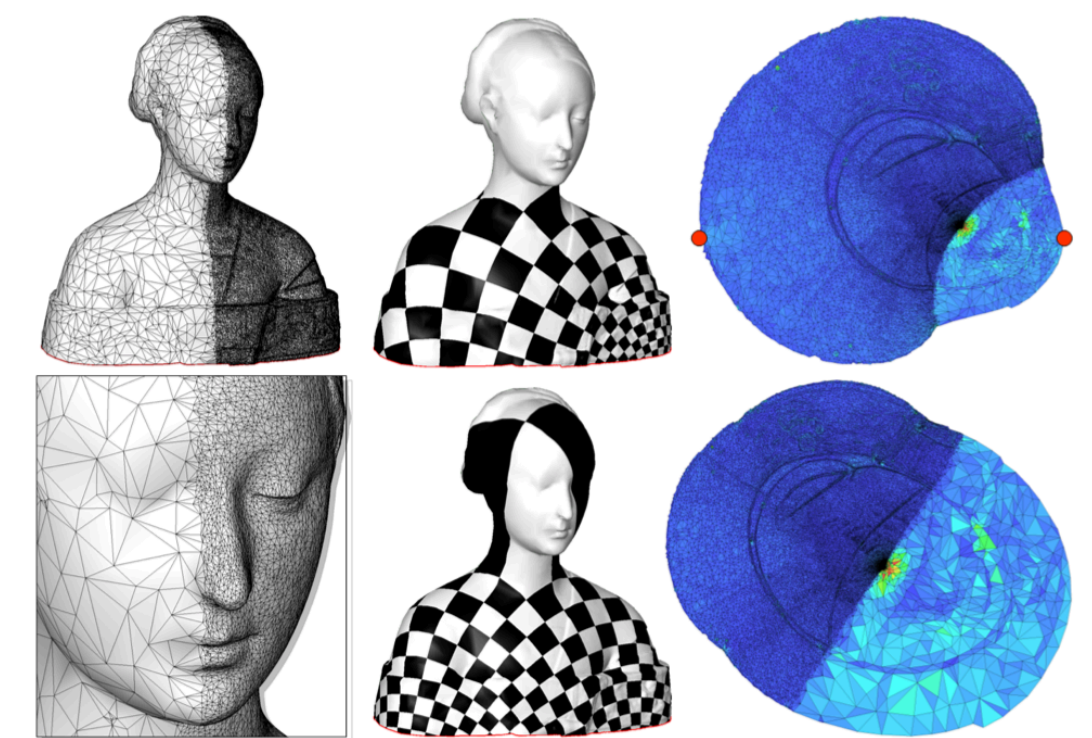
Obtained by flattening and then applying in-plane maps



DISCRETE SETTING

Unique solution must depend on discretization

Results change based on mesh or numerical treatment



Special Conformal Parameterization
[Mullen et al 2008]

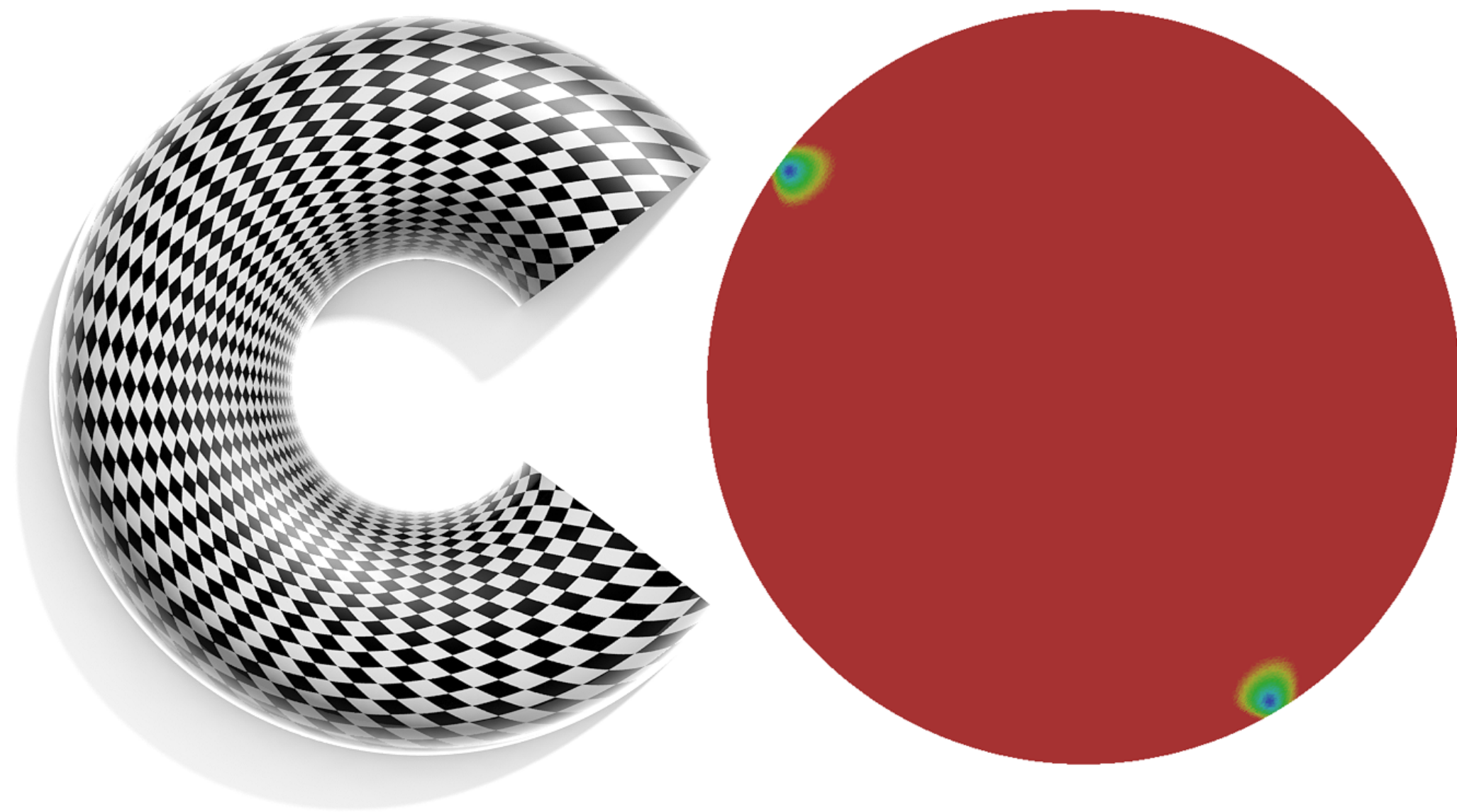
Forcing the Boundary

First attempt: Pin all boundary points to get desired shape

Forcing the Boundary

First attempt: Pin all boundary points to get desired shape

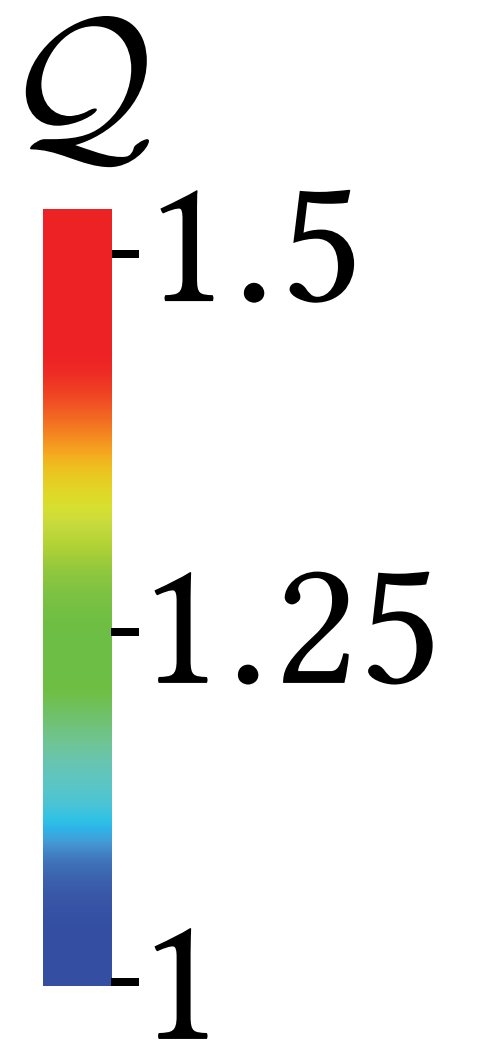
Least squares yields harmonic map with severe angle distortion:







Harmonic



Conformal







Prescribed Lengths and Angles

ALGORITHM	COMPLEXITY	BOUNDARY CONTROL
Circle Patterns (CP)	Nonlinear	 (only angles)
Conformal Equivalence (CETM)	Nonlinear	
Curvature Prescription (CPMS)*	Linear	
Boundary First Flattening (BFF)	Linear	





*can be modified to provide boundary control

Prescribed Lengths and Angles

ALGORITHM	COMPLEXITY	BOUNDARY CONTROL
Circle Patterns (CP)	Nonlinear	 (only angles)
Conformal Equivalence (CETM)	Nonlinear	
Curvature Prescription (CPMS)*	Linear	
Boundary First Flattening (BFF)	Linear	

*can be modified to provide boundary control

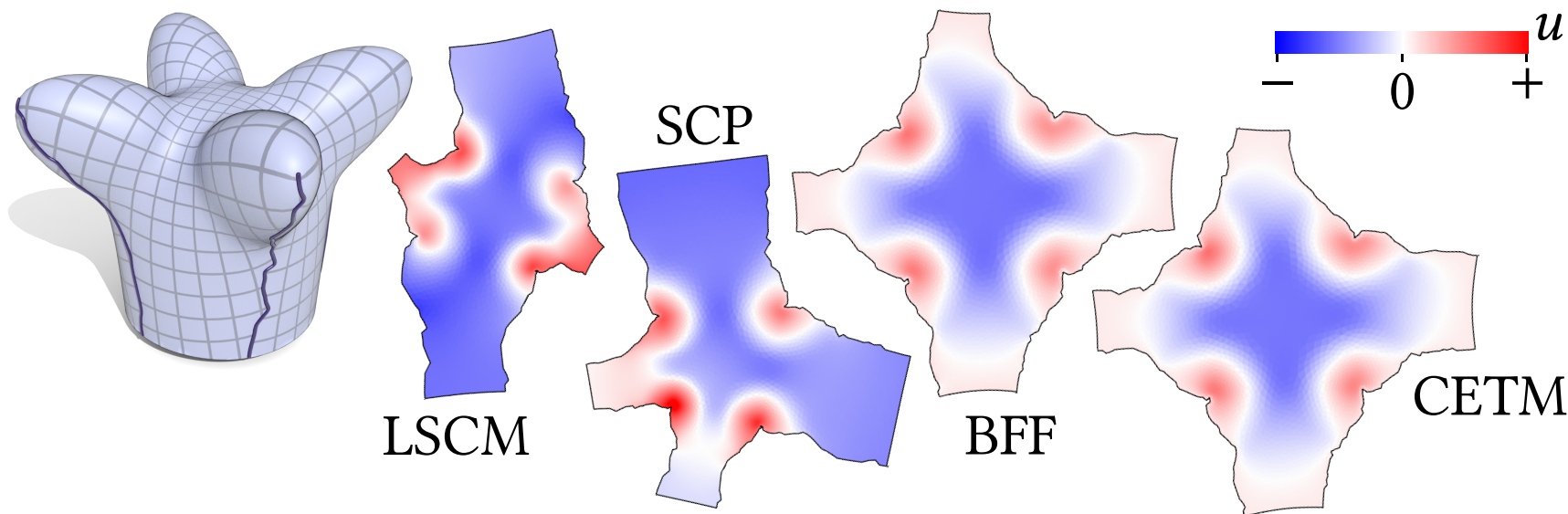
Prescribed Lengths and Angles

ALGORITHM	COMPLEXITY	BOUNDARY CONTROL
Circle Patterns (CP)	Nonlinear	 (only angles)
Conformal Equivalence (CETM)	Nonlinear	
Curvature Prescription (CPMS)*	Linear	
Boundary First Flattening (BFF)	Linear	

BFF is faster than existing linear methods

Quality & control comparable to nonlinear schemes

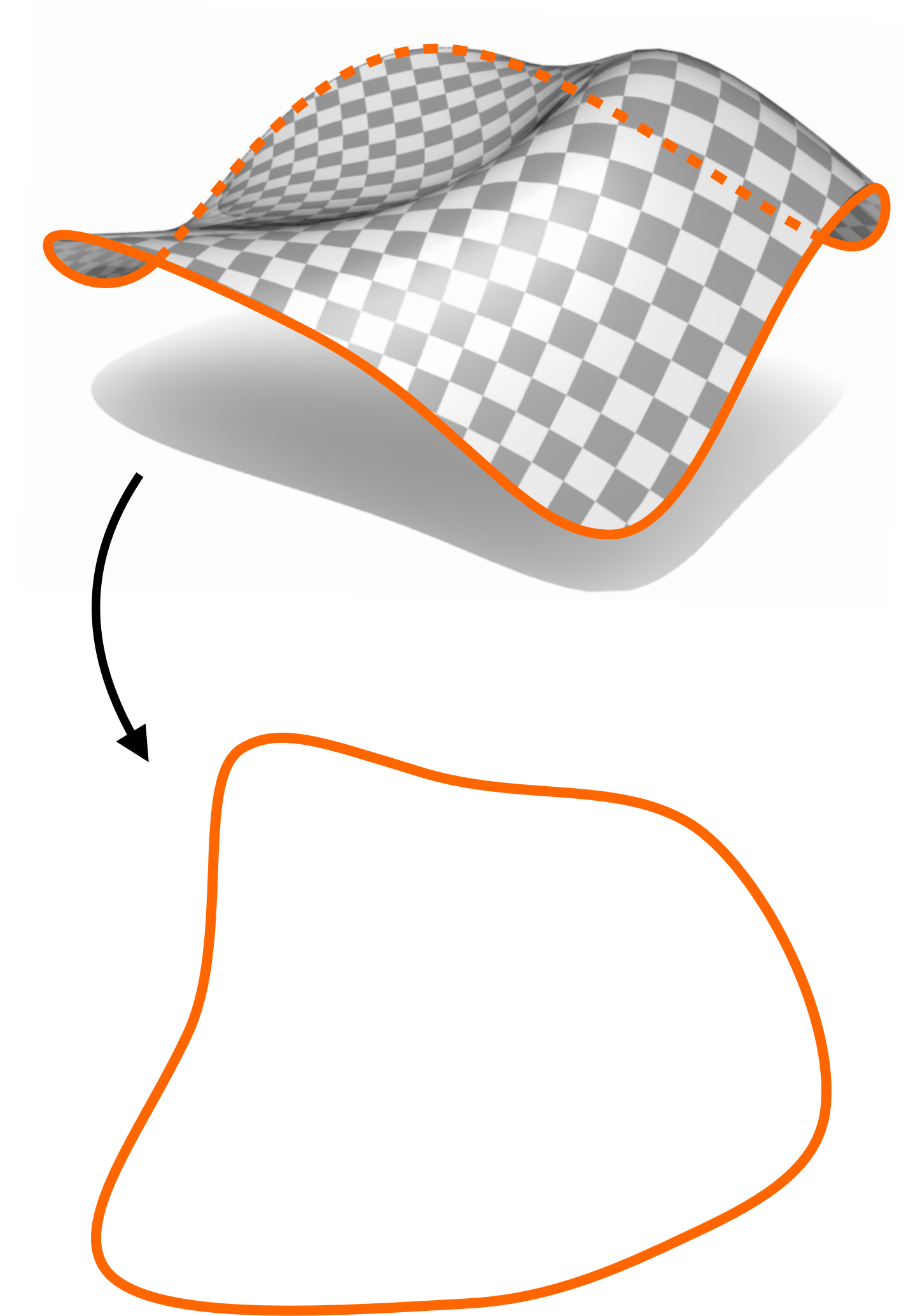
*can be modified to provide boundary control



SMOOTH THEORY

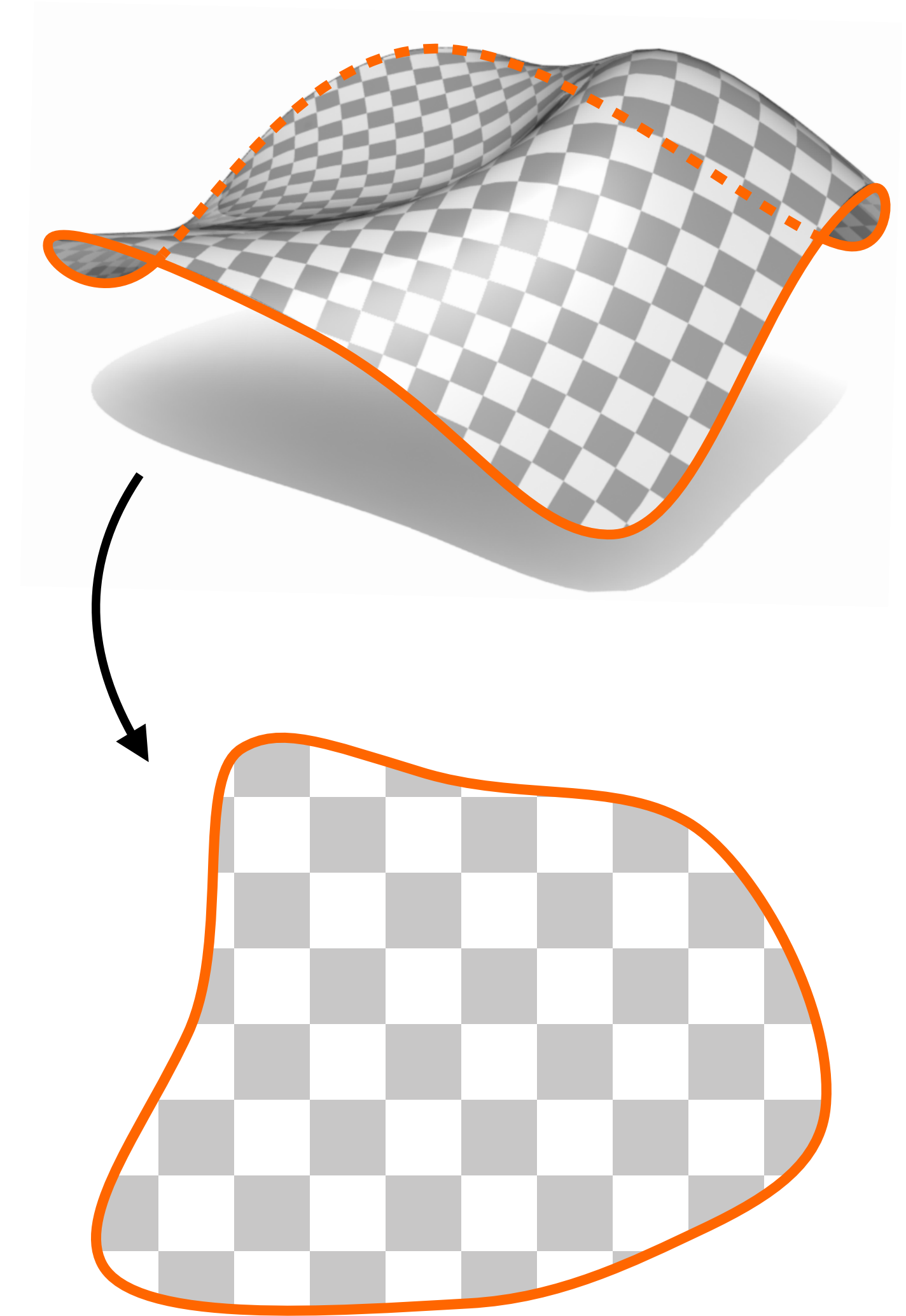
Key Idea

If you know the boundary
of a conformal map,

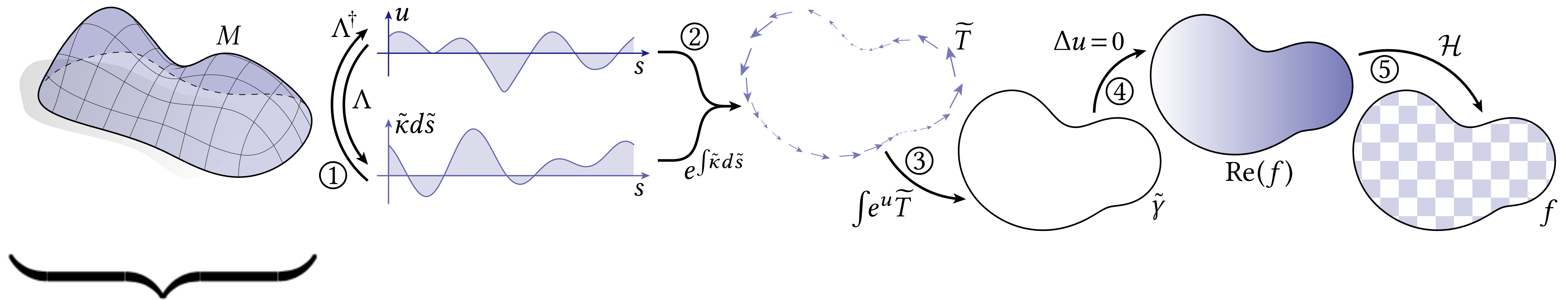


Key Idea

If you know the boundary
of a conformal map,
then extension to the
interior is easy

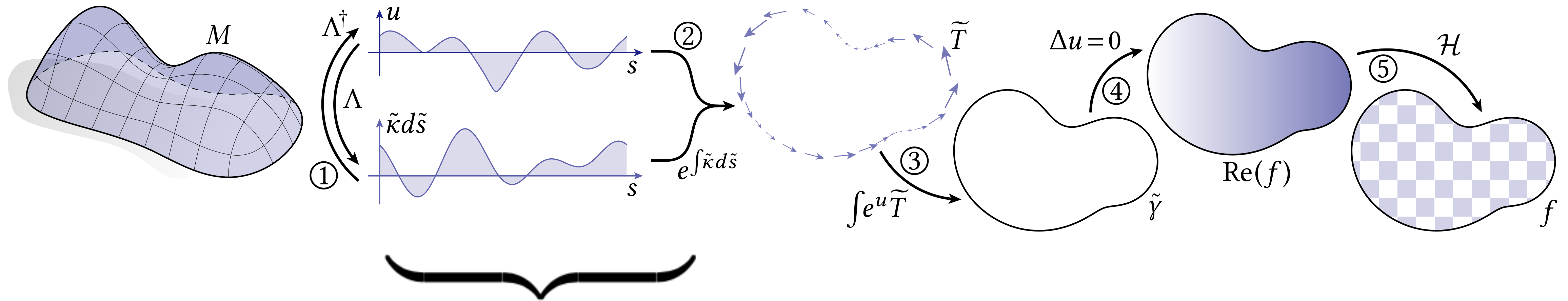


Algorithm Outline



Given a surface with either scale or curvature of target boundary curve

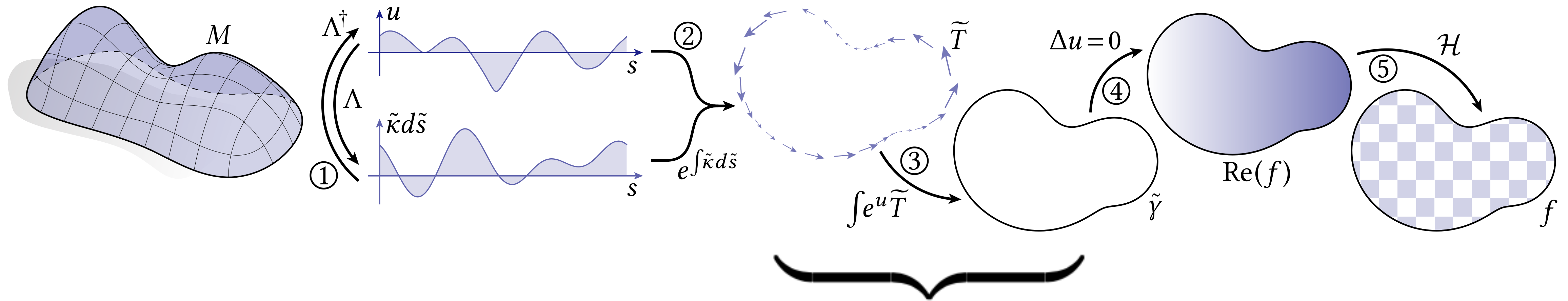
Algorithm Outline



Given a surface with either scale or curvature of target boundary curve

1. Solve *Yamabe Problem* to get complementary data (curvature or scale)

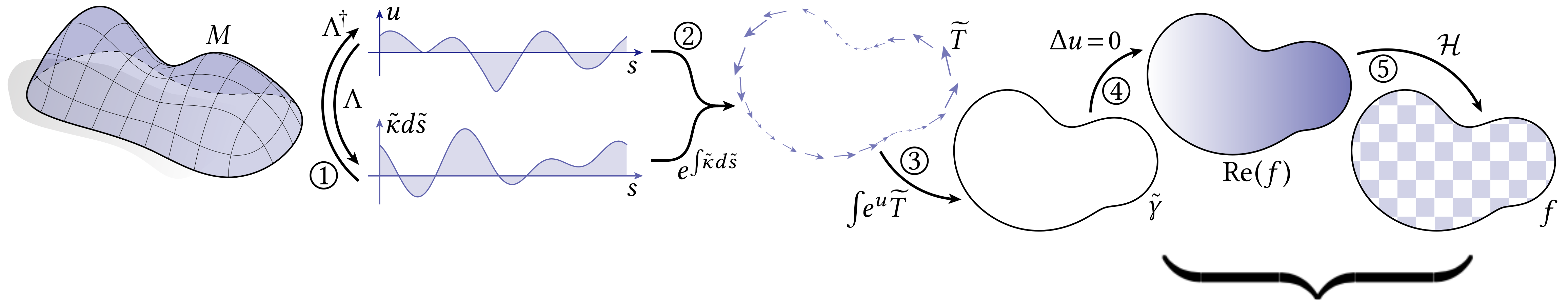
Algorithm Outline



Given a surface with either scale or curvature of target boundary curve

1. Solve *Yamabe Problem* to get complementary data (curvature or scale)
2. Integrate boundary data to get boundary curve

Algorithm Outline



Given a surface with either scale or curvature of target boundary curve

1. Solve *Yamabe Problem* to get complementary data (curvature or scale)
2. Integrate boundary data to get boundary curve
3. Extend boundary curve to a pair of *conjugate harmonic functions*

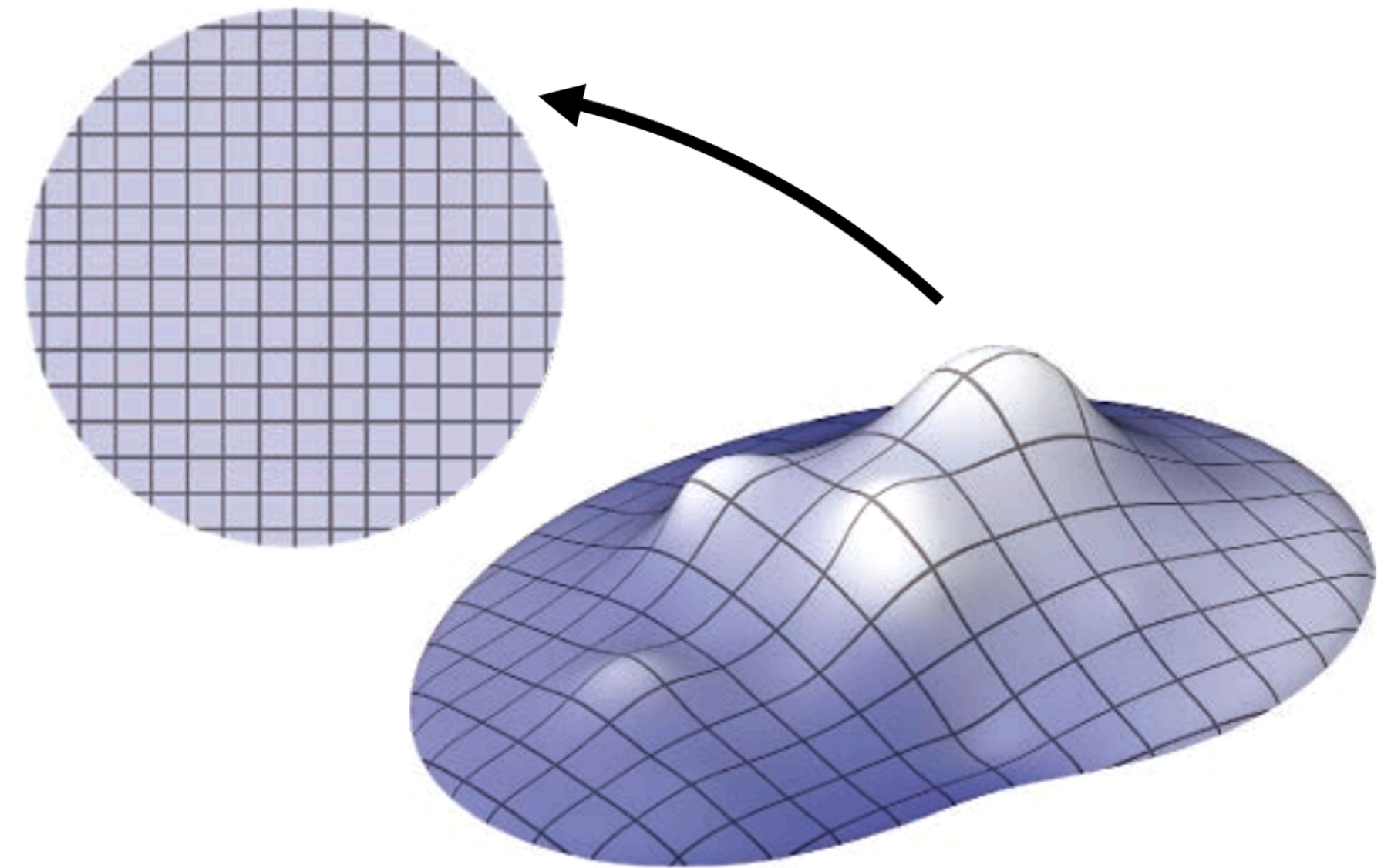
Compatibility of Boundary Data

**Not every parameterized curve is
the boundary of a conformal map!**

Yamabe Problem

Yamabe equation provides explicit relationship between conformal scaling and change in curvature:

$$\Delta u = K - e^{2u} \tilde{K} \quad \text{on } M$$



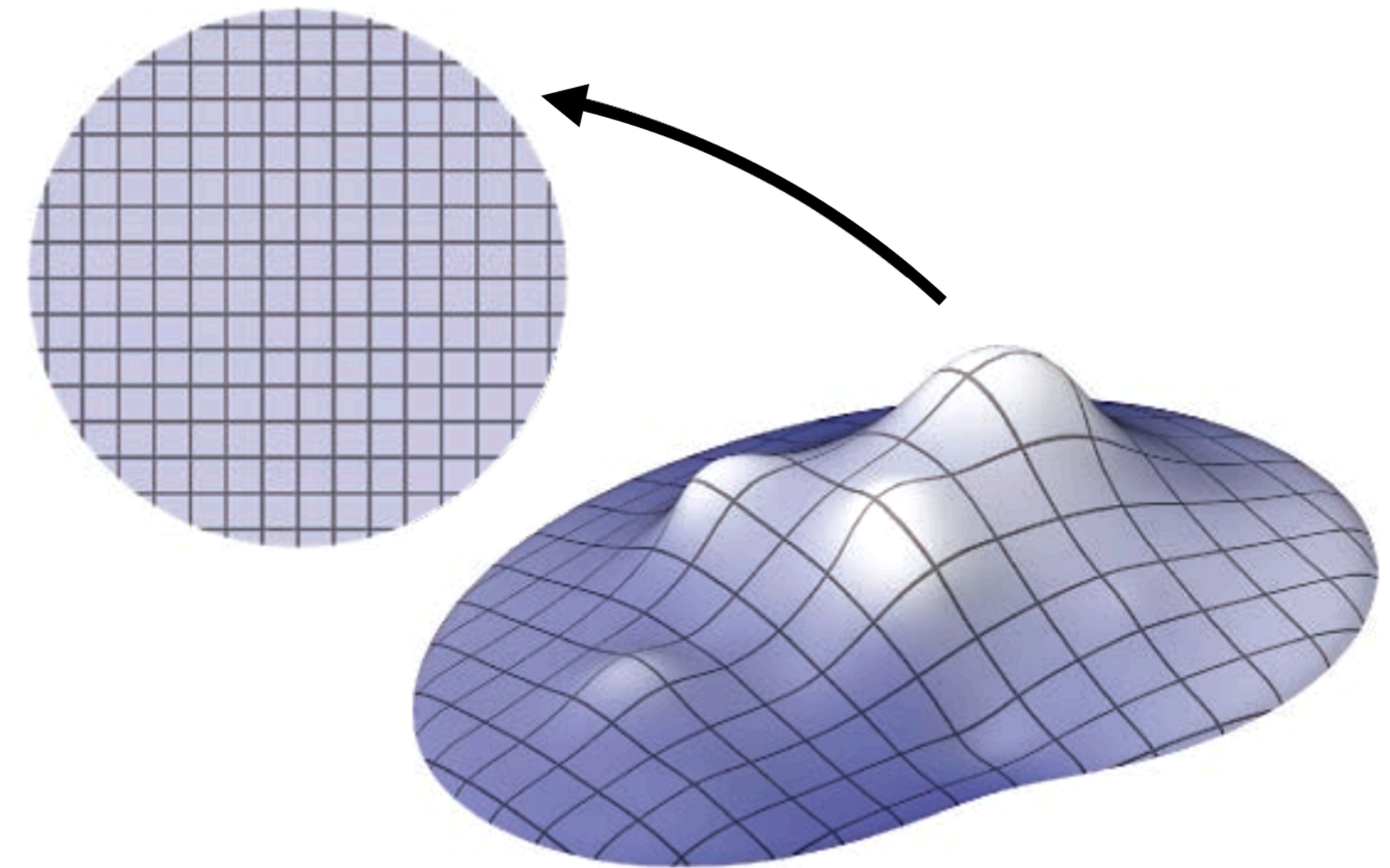
Yamabe Problem

Yamabe equation provides explicit relationship between conformal scaling and change in curvature:

$$\Delta u = K - e^{2u} \tilde{K} \quad \text{on } M$$

log scale factor

↓



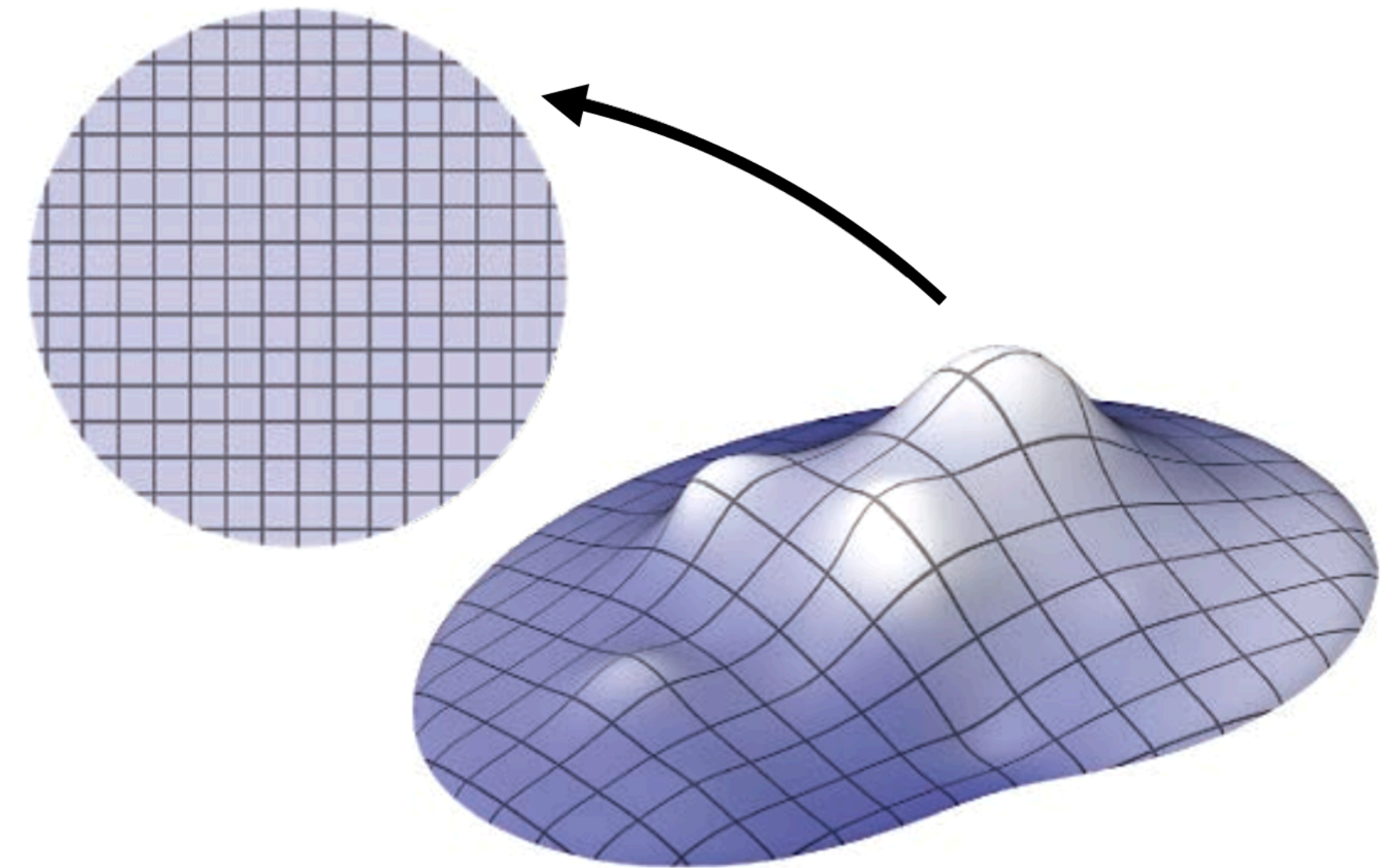
Yamabe Problem

Yamabe equation provides explicit relationship between conformal scaling and change in curvature:

$$\Delta u = K - e^{2u} \tilde{K} \quad \text{on } M$$

Diagram illustrating the Yamabe equation with labels:

- Δu : log scale factor
- K : original Gaussian curvature
- $e^{2u} \tilde{K}$: new Gaussian curvature



Yamabe Problem

Yamabe equation provides explicit relationship between conformal scaling and change in curvature:

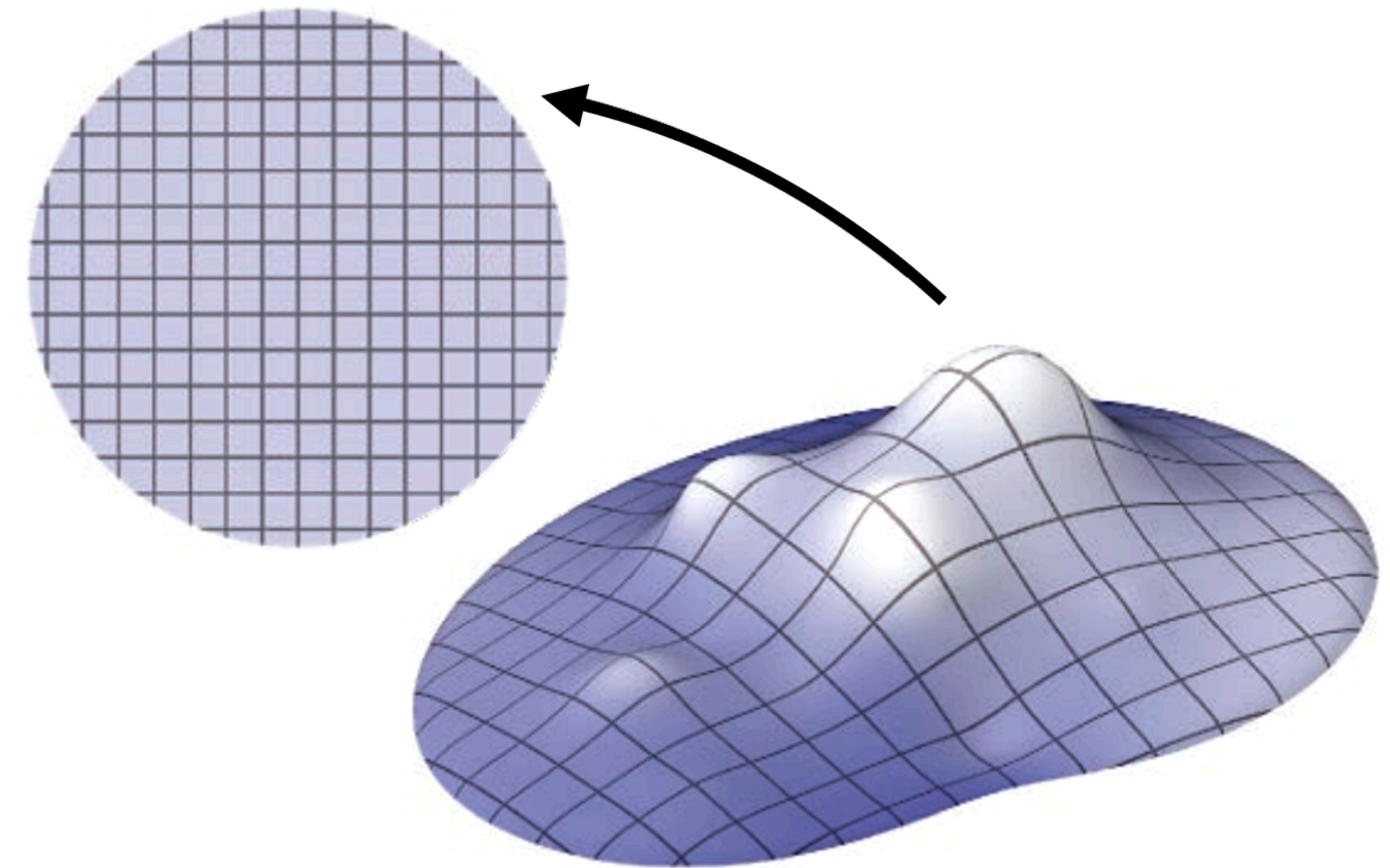
$$\Delta u = K - e^{2u} \tilde{K} \quad \text{on } M$$

Diagram illustrating the Yamabe equation with labels:

- Δu : log scale factor
- K : original Gaussian curvature
- $e^{2u} \tilde{K}$: new Gaussian curvature

Cherrier boundary conditions:

$$\frac{\partial u}{\partial n} = \kappa - e^u \tilde{\kappa} \quad \text{on } \partial M$$



Yamabe Problem

Yamabe equation provides explicit relationship between conformal scaling and change in curvature:

$$\Delta u = K - e^{2u} \tilde{K} \quad \text{on } M$$

Diagram illustrating the Yamabe equation:

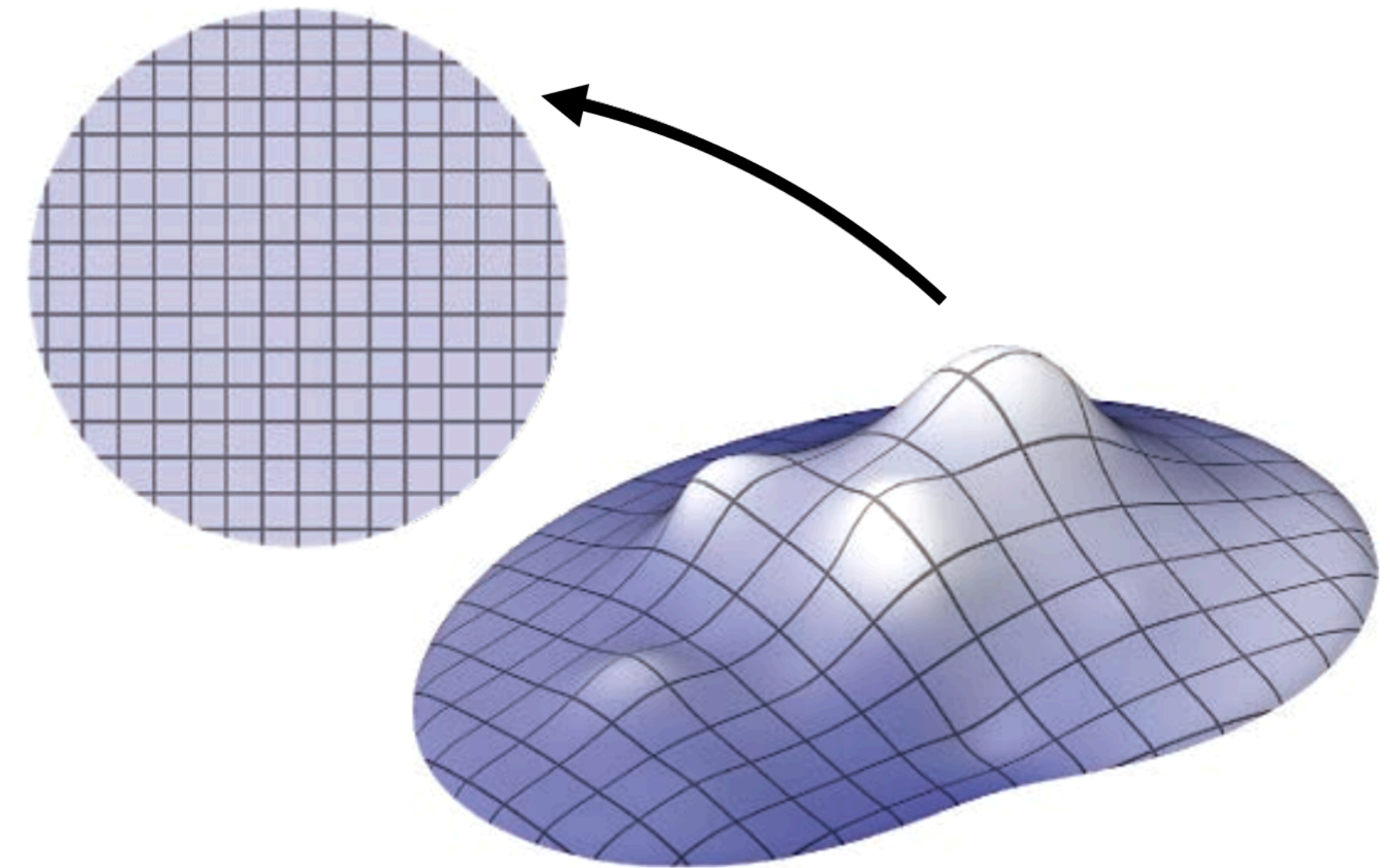
- Δu : Laplacian of the log scale factor u
- K : original Gaussian curvature
- $e^{2u} \tilde{K}$: new Gaussian curvature

Cherrier boundary conditions:

$$\frac{\partial u}{\partial n} = \kappa - e^u \tilde{\kappa} \quad \text{on } \partial M$$

Diagram illustrating the Cherrier boundary conditions:

- $\frac{\partial u}{\partial n}$: normal derivative of the log scale factor u
- κ : original geodesic curvature
- $e^u \tilde{\kappa}$: new geodesic curvature



Yamabe Problem

Yamabe equation provides explicit relationship between conformal scaling and change in curvature:

$$\Delta u = K - e^{2u} \tilde{K} \quad \text{on } M$$

Diagram illustrating the Yamabe equation:

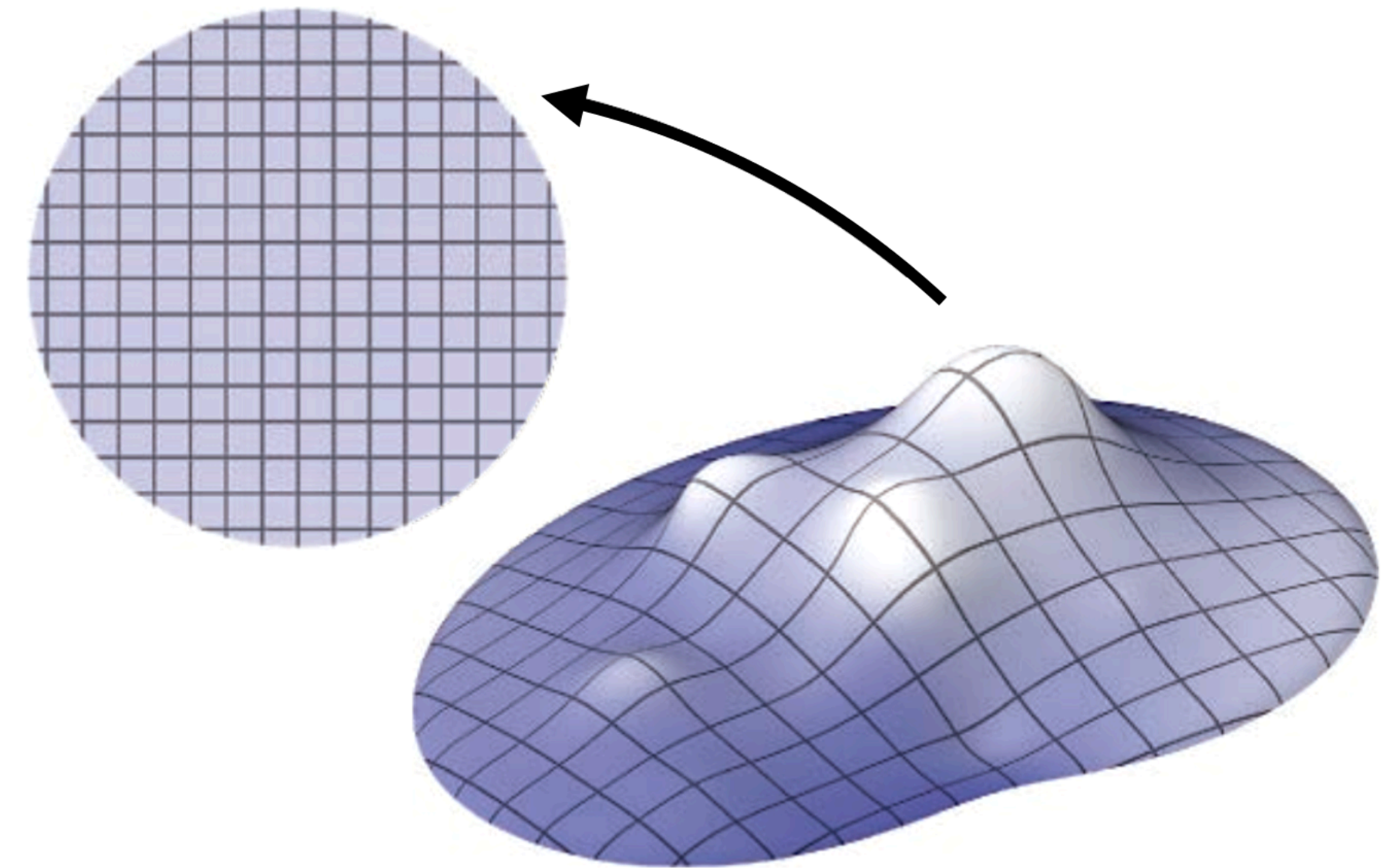
- Δu : Laplacian of the log scale factor u
- K : original Gaussian curvature
- $e^{2u} \tilde{K}$: new Gaussian curvature

Cherrier boundary conditions:

$$\frac{\partial u}{\partial n} = \kappa - e^u \tilde{\kappa} \quad \text{on } \partial M$$

Diagram illustrating the Cherrier boundary conditions:

- $\frac{\partial u}{\partial n}$: normal derivative of the log scale factor u
- κ : original geodesic curvature
- $e^u \tilde{\kappa}$: new geodesic curvature



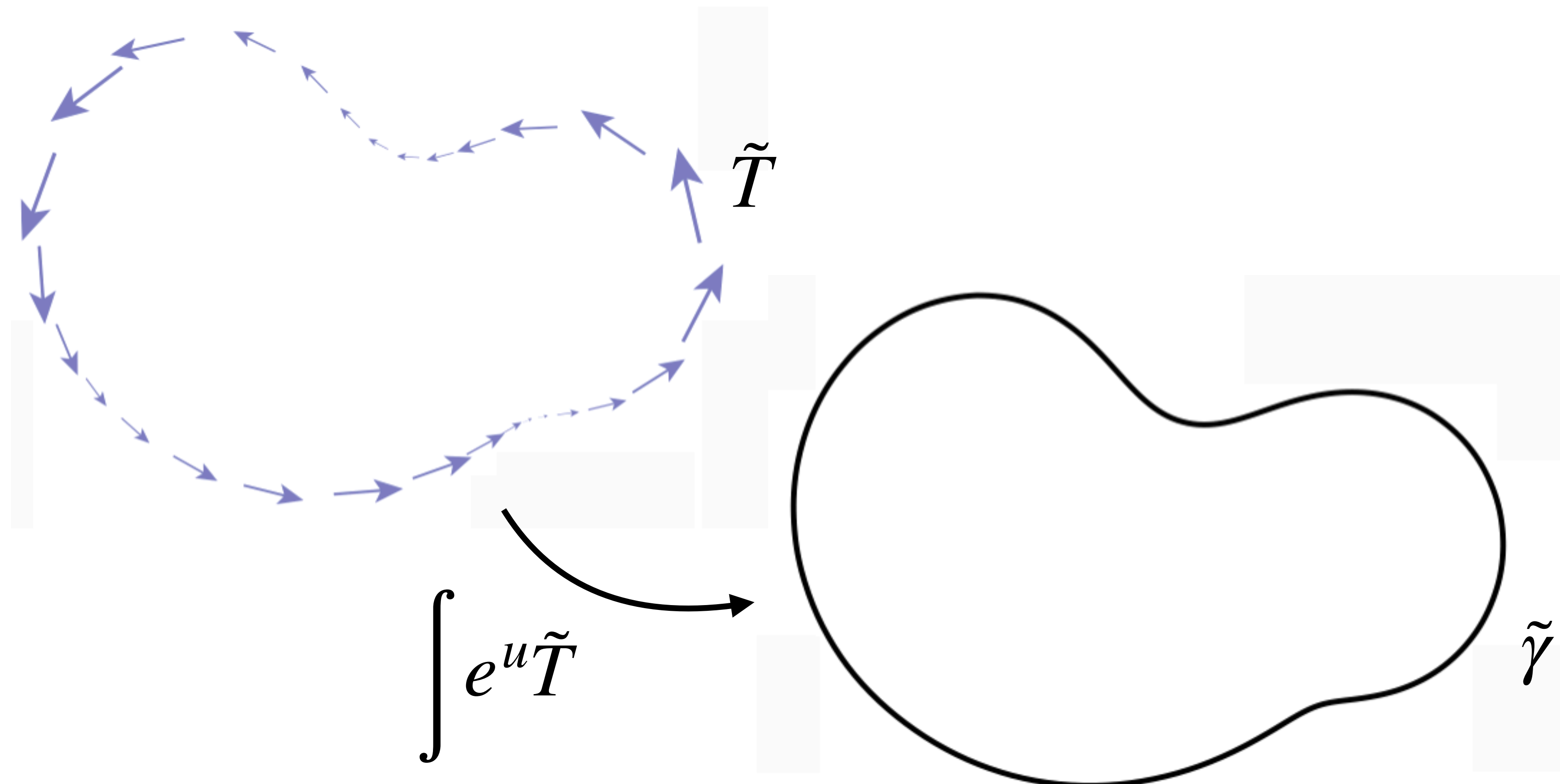
Can prescribe either curvature or scaling,
but not both!

Curve Integration

Curvature and scaling determine a closed curve up to rigid transformation

Curve Integration

Curvature and scaling determine a closed curve up to rigid transformation

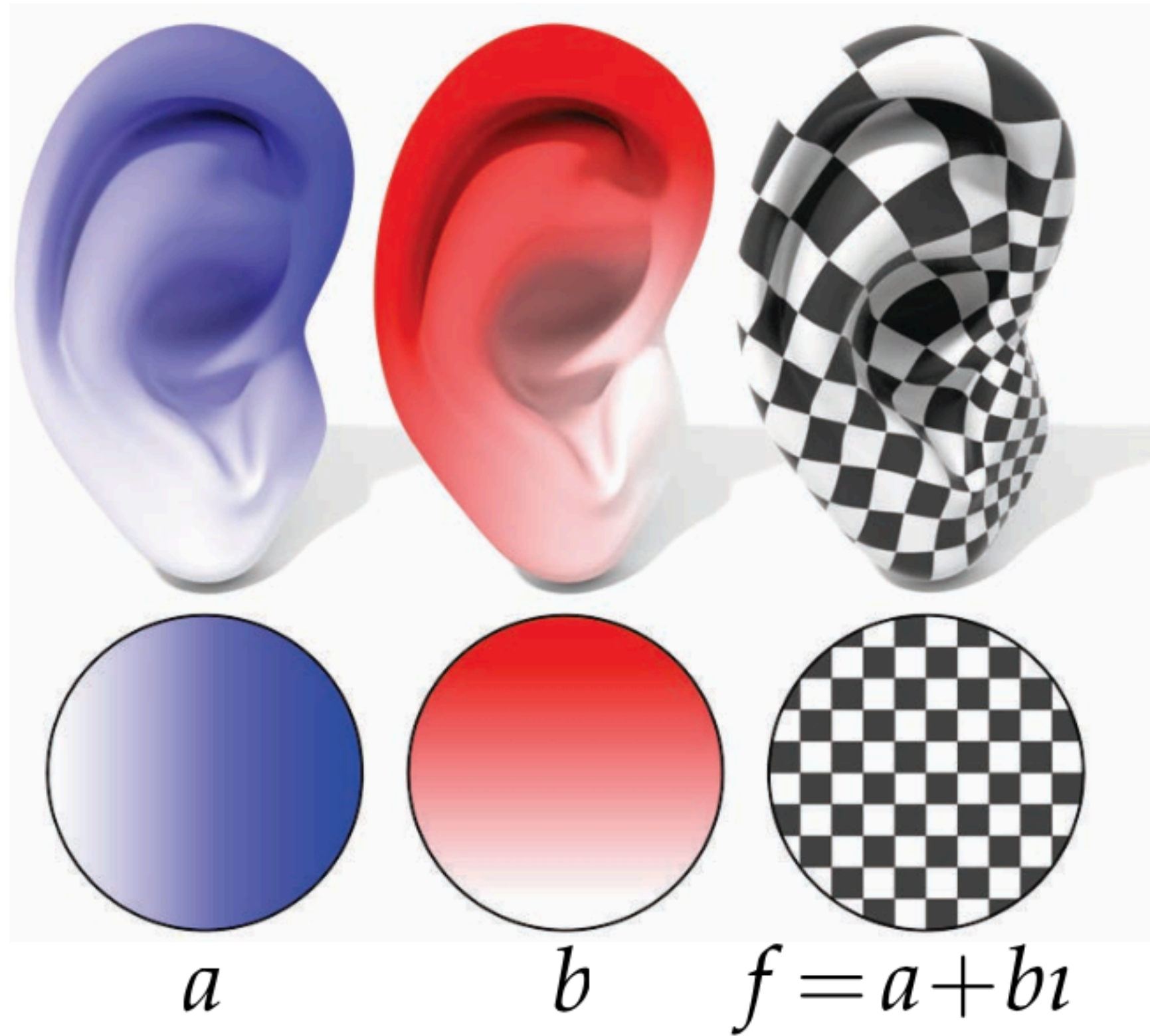


Conjugate Harmonic Functions

How do we find the solution on the interior?

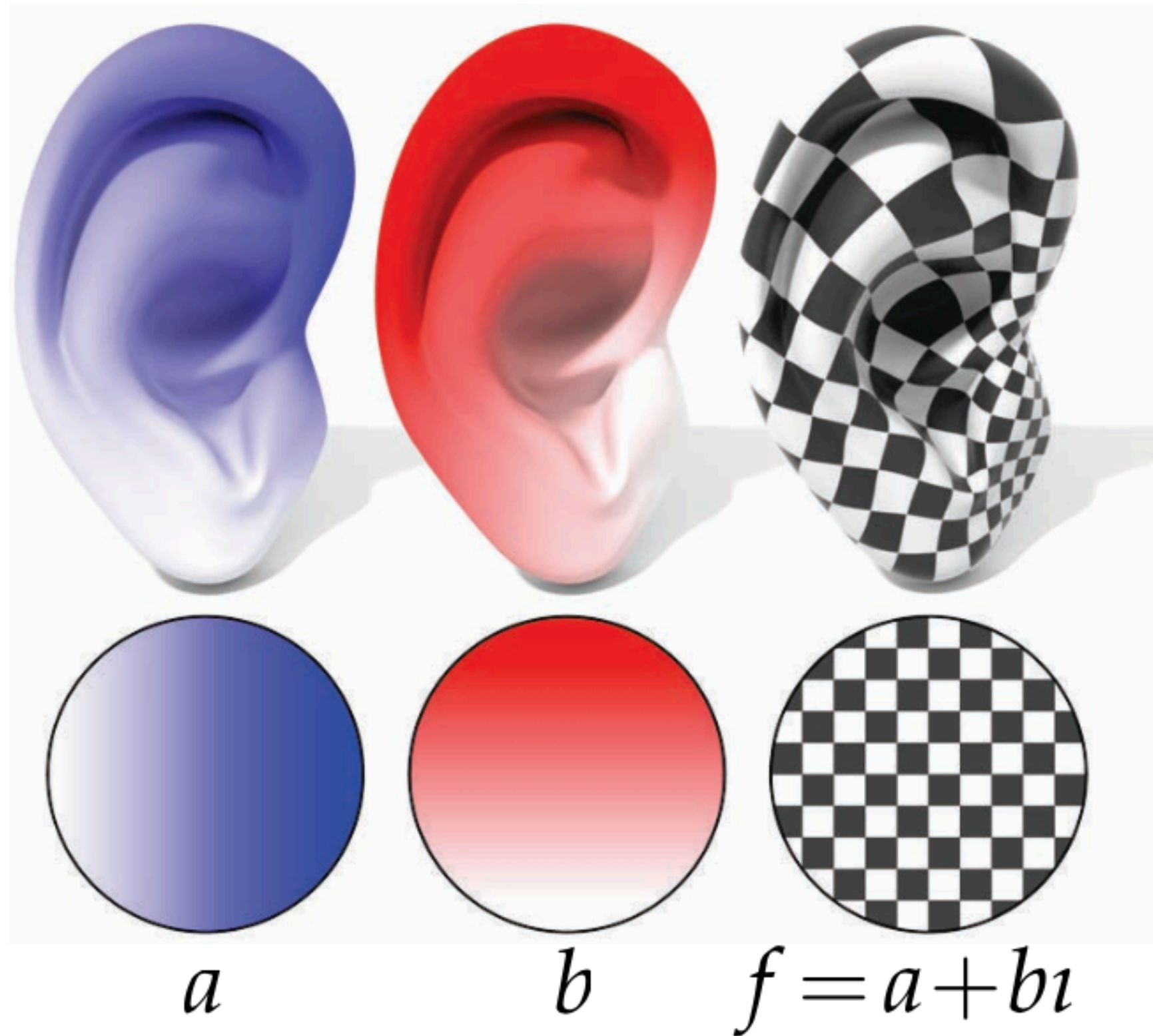
Conjugate Harmonic Functions

How do we find the solution on the interior?



Conjugate Harmonic Functions

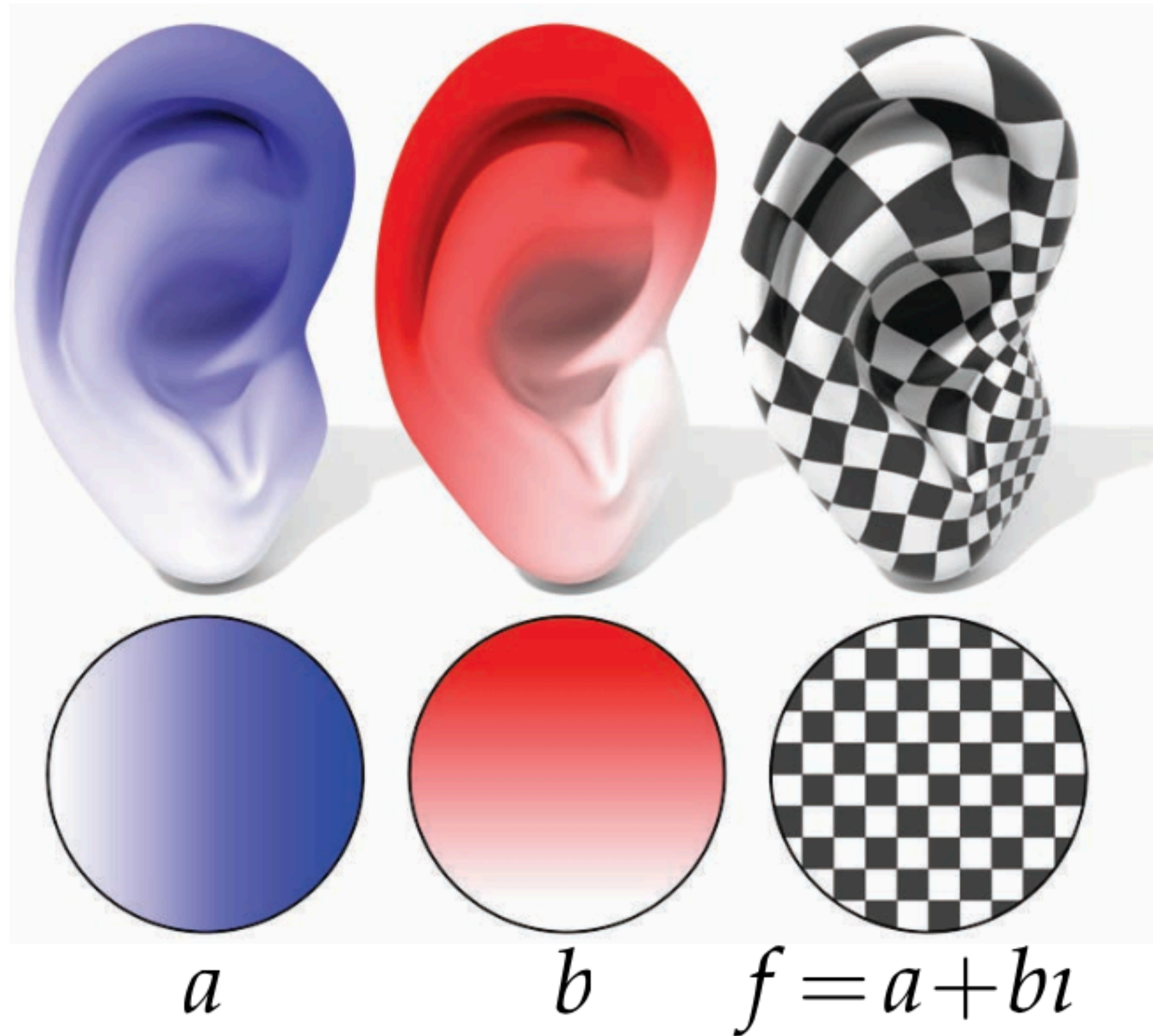
How do we find the solution on the interior?



$$J \nabla a = \nabla b$$

Conjugate Harmonic Functions

How do we find the solution on the interior?



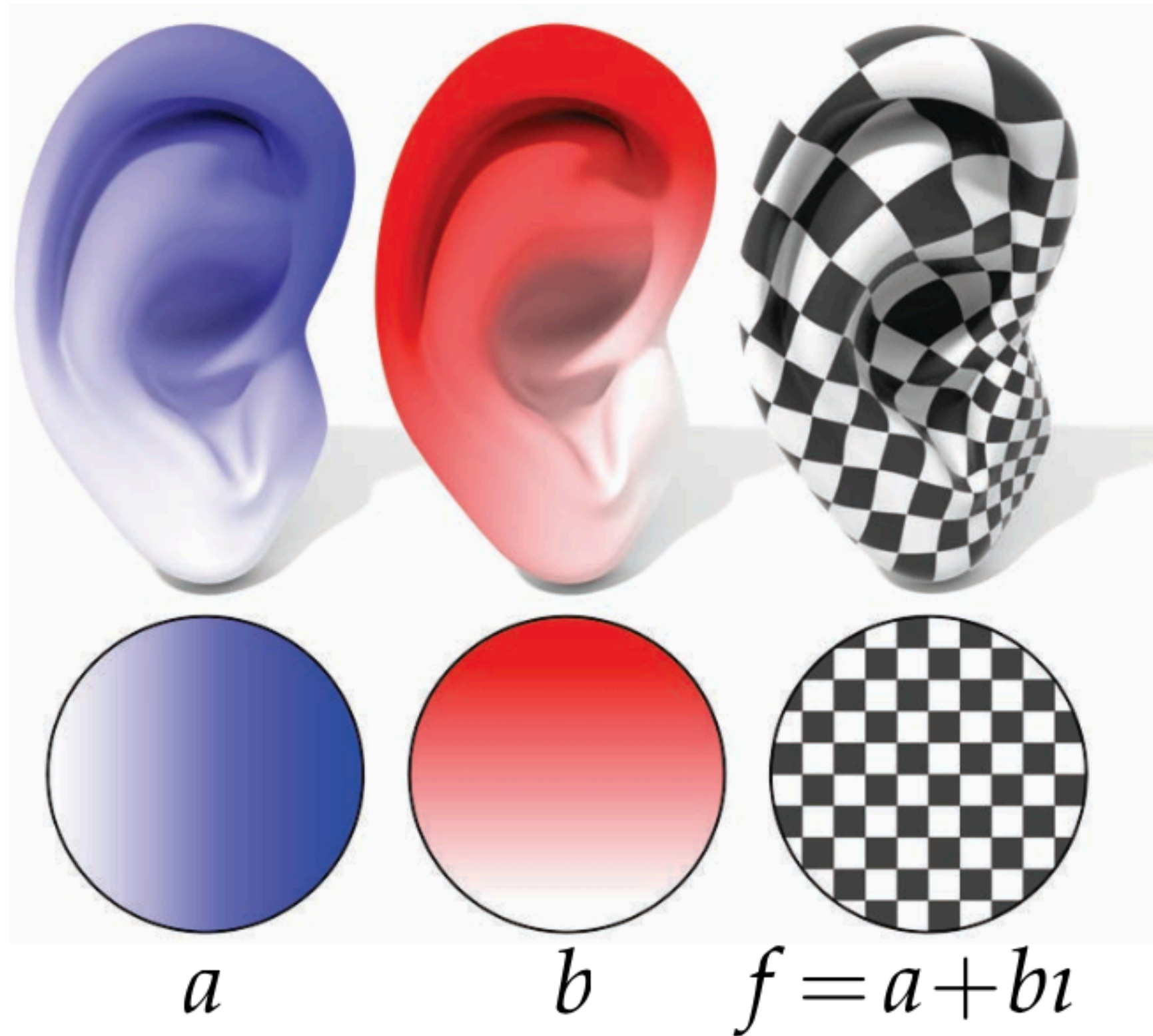
$$J \nabla a = \nabla b$$

$$\Delta a = 0$$

$$\Delta b = 0$$

Conjugate Harmonic Functions

How do we find the solution on the interior?



$$J \nabla a = \nabla b$$

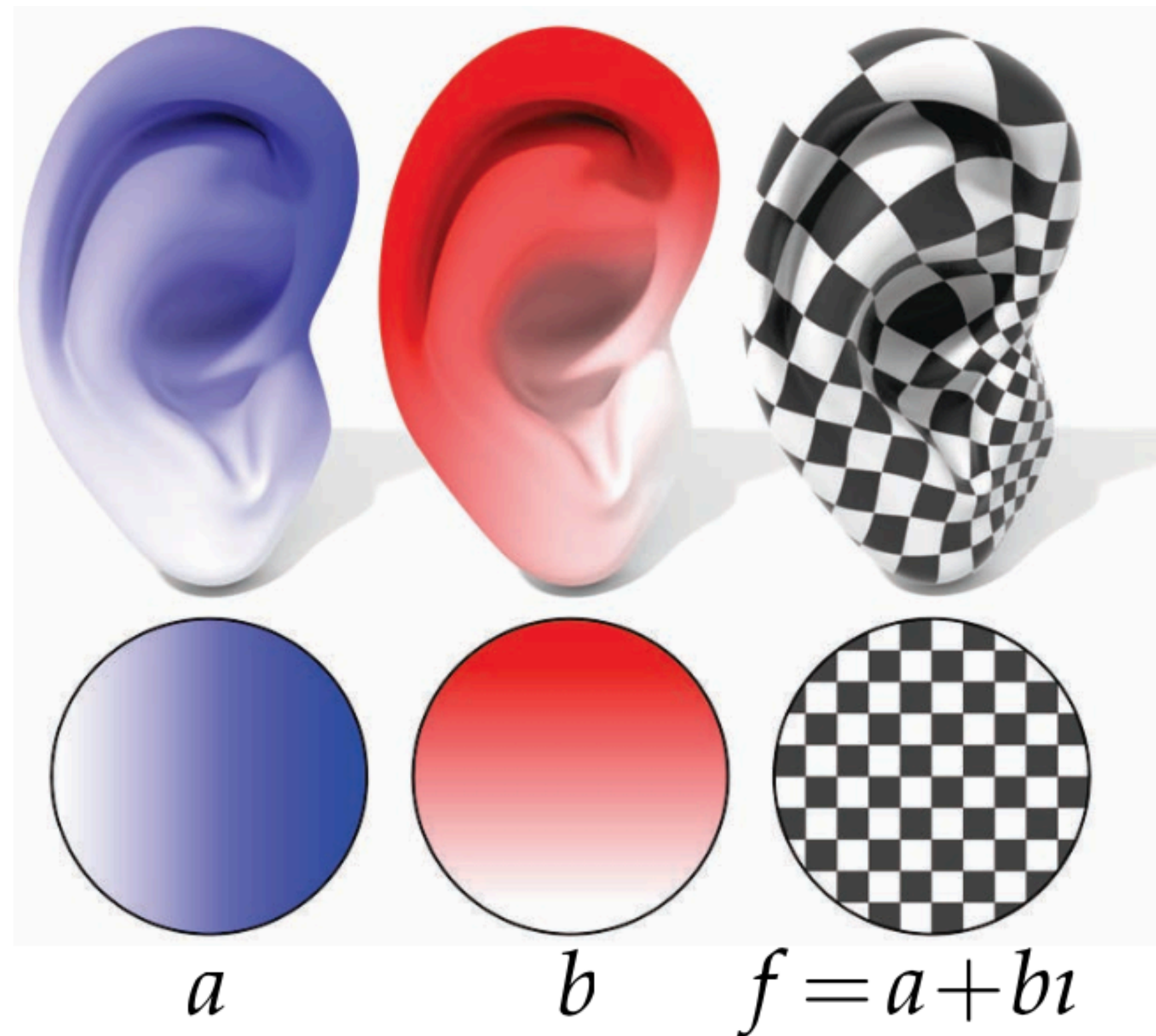
$$\Delta a = 0$$

$$\Delta b = 0$$

CONJUGATE HARMONIC PAIR

Conjugate Harmonic Functions

How do we find the solution on the interior?



$$J \nabla a = \nabla b$$

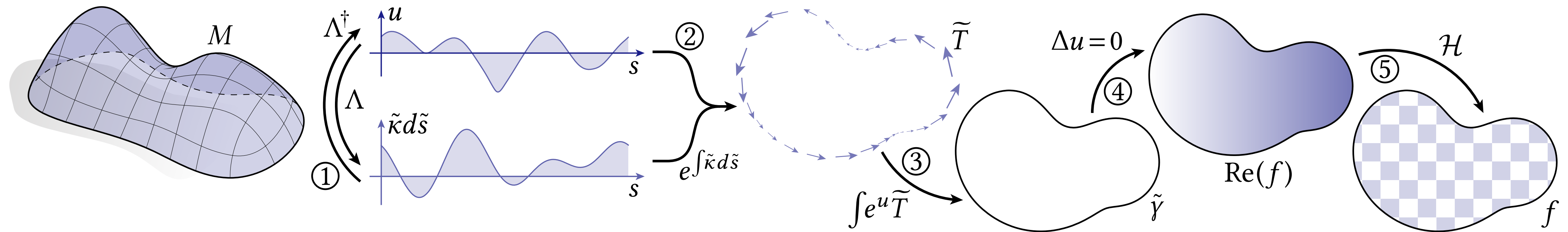
$$\Delta a = 0$$

$$\Delta b = 0$$

CONJUGATE HARMONIC PAIR

Fix a along the boundary and minimize conformal energy w.r.t. b (easy linear problem!)

Algorithm Outline



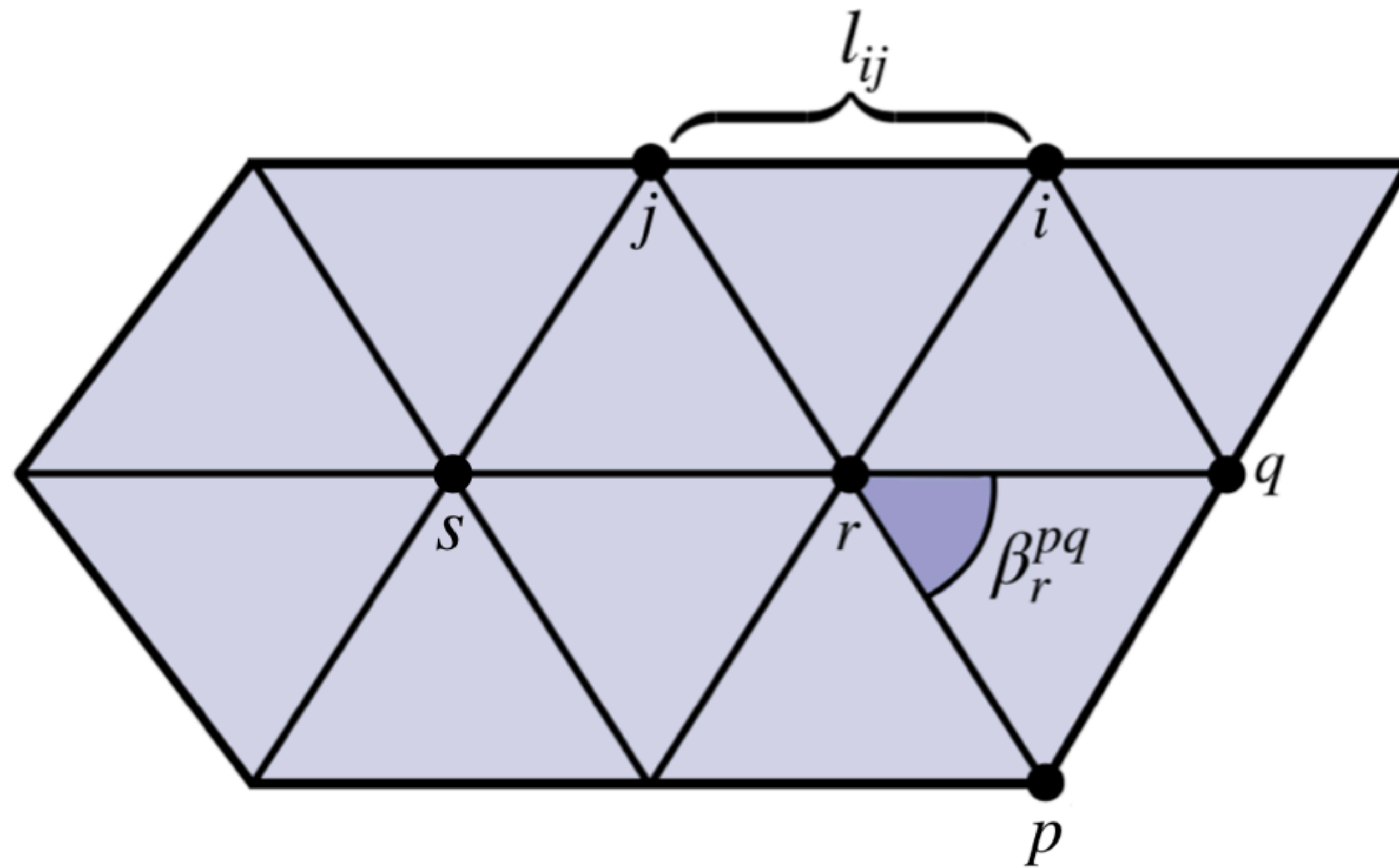
Given a surface with either scale or curvature of target boundary curve

1. Solve *Yamabe Problem* to get complementary data (curvature or scale)
2. Integrate boundary data to get boundary curve
3. Extend boundary curve to a pair of *conjugate harmonic functions*

DISCRETIZATION

Discretization

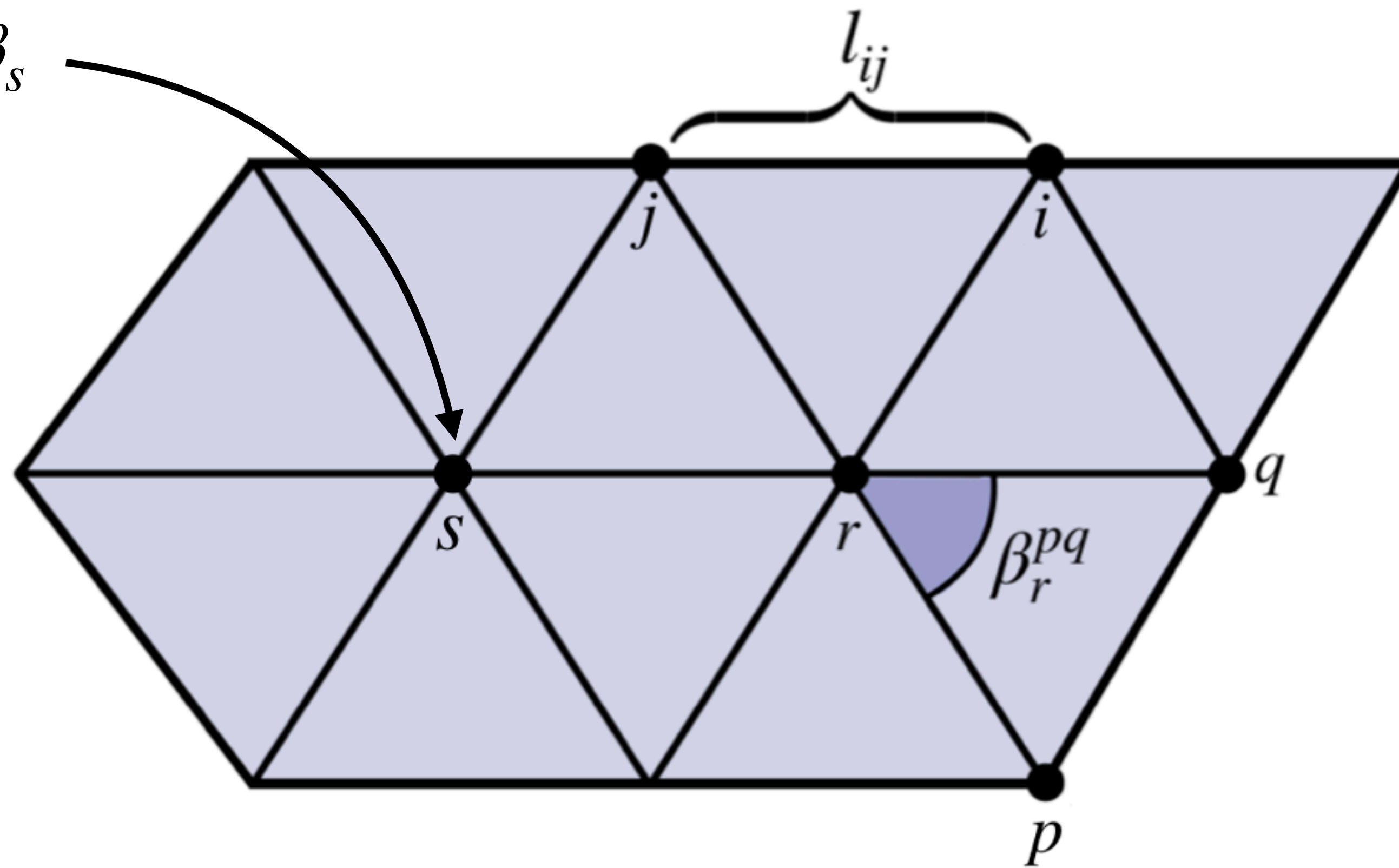
Discretize surface as a manifold triangle mesh with disk topology



Discretization

Discretize surface as a manifold triangle mesh with disk topology

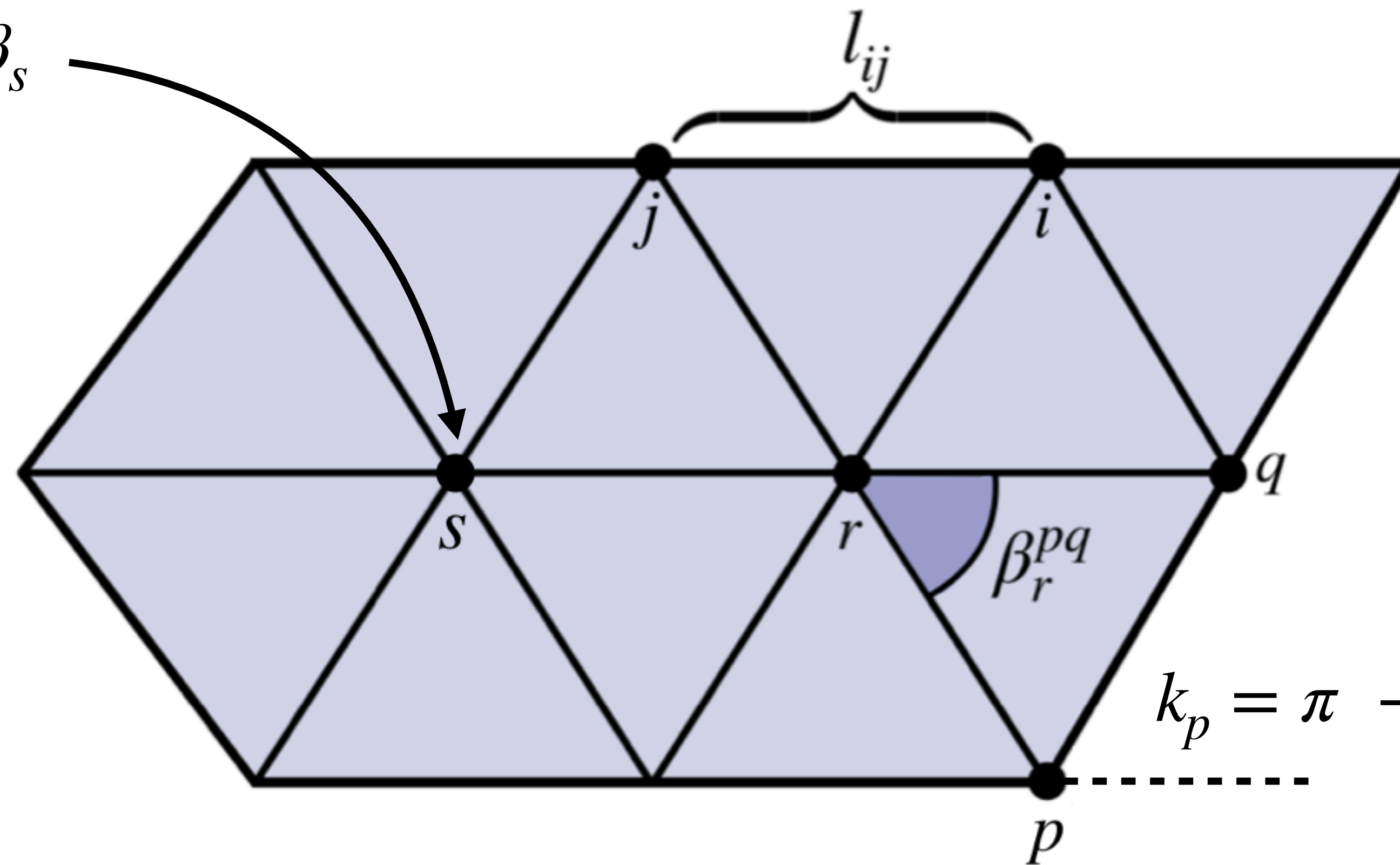
$$\Omega_s = 2\pi - \sum \beta_s$$



Discretization

Discretize surface as a manifold triangle mesh with disk topology

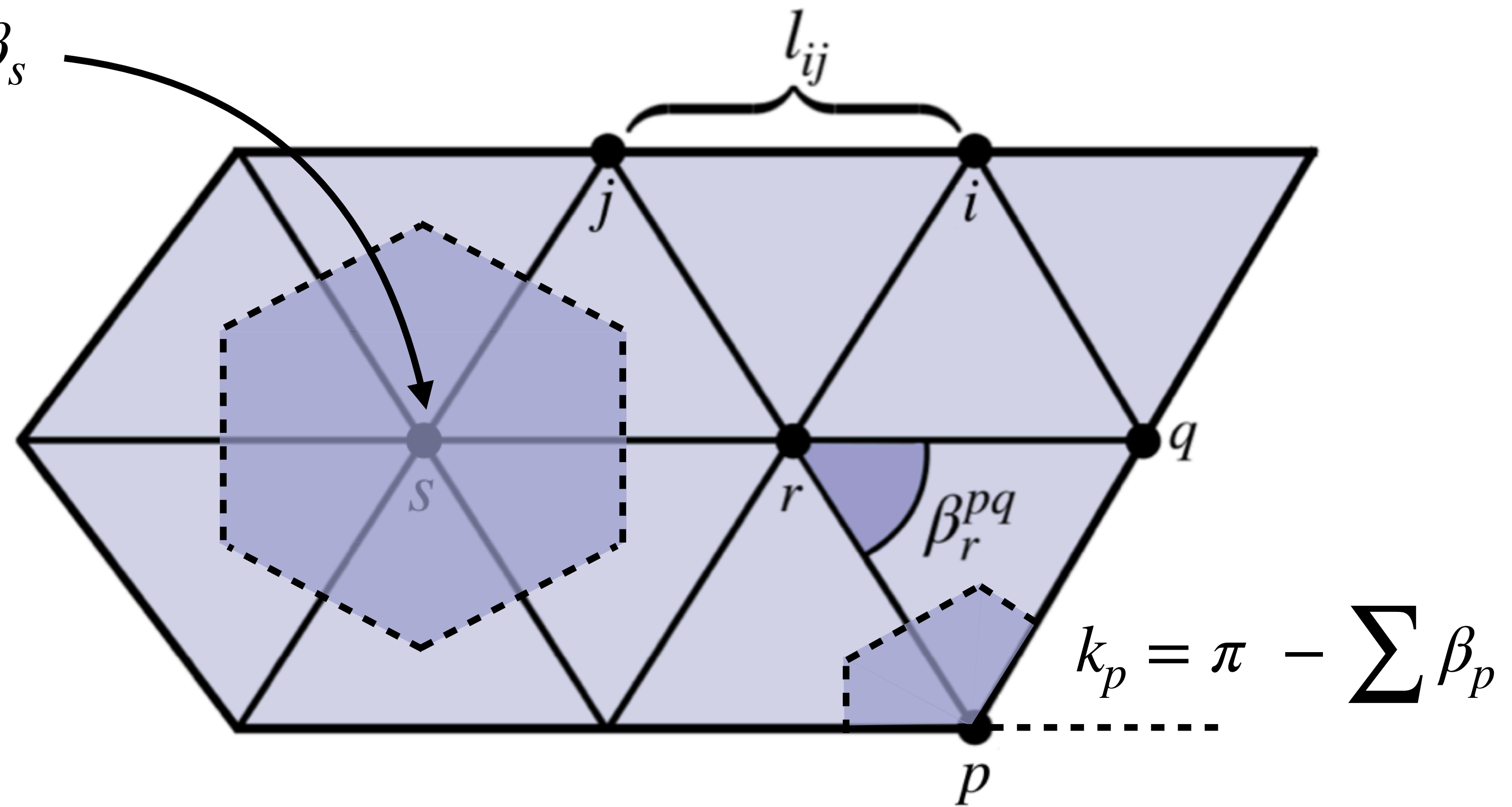
$$\Omega_s = 2\pi - \sum \beta_s$$



Discretization

Discretize surface as a manifold triangle mesh with disk topology

$$\Omega_s = 2\pi - \sum \beta_s$$



Discretizing the Yamabe Problem

Smooth *Yamabe Problem* is nonlinear

$$\Delta u = K - e^{2u}\tilde{K} \qquad \text{on } M$$

$$\frac{\partial u}{\partial n} = \kappa - e^u\tilde{\kappa} \qquad \text{on } \partial M$$

Discretizing the Yamabe Problem

Smooth *Yamabe Problem* is nonlinear

Integration over *dual volumes* yields linear relationships

$$\Delta u = K - e^{2u}\tilde{K}$$

$$Au = \Omega - \tilde{\Omega} \quad \text{on } M$$

integrating
 \Rightarrow

$$\frac{\partial u}{\partial n} = \kappa - e^u\tilde{\kappa}$$

$$h = k - \tilde{k} \quad \text{on } \partial M$$

Discretizing the Yamabe Problem

Smooth *Yamabe Problem* is nonlinear

Integration over *dual volumes* yields linear relationships

$$\Delta u = K - e^{2u} \tilde{K}$$

integrating
 \Rightarrow

$$\begin{array}{c} \uparrow \\ \text{cotan} \\ \text{Laplace matrix} \end{array} Au = \Omega - \tilde{\Omega} \quad \text{on } M$$

$$\frac{\partial u}{\partial n} = \kappa - e^u \tilde{\kappa}$$

$$h = k - \tilde{k} \quad \text{on } \partial M$$

Discretizing the Yamabe Problem

Smooth *Yamabe Problem* is nonlinear

Integration over *dual volumes* yields linear relationships

$$\Delta u = K - e^{2u} \tilde{K}$$

integrating
 \Rightarrow

$$\frac{\partial u}{\partial n} = \kappa - e^u \tilde{\kappa}$$

$$Au = \Omega - \tilde{\Omega} \quad \text{on } M$$

↑
cotan
Laplace matrix

↖ ↗
old new
angle defects angle defects

$$h = k - \tilde{k} \quad \text{on } \partial M$$

Discretizing the Yamabe Problem

Smooth *Yamabe Problem* is nonlinear

Integration over *dual volumes* yields linear relationships

$$\Delta u = K - e^{2u} \tilde{K}$$

integrating
 \Rightarrow

$$\frac{\partial u}{\partial n} = \kappa - e^u \tilde{\kappa}$$

$$\begin{array}{c} \begin{array}{c} \uparrow \\ \text{cotan} \\ \text{Laplace matrix} \end{array} Au = \begin{array}{c} \uparrow \\ \text{old} \\ \text{angle defects} \end{array} \Omega - \begin{array}{c} \uparrow \\ \text{new} \\ \text{angle defects} \end{array} \tilde{\Omega} \quad \text{on } M \end{array}$$
$$\begin{array}{c} \uparrow \\ \text{Neumann} \\ \text{boundary data} \end{array} h = k - \tilde{k} \quad \text{on } \partial M$$

Discretizing the Yamabe Problem

Smooth *Yamabe Problem* is nonlinear

Integration over *dual volumes* yields linear relationships

$$\Delta u = K - e^{2u} \tilde{K}$$

integrating
 \Rightarrow

$$\frac{\partial u}{\partial n} = \kappa - e^u \tilde{\kappa}$$

$$Au = \Omega - \tilde{\Omega} \quad \text{on } M$$

↑ ↖ ↗
cotan old new
Laplace matrix angle defects angle defects

$$h = k - \tilde{k} \quad \text{on } \partial M$$

↑ ↖ ↗
Neumann old new
boundary data exterior angles exterior angles

Discretizing the Yamabe Problem

Smooth *Yamabe Problem* is nonlinear

Integration over *dual volumes* yields linear relationships

$$\Delta u = K - e^{2u} \tilde{K}$$

integrating
 \Rightarrow

$$\frac{\partial u}{\partial n} = \kappa - e^u \tilde{\kappa}$$

$Au = \Omega - \tilde{\Omega}$ *on* M

\uparrow \uparrow \uparrow

cotan Ω $\tilde{\Omega}$

Laplace matrix angle defects angle defects

$h = k - \tilde{k}$ *on* ∂M

\uparrow \uparrow \uparrow

Neumann k \tilde{k}

boundary data exterior angles exterior angles

Discretizing the Yamabe Problem

Smooth *Yamabe Problem* is nonlinear

Integration over *dual volumes* yields linear relationships

$$\Delta u = K - e^{2u} \tilde{K}$$

integrating
 \Rightarrow

$$\frac{\partial u}{\partial n} = \kappa - e^u \tilde{\kappa}$$

Can prescribe either exterior angles or scaling,
but not both!

$$Au = \Omega - \tilde{\Omega} \quad \text{on } M$$

↑ cotan Laplace matrix old angle defects new angle defects

$$h = k - \tilde{k} \quad \text{on } \partial M$$

↑ Neumann boundary data old exterior angles new exterior angles

Poincaré Steklov Operators

How do we switch between angles and scale factors?

$$Au = \Omega \qquad \text{on } M$$

$$h = k - \tilde{k} \qquad \text{on } \partial M$$

Poincaré Steklov Operators

How do we switch between angles and scale factors?

Rewrite integrated *Yamabe Problem* in block matrix form

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} \begin{bmatrix} u_I \\ u_B \end{bmatrix} = \begin{bmatrix} \Omega \\ -(k - \tilde{k}) \end{bmatrix}$$

Poincaré Steklov Operators

How do we switch between angles and scale factors?

Rewrite integrated *Yamabe Problem* in block matrix form

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} \begin{bmatrix} u_I \\ u_B \end{bmatrix} = \begin{bmatrix} \Omega \\ -(k - \tilde{k}) \end{bmatrix}$$

NEUMANN TO DIRICHLET MAP

DIRICHLET TO NEUMANN MAP

Poincaré Steklov Operators

How do we switch between angles and scale factors?

Rewrite integrated *Yamabe Problem* in block matrix form

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} \begin{bmatrix} u_I \\ u_B \end{bmatrix} = \begin{bmatrix} \Omega \\ -(k - \tilde{k}) \end{bmatrix}$$

NEUMANN TO DIRICHLET MAP

DIRICHLET TO NEUMANN MAP

Given \tilde{k}

Poincaré Steklov Operators

How do we switch between angles and scale factors?

Rewrite integrated *Yamabe Problem* in block matrix form

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} \begin{bmatrix} u_I \\ u_B \end{bmatrix} = \begin{bmatrix} \Omega \\ -(k - \tilde{k}) \end{bmatrix}$$

NEUMANN TO DIRICHLET MAP

DIRICHLET TO NEUMANN MAP

Given \tilde{k}

Solve Neumann system above for u

Poincaré Steklov Operators

How do we switch between angles and scale factors?

Rewrite integrated *Yamabe Problem* in block matrix form

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} \begin{bmatrix} u_I \\ u_B \end{bmatrix} = \begin{bmatrix} \Omega \\ -(k - \tilde{k}) \end{bmatrix}$$

NEUMANN TO DIRICHLET MAP

DIRICHLET TO NEUMANN MAP

Given \tilde{k}

Solve Neumann system above for u

Read off u_B

Poincaré Steklov Operators

How do we switch between angles and scale factors?

Rewrite integrated *Yamabe Problem* in block matrix form

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} \begin{bmatrix} u_I \\ u_B \end{bmatrix} = \begin{bmatrix} \Omega \\ -(k - \tilde{k}) \end{bmatrix}$$

NEUMANN TO DIRICHLET MAP

Given \tilde{k}

Solve Neumann system above for u

Read off u_B

DIRICHLET TO NEUMANN MAP

Given u_B

Poincaré Steklov Operators

How do we switch between angles and scale factors?

Rewrite integrated *Yamabe Problem* in block matrix form

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} \begin{bmatrix} u_I \\ u_B \end{bmatrix} = \begin{bmatrix} \Omega \\ -(k - \tilde{k}) \end{bmatrix}$$

NEUMANN TO DIRICHLET MAP

Given \tilde{k}

Solve Neumann system above for u

Read off u_B

DIRICHLET TO NEUMANN MAP

Given u_B

Solve Dirichlet Problem $A_{II}u_I = \Omega - A_{IB}u_B$ for u_I

Poincaré Steklov Operators

How do we switch between angles and scale factors?

Rewrite integrated *Yamabe Problem* in block matrix form

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} \begin{bmatrix} u_I \\ u_B \end{bmatrix} = \begin{bmatrix} \Omega \\ -(k - \tilde{k}) \end{bmatrix}$$

NEUMANN TO DIRICHLET MAP

Given \tilde{k}

Solve Neumann system above for u

Read off u_B

DIRICHLET TO NEUMANN MAP

Given u_B

Solve Dirichlet Problem $A_{II}u_I = \Omega - A_{IB}u_B$ for u_I

$$\tilde{k} = k + A_{IB}^T u_I + A_{BB} u_B$$

Poincaré Steklov Operators

How do we switch between angles and scale factors?

Rewrite integrated *Yamabe Problem* in block matrix form

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} \begin{bmatrix} u_I \\ u_B \end{bmatrix} = \begin{bmatrix} \Omega \\ -(k - \tilde{k}) \end{bmatrix}$$

NEUMANN TO DIRICHLET MAP

Given \tilde{k}

Solve Neumann system above for u

Read off u_B

DIRICHLET TO NEUMANN MAP

Given u_B

Solve Dirichlet Problem $A_{II}u_I = \Omega - A_{IB}u_B$ for u_I

$$\tilde{k} = k + A_{IB}^T u_I + A_{BB} u_B$$

Angles exactly sum to 2π !

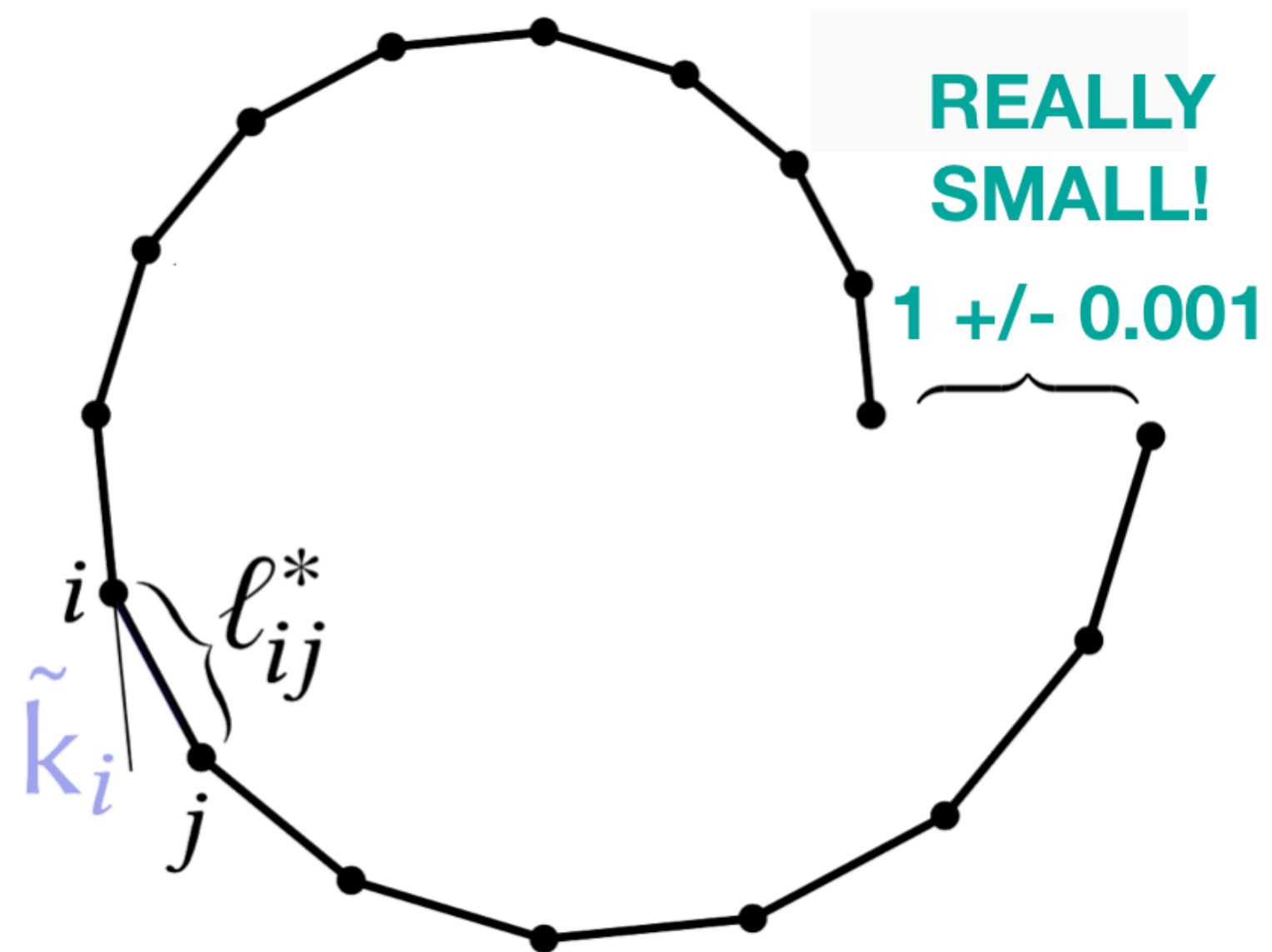
Curve Integration

Rescale boundary edge lengths using scale factors u

Curve Integration

Rescale boundary edge lengths using scale factors u

Extremely small discretization errors prevent curve from closing

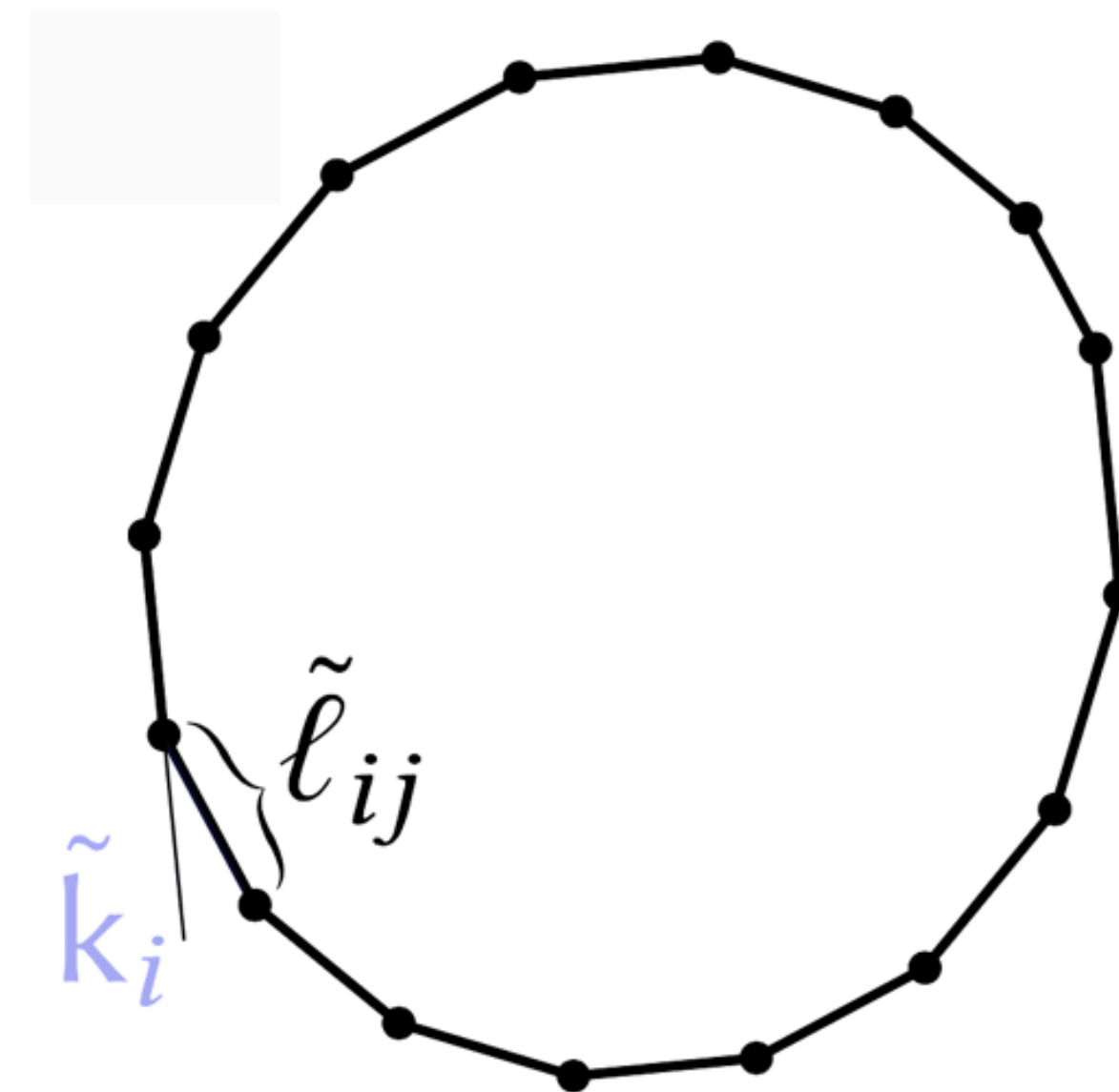
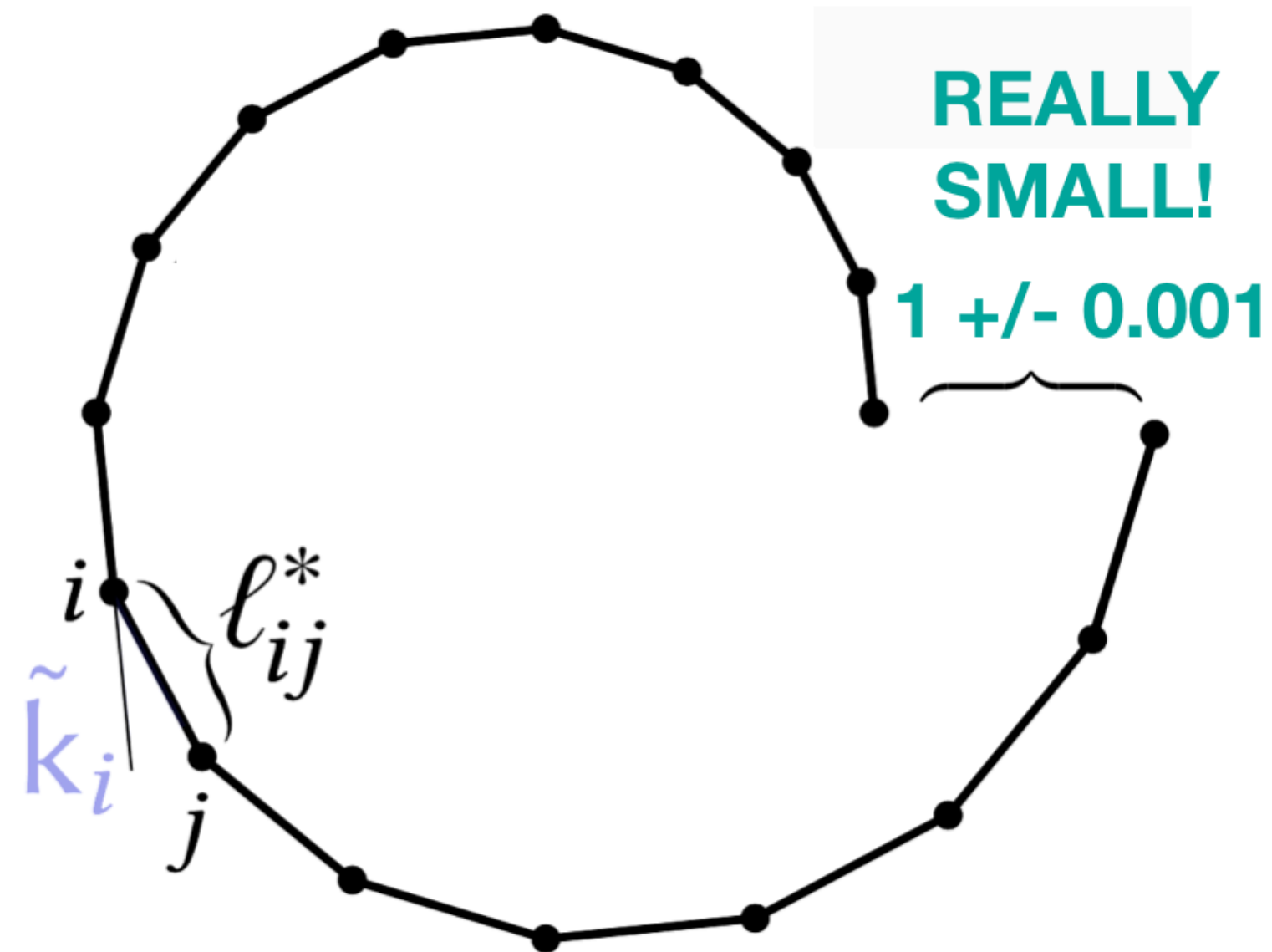


Curve Integration

Rescale boundary edge lengths using scale factors u

Extremely small discretization errors prevent curve from closing

Formulate small least squares problem to adjust only lengths to close curve



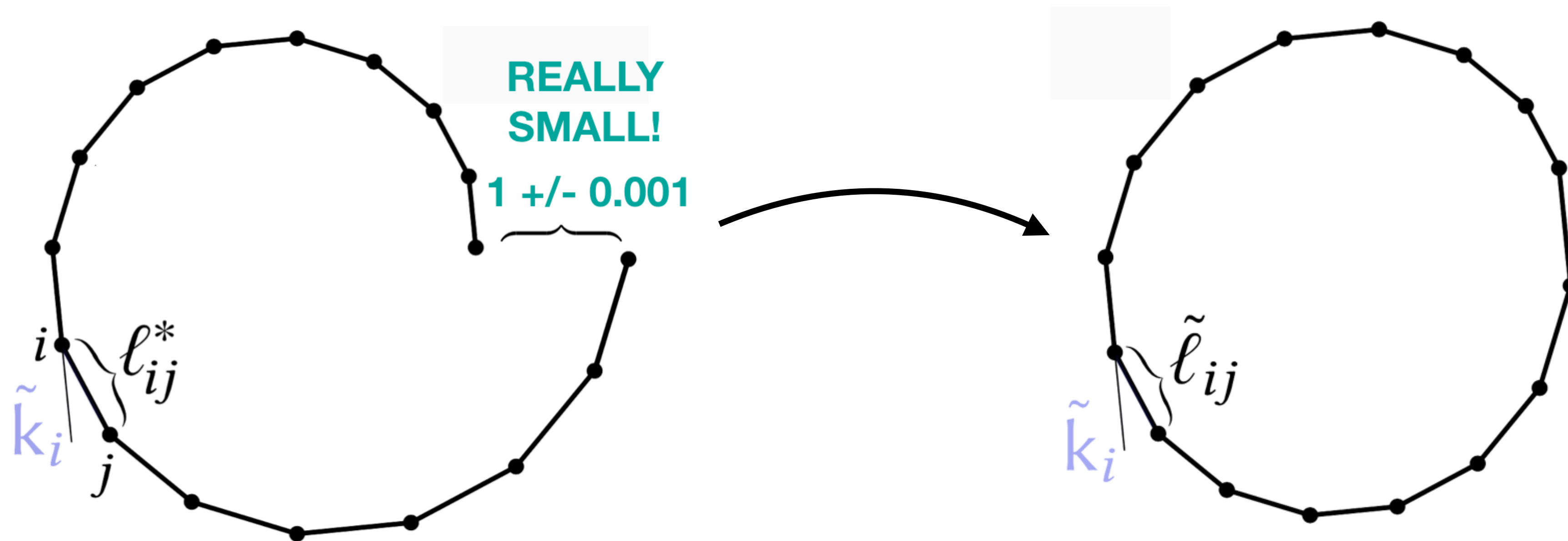
Curve Integration

Rescale boundary edge lengths using scale factors u

Extremely small discretization errors prevent curve from closing

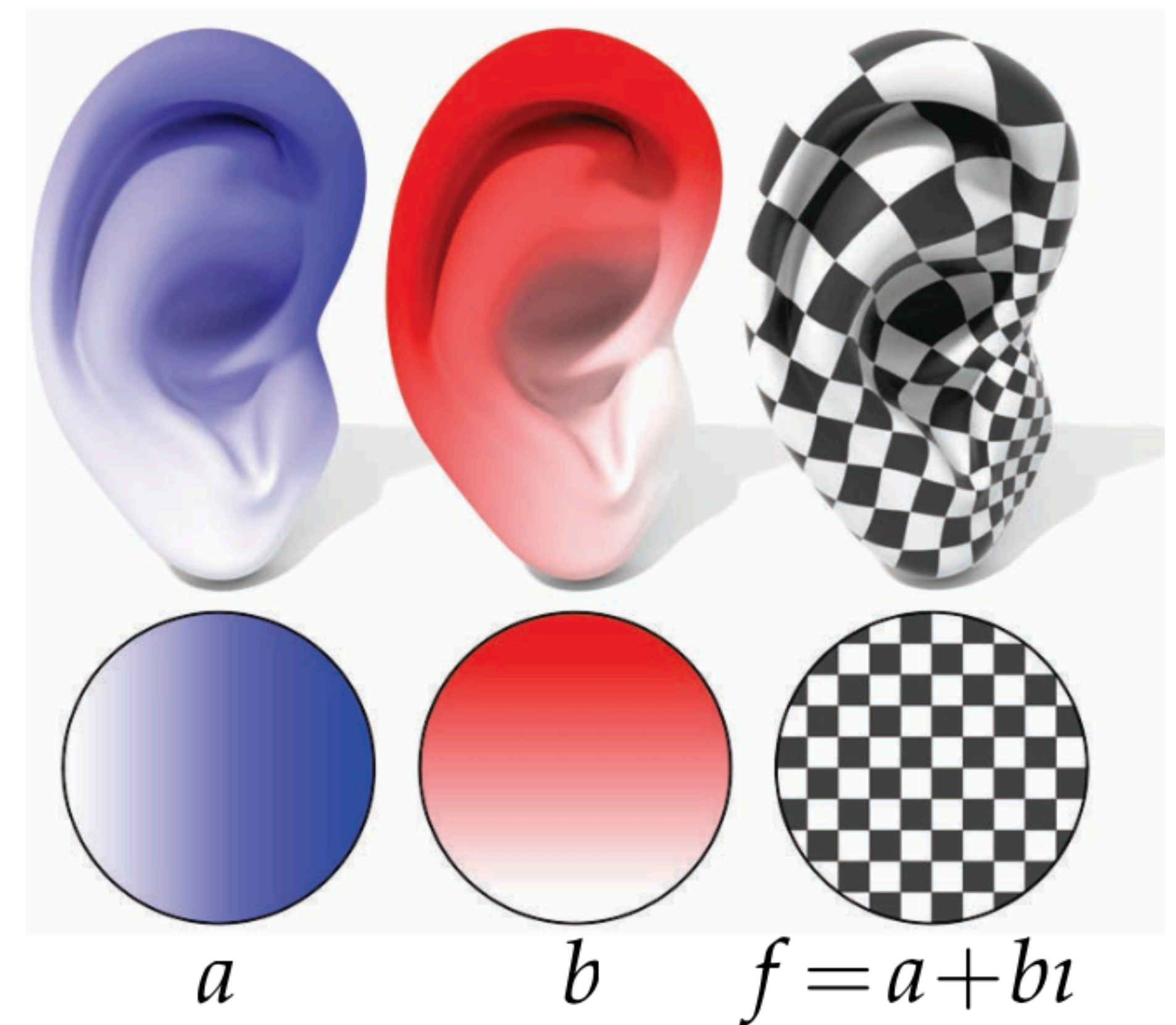
Formulate small least squares problem to adjust only lengths to close curve

Exterior angles are exactly preserved



Harmonic Extension and Conjugation

Basic Idea: Fix one coordinate of $\tilde{\gamma}$, minimize discrete conformal energy w.r.t. other coordinate

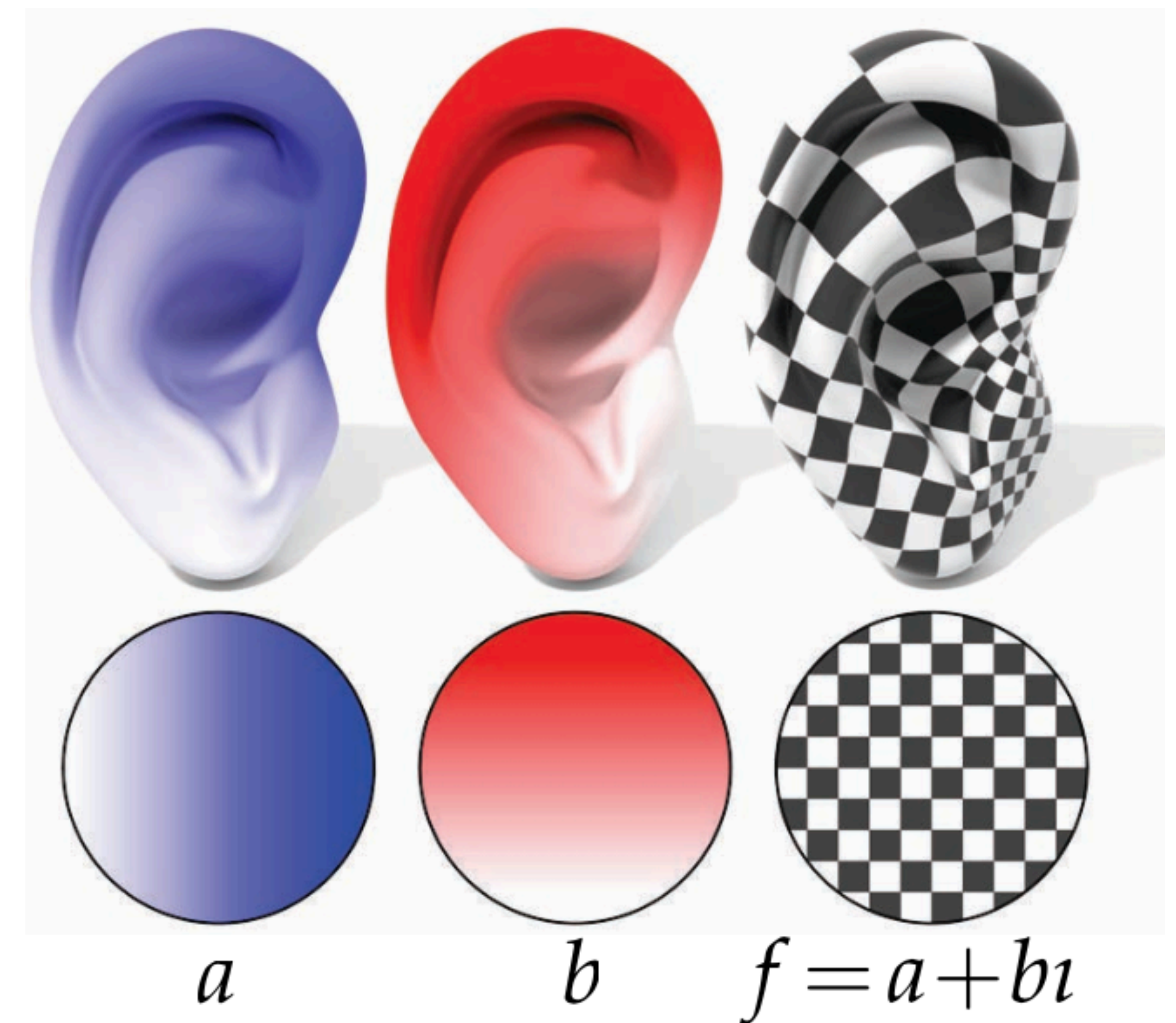


Harmonic Extension and Conjugation

Basic Idea: Fix one coordinate of $\tilde{\gamma}$, minimize discrete conformal energy w.r.t. other coordinate

$$\Delta a = 0 \text{ s.t. } a|_{\partial M} = \text{Re}(\tilde{\gamma})$$

$$\Delta b = 0 \text{ s.t. } \frac{\partial b}{\partial n} = H a$$

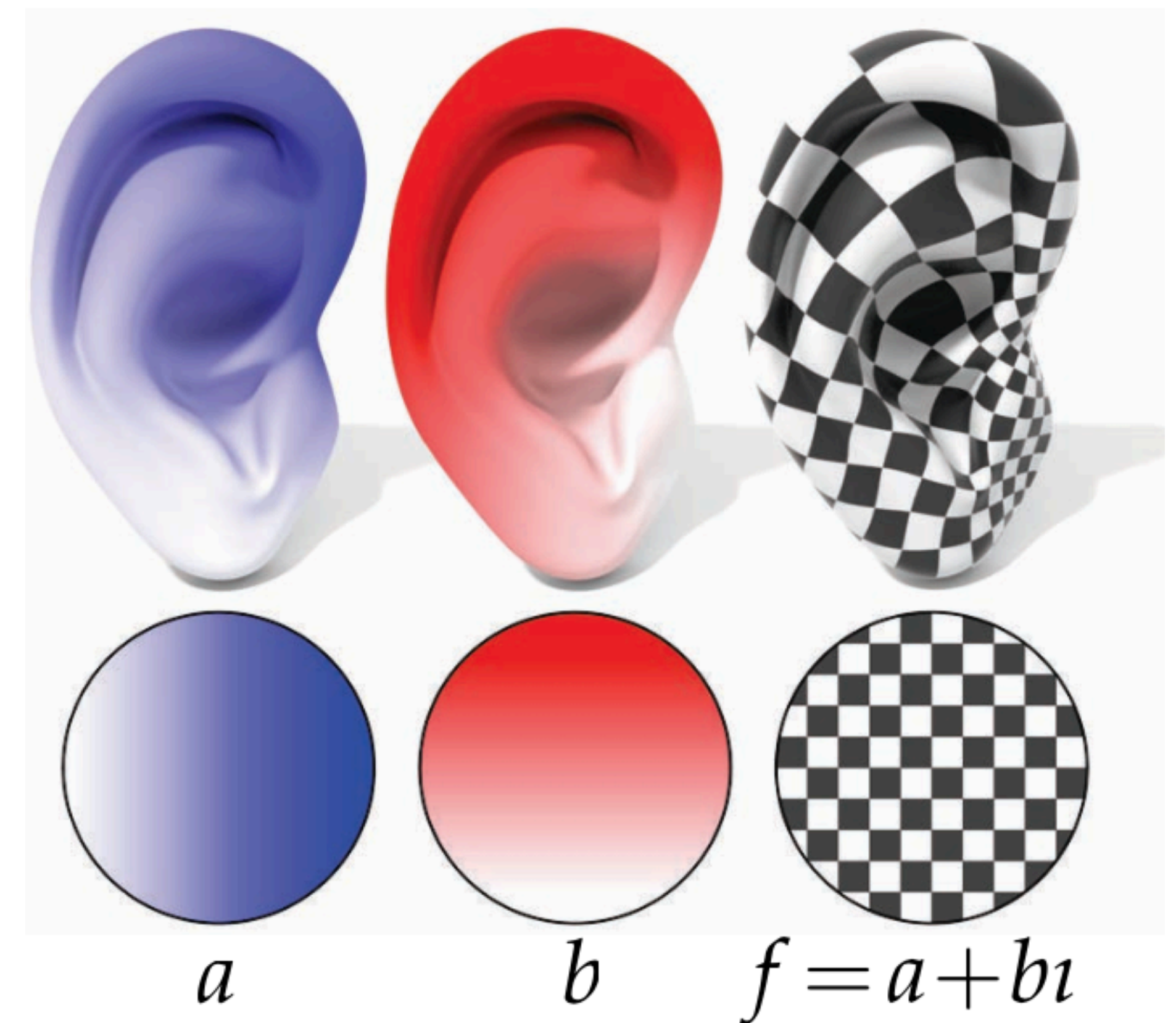


Harmonic Extension and Conjugation

Basic Idea: Fix one coordinate of $\tilde{\gamma}$, minimize discrete conformal energy w.r.t. other coordinate

$$\Delta a = 0 \text{ s.t. } a|_{\partial M} = \text{Re}(\tilde{\gamma})$$

$$\Delta b = 0 \text{ s.t. } \frac{\partial b}{\partial n} = \underset{\substack{\uparrow \\ \text{Hilbert Transform}}}{Ha}$$



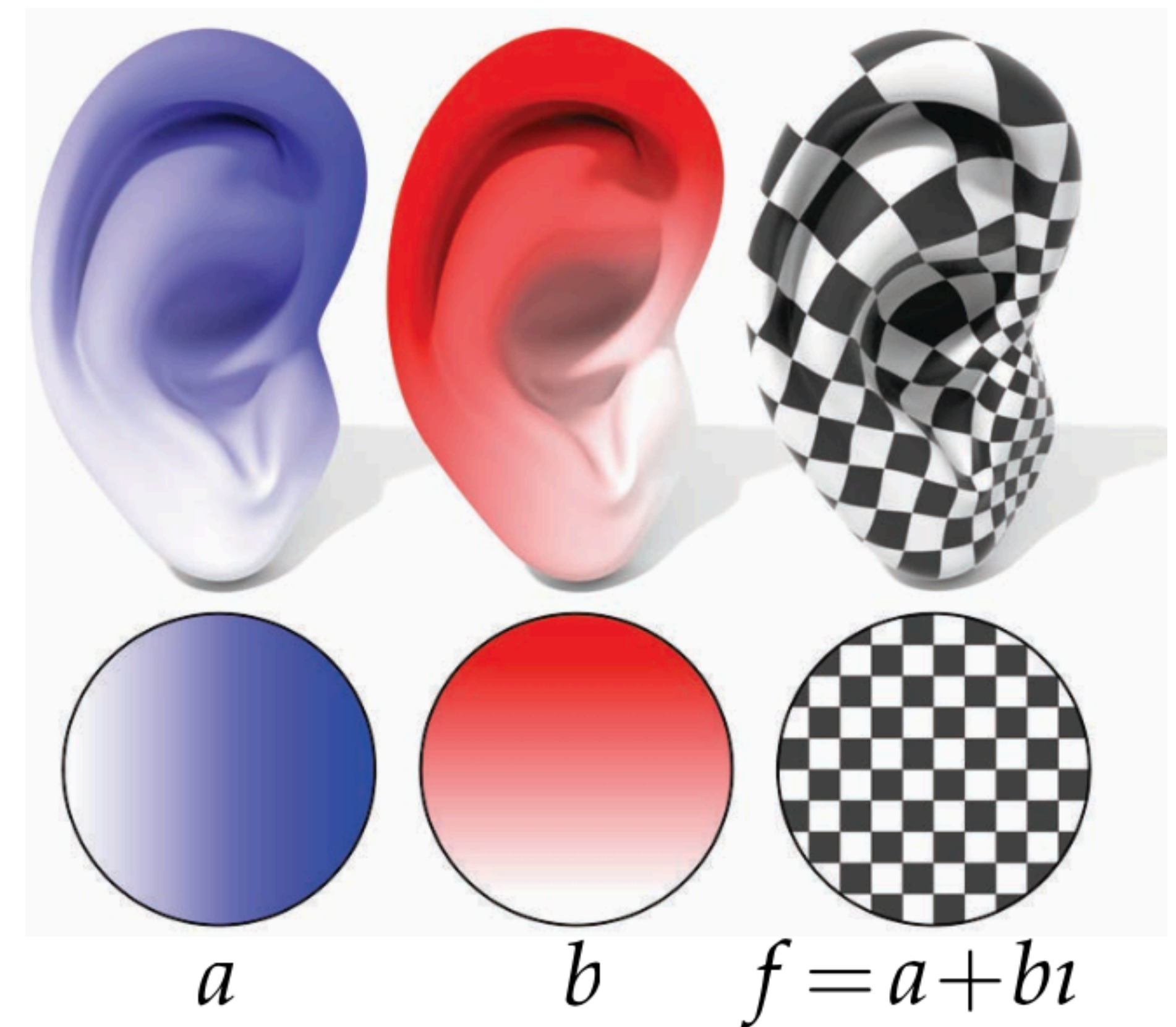
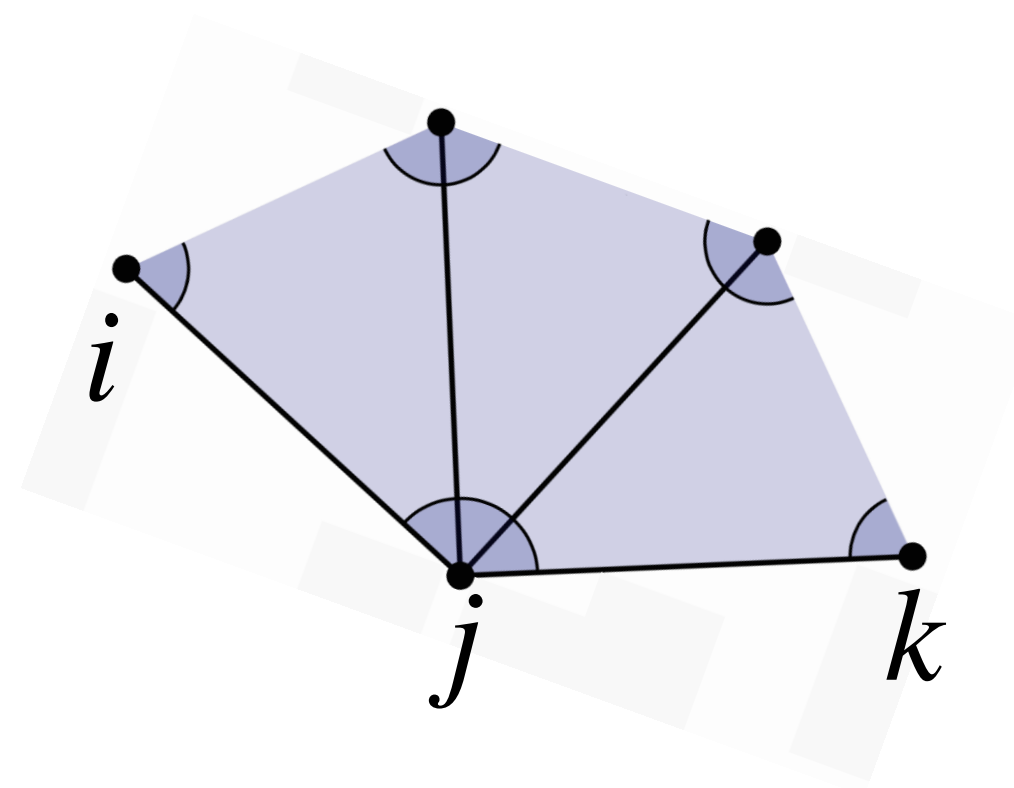
Harmonic Extension and Conjugation

Basic Idea: Fix one coordinate of $\tilde{\gamma}$, minimize discrete conformal energy w.r.t. other coordinate

$$\Delta a = 0 \text{ s.t. } a|_{\partial M} = \text{Re}(\tilde{\gamma})$$

$$\Delta b = 0 \text{ s.t. } \frac{\partial b}{\partial n} = \underset{\substack{\uparrow \\ \text{Hilbert Transform}}}{Ha}$$

$$h_j = \frac{1}{2}(a_k - a_i)$$



Harmonic Extension and Conjugation

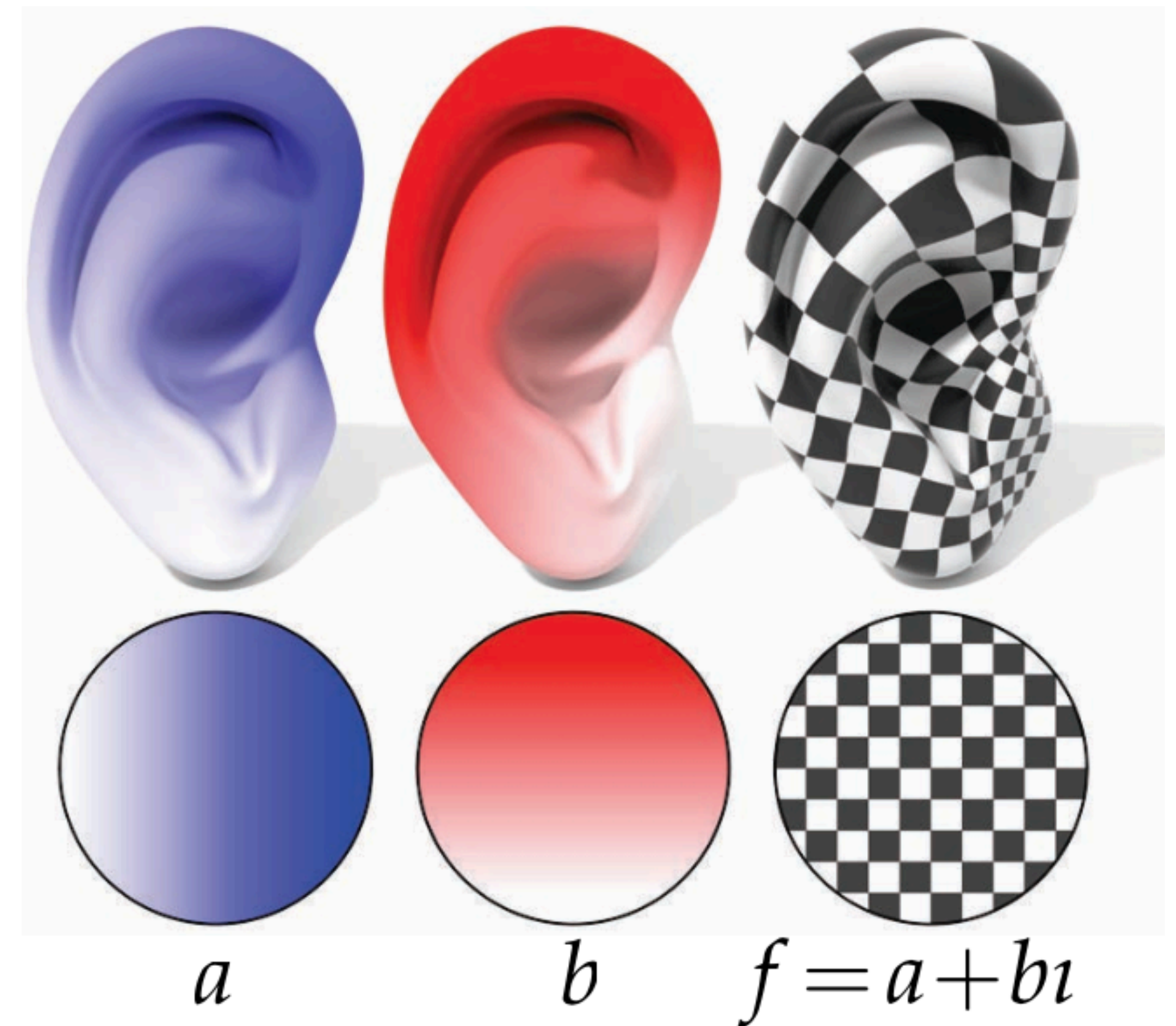
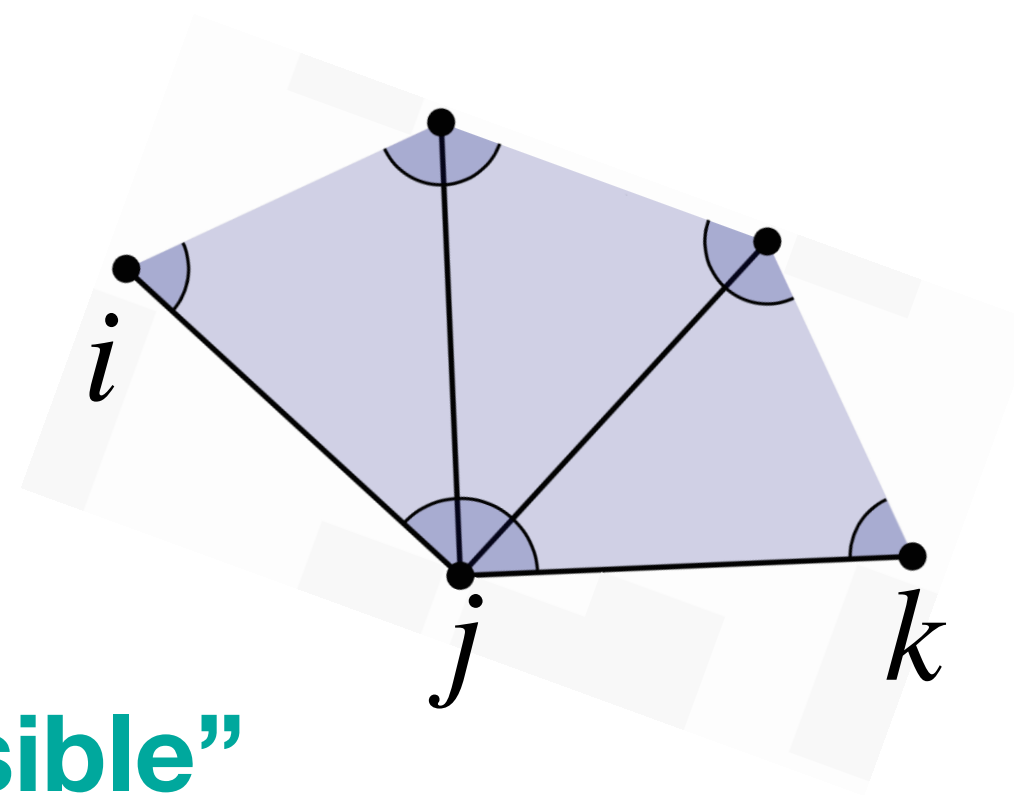
Basic Idea: Fix one coordinate of $\tilde{\gamma}$, minimize discrete conformal energy w.r.t. other coordinate

$$\Delta a = 0 \text{ s.t. } a|_{\partial M} = \text{Re}(\tilde{\gamma})$$

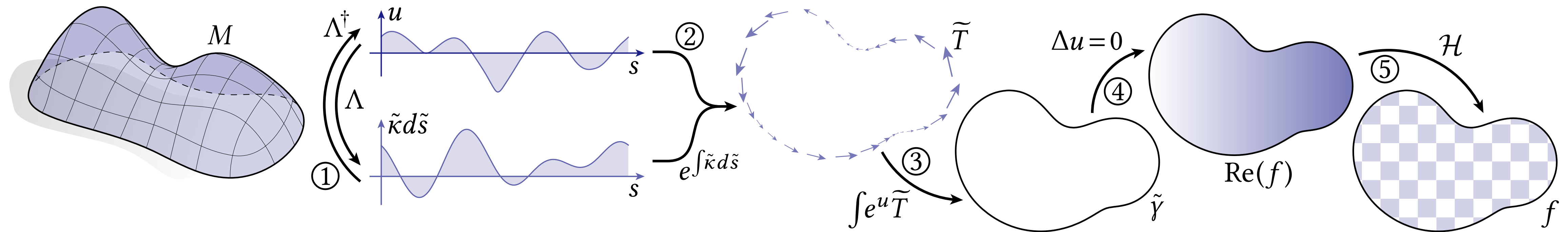
$$\Delta b = 0 \text{ s.t. } \frac{\partial b}{\partial n} = \underset{\substack{\uparrow \\ \text{Hilbert Transform}}}{Ha}$$

$$h_j = \frac{1}{2}(a_k - a_i)$$

“as conjugate as possible”



Algorithm Outline



Given a surface with either scale or curvature of target boundary curve

1. Solve *Yamabe Problem* to get complementary data (curvature or scale)
2. Integrate boundary data to get boundary curve
3. Extend boundary curve to a pair of *conjugate harmonic functions*

APPLICATIONS

Automatic Flattening

User does not have to specify boundary curve: automatically pick flattening with minimal scale distortion

Automatic Flattening

User does not have to specify boundary curve: automatically pick flattening with minimal scale distortion

Theorem. [Springborn, Schröder, Pinkall] *Let (M, g) be a surface with boundary. Then among all conformally equivalent flat metrics $\tilde{g} = e^{2u}g$, the ones with least area distortion are obtained if $u|_{\partial M} = \text{const.}$*

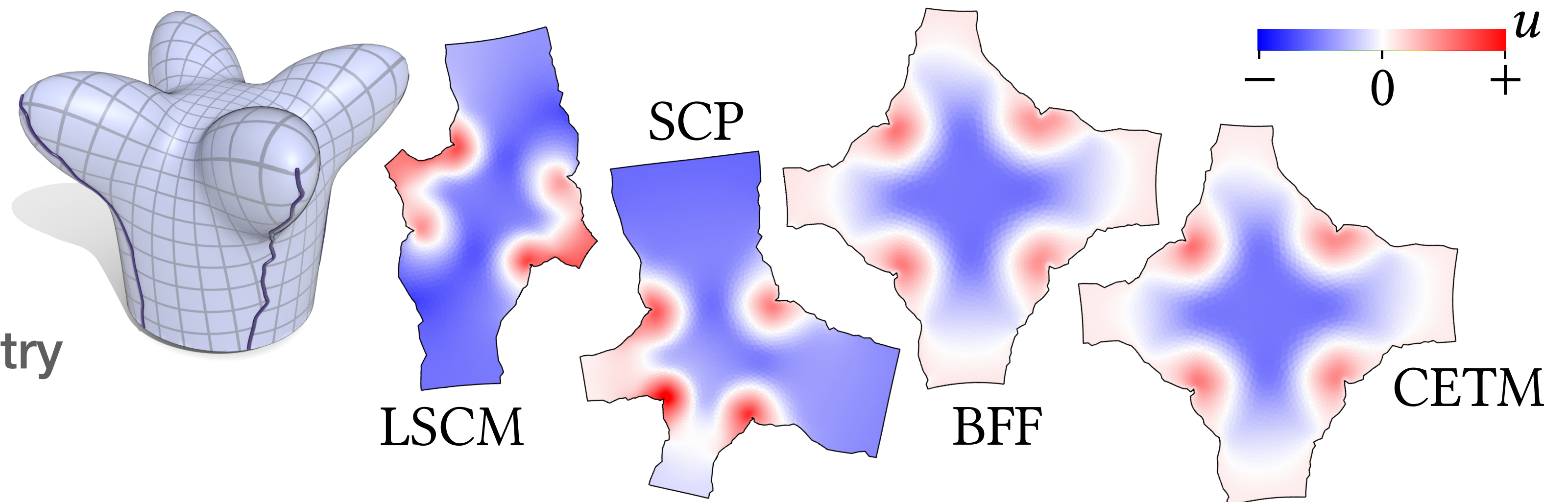
Automatic Flattening

User does not have to specify boundary curve: automatically pick flattening with minimal scale distortion

Theorem. [Springborn, Schröder, Pinkall] *Let (M, g) be a surface with boundary. Then among all conformally equivalent flat metrics $\tilde{g} = e^{2u}g$, the ones with least area distortion are obtained if $u|_{\partial M} = \text{const.}$*

Results indistinguishable from CETM

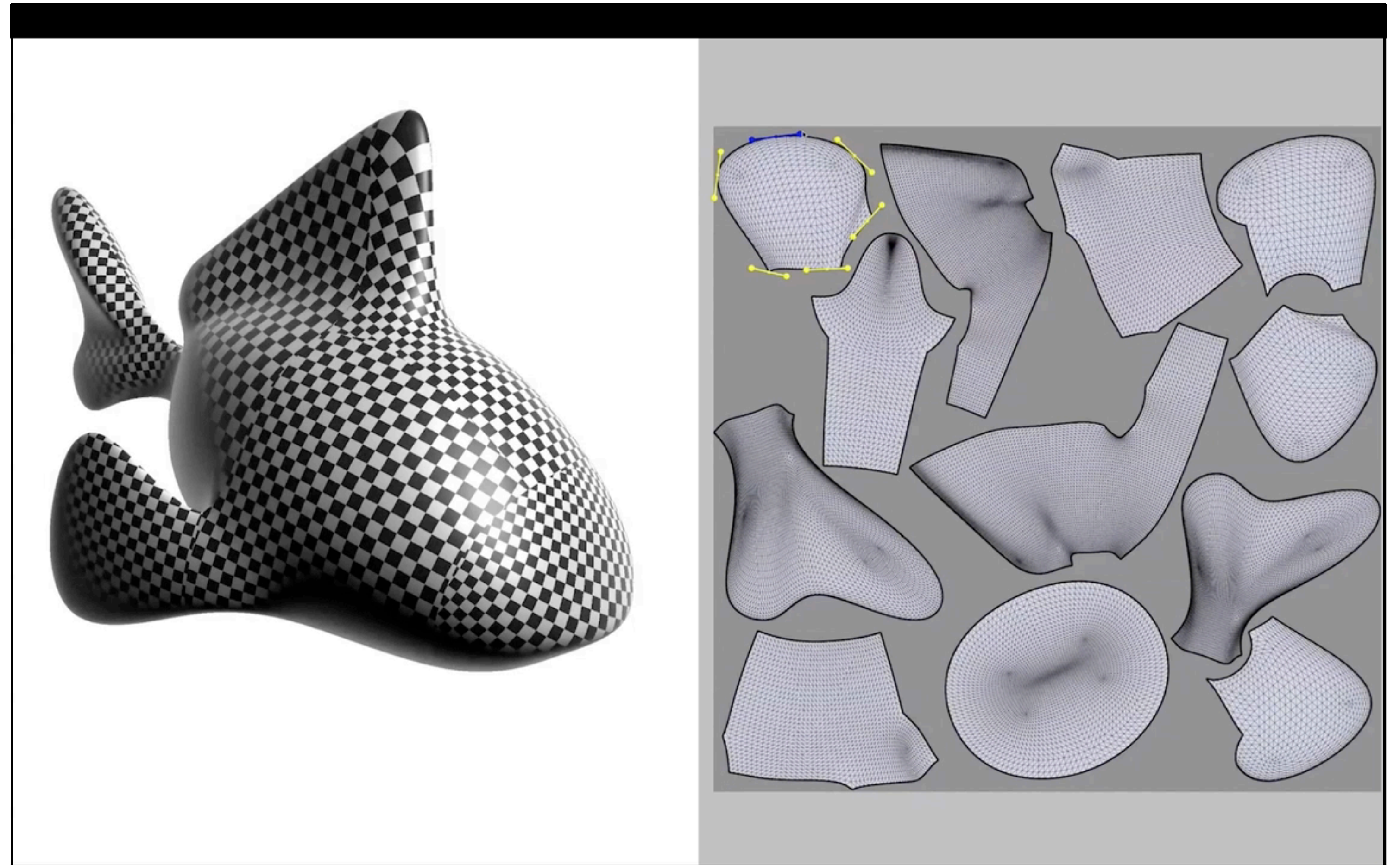
Better preservation of symmetry compared to LSCM and SCP



Direct Editing

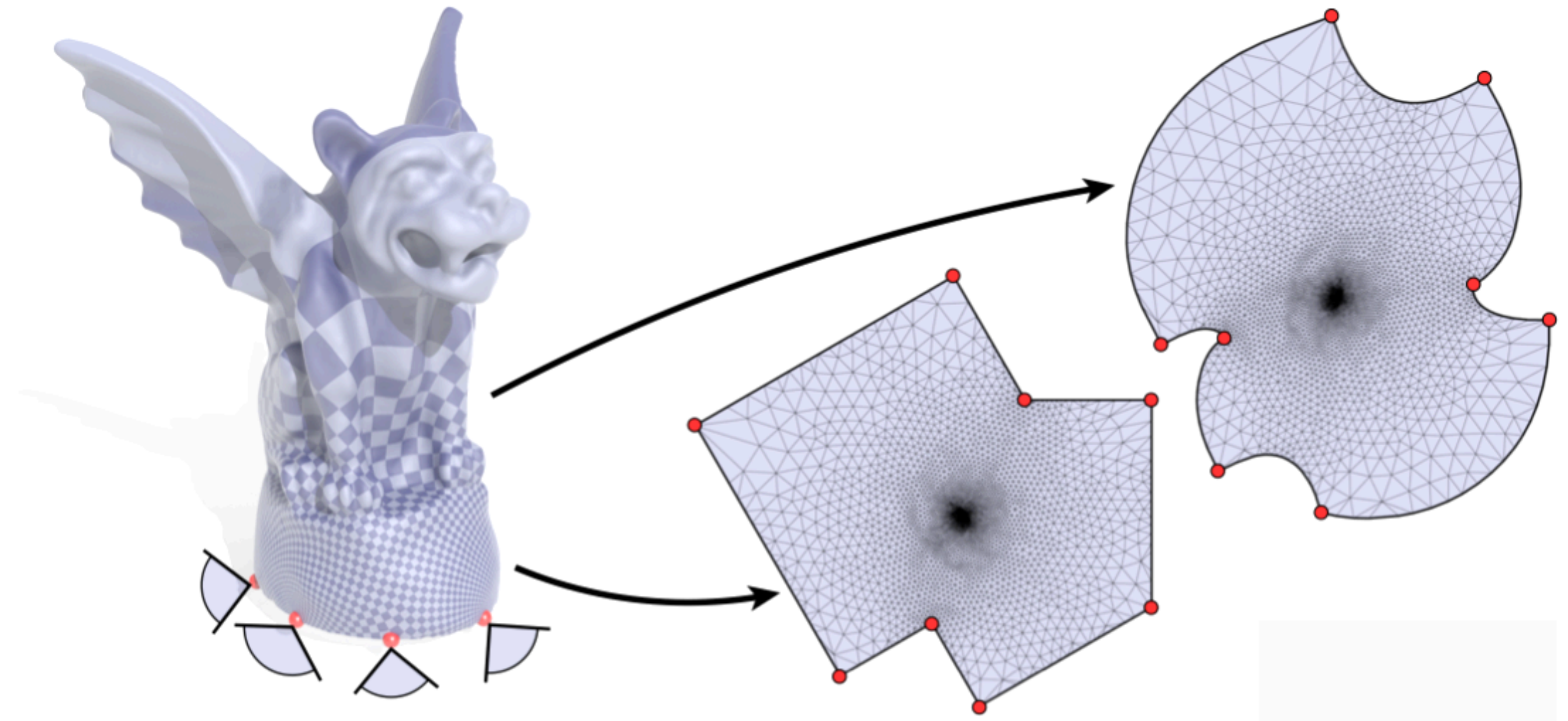
Spline based curve editor
to manipulate target angles
and lengths

Interactively and nonrigidly
tweak a texture layout
while remaining conformal



Exact Preservation of Sharp Corners

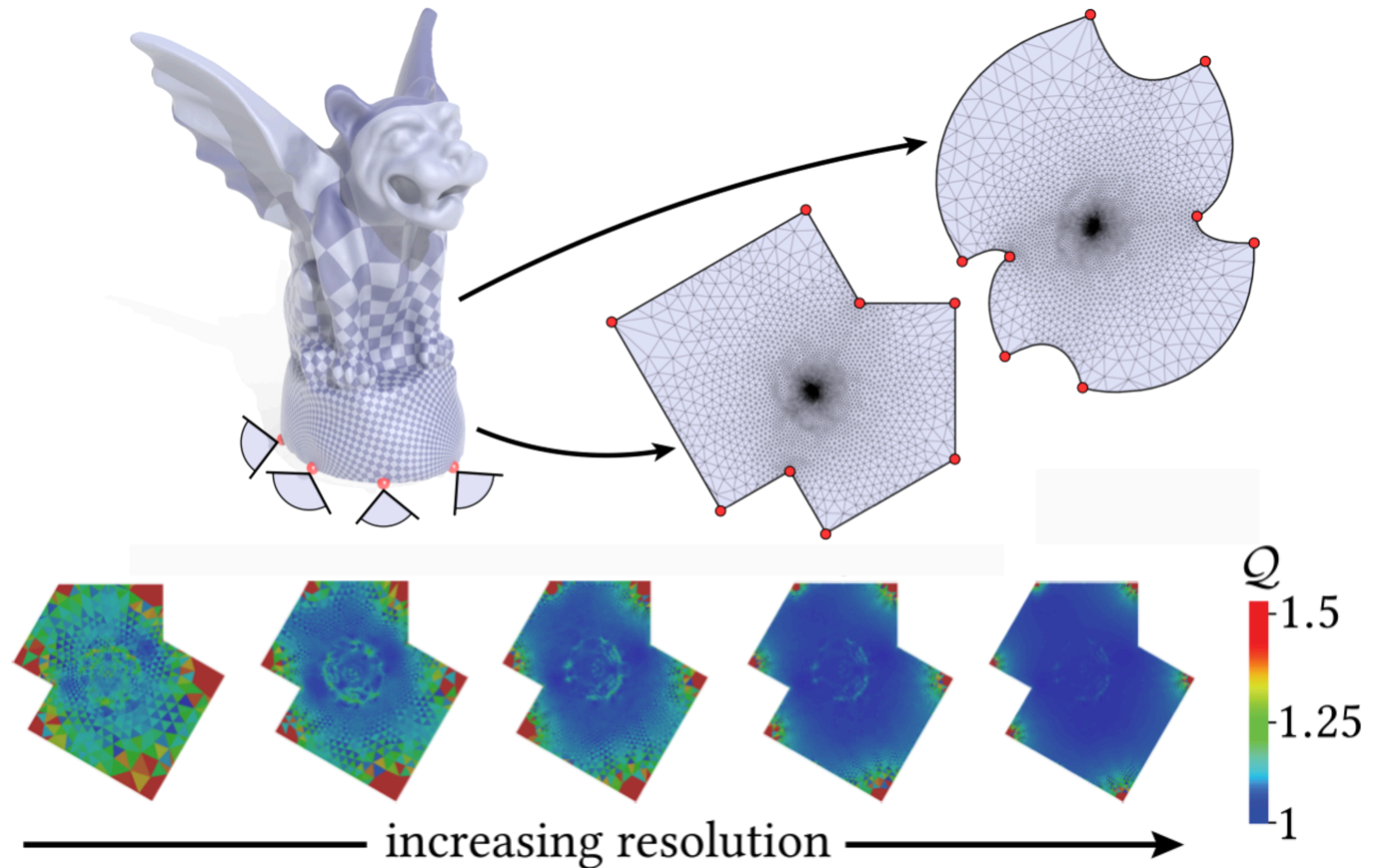
Harmonically extend both coordinates of $\tilde{\gamma}$ to exactly interpolate angles



Exact Preservation of Sharp Corners

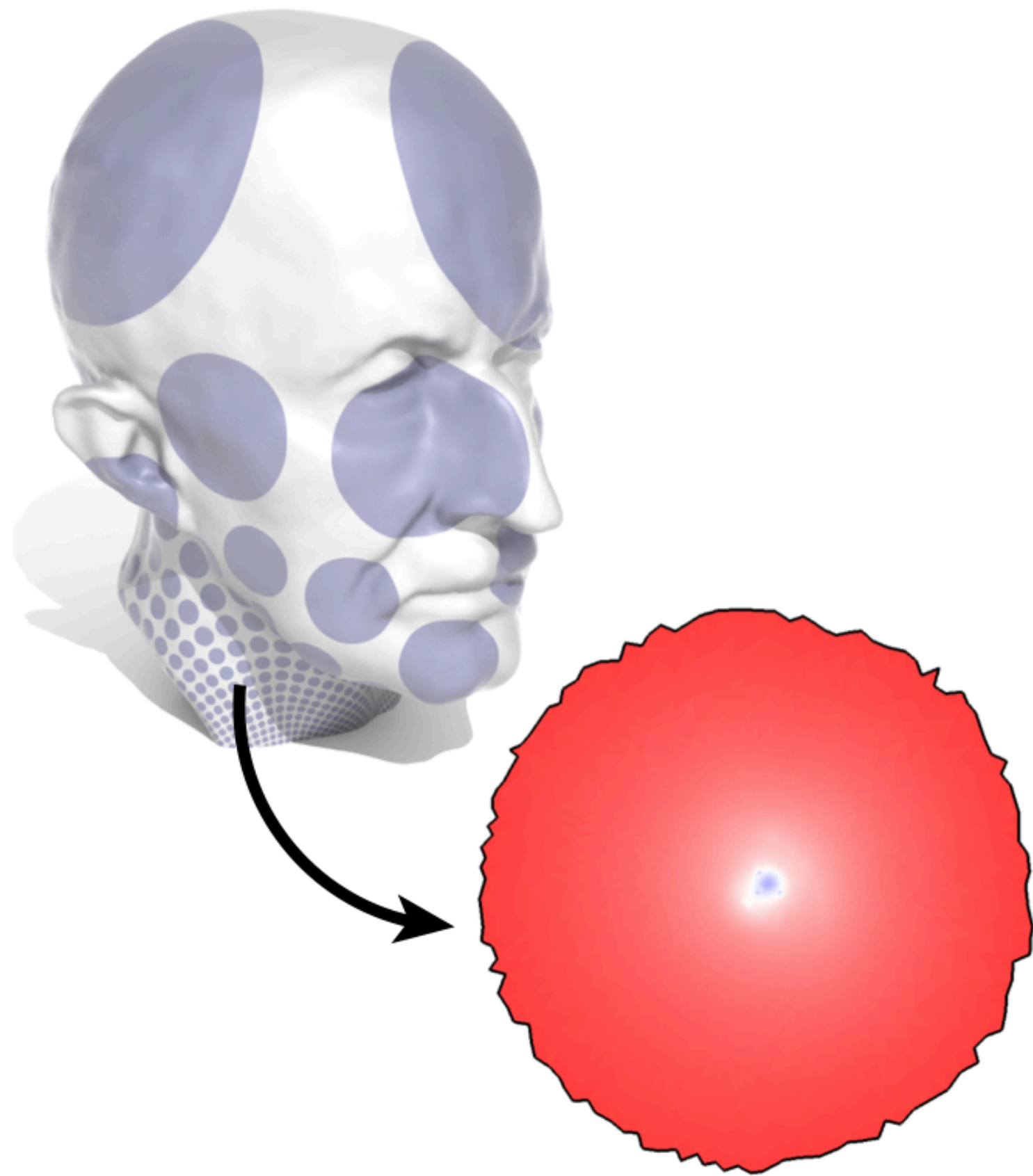
Harmonically extend both coordinates of $\tilde{\gamma}$ to exactly interpolate angles

Converges to conformal map under refinement since $\tilde{\gamma}$ is approximately conformal



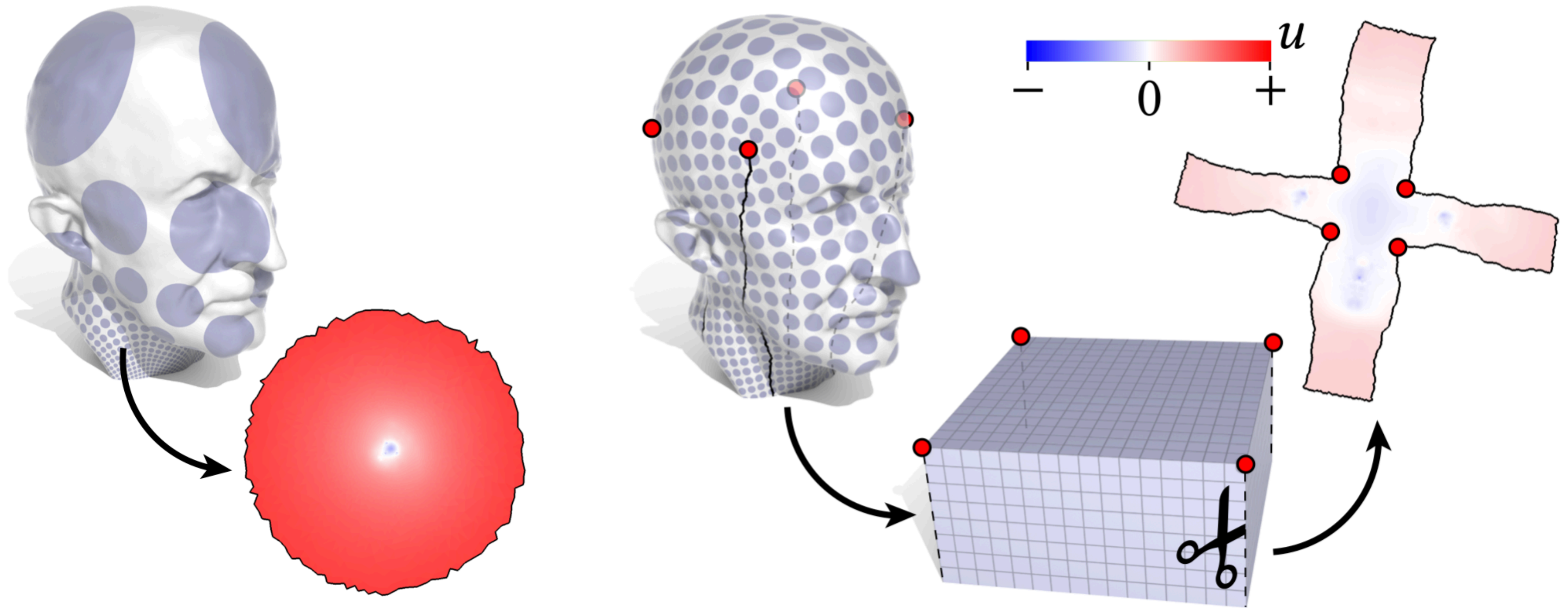
Seamless Cone Parameterization

Cone singularities offer a powerful technique for mitigating scale distortion



Seamless Cone Parameterization

Cone singularities offer a powerful technique for mitigating scale distortion



Seamless Cone Parameterization

Cone singularities in BFF

Seamless Cone Parameterization

Cone singularities in BFF

Solve *Yamabe Problem* with modified source term

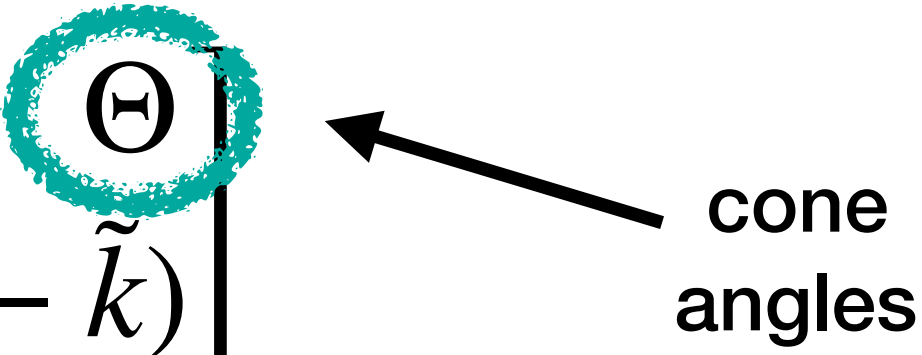
$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} \begin{bmatrix} u_I \\ u_B \end{bmatrix} = \begin{bmatrix} \Omega - \Theta \\ -(k - \tilde{k}) \end{bmatrix}$$

← cone angles

Seamless Cone Parameterization

Cone singularities in BFF

Solve *Yamabe Problem* with modified source term

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} \begin{bmatrix} u_I \\ u_B \end{bmatrix} = \begin{bmatrix} \Omega & -\Theta \\ -(k - \tilde{k}) \end{bmatrix}$$


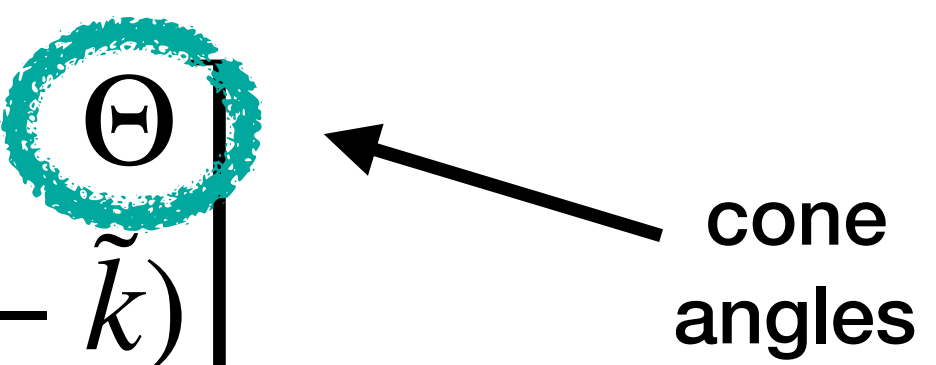
cone angles

Cut through cones, prescribing u along cut

Seamless Cone Parameterization

Cone singularities in BFF

Solve *Yamabe Problem* with modified source term

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} \begin{bmatrix} u_I \\ u_B \end{bmatrix} = \begin{bmatrix} \Omega - \Theta \\ -(k - \tilde{k}) \end{bmatrix}$$


cone angles

Cut through cones, prescribing u along cut

Maps are seamless by construction

Seamless Cone Parameterization

Cone singularities in BFF

Solve *Yamabe Problem* with modified source term

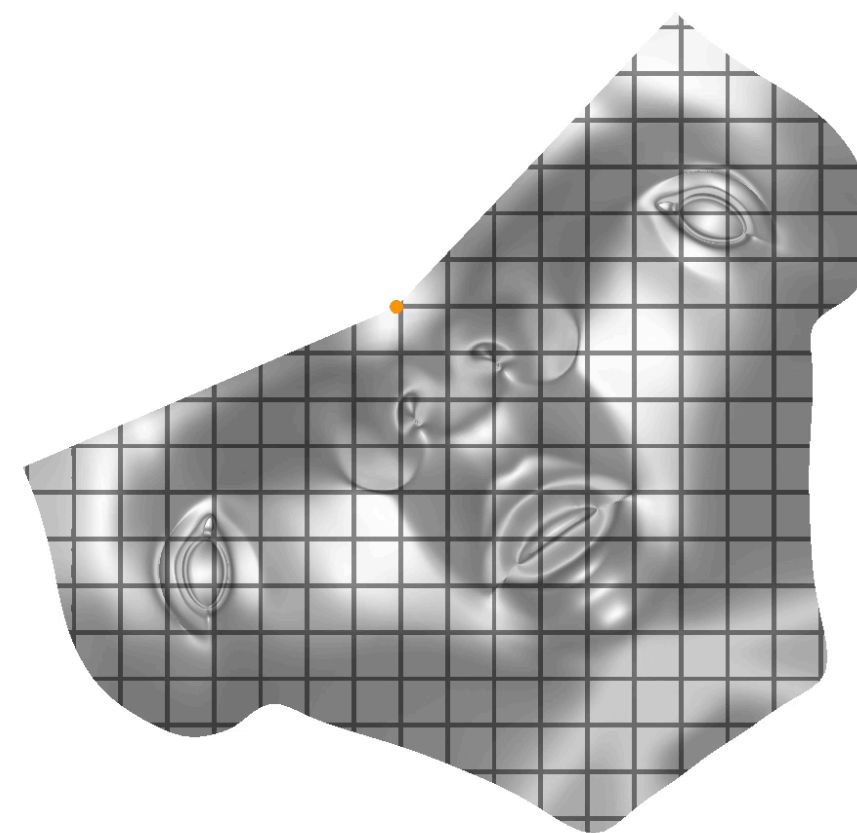
$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} \begin{bmatrix} u_I \\ u_B \end{bmatrix} = \begin{bmatrix} \Omega - \Theta \\ -(k - \tilde{k}) \end{bmatrix}$$

← cone angles

Cut through cones, prescribing u along cut

Maps are seamless by construction

Allow interactive editing of cone angles



Seamless Cone Parameterization

Cone singularities in BFF

Solve *Yamabe Problem* with modified source term

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} \begin{bmatrix} u_I \\ u_B \end{bmatrix} = \begin{bmatrix} \Omega - \Theta \\ -(k - \tilde{k}) \end{bmatrix}$$

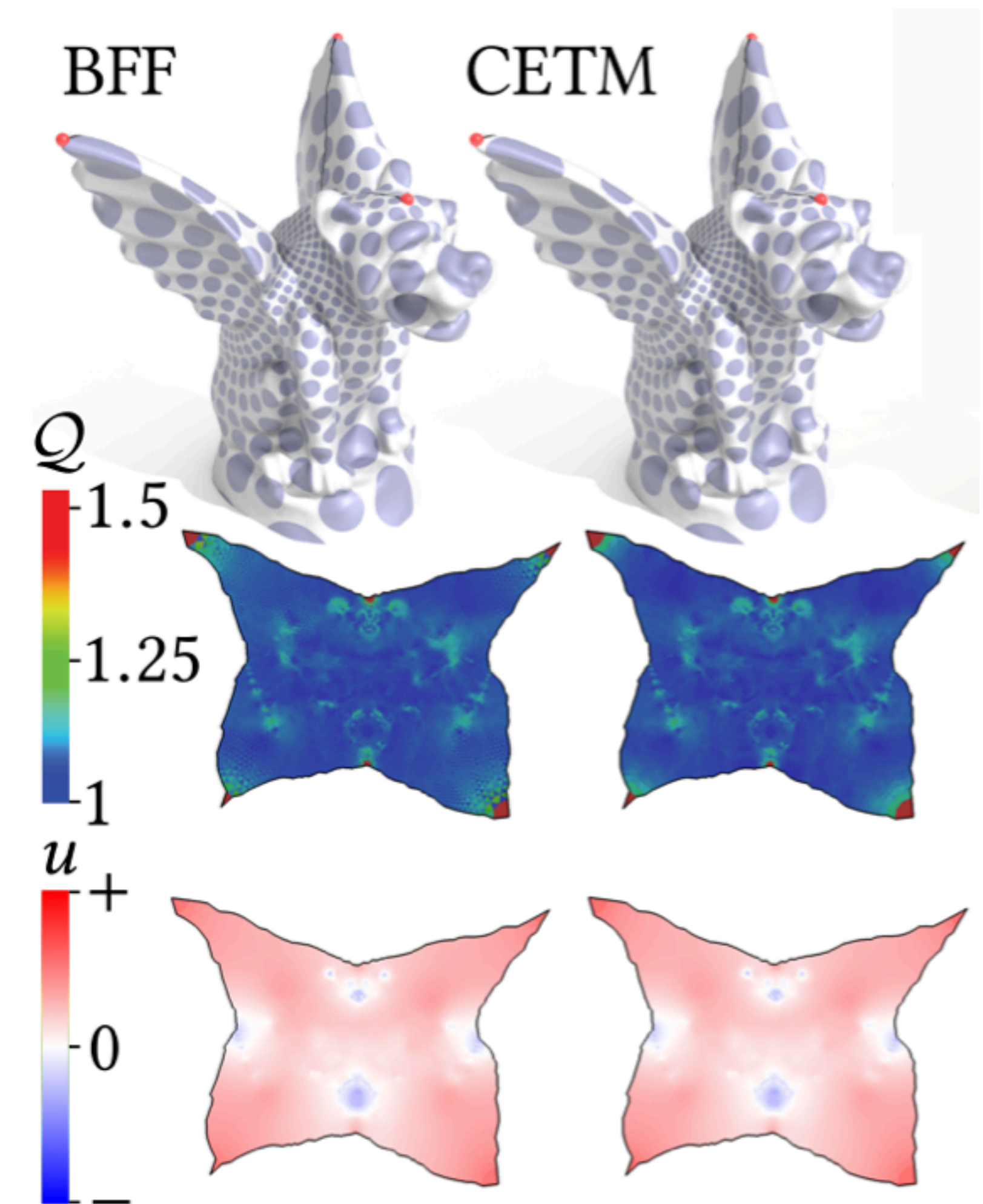
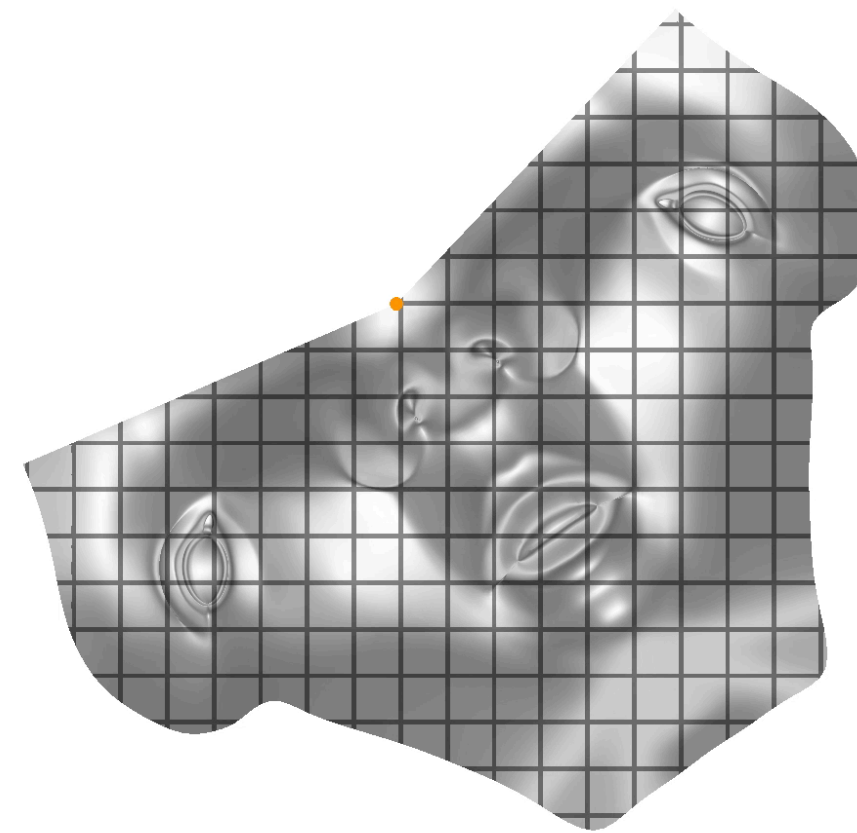
← cone angles

Cut through cones, prescribing u along cut

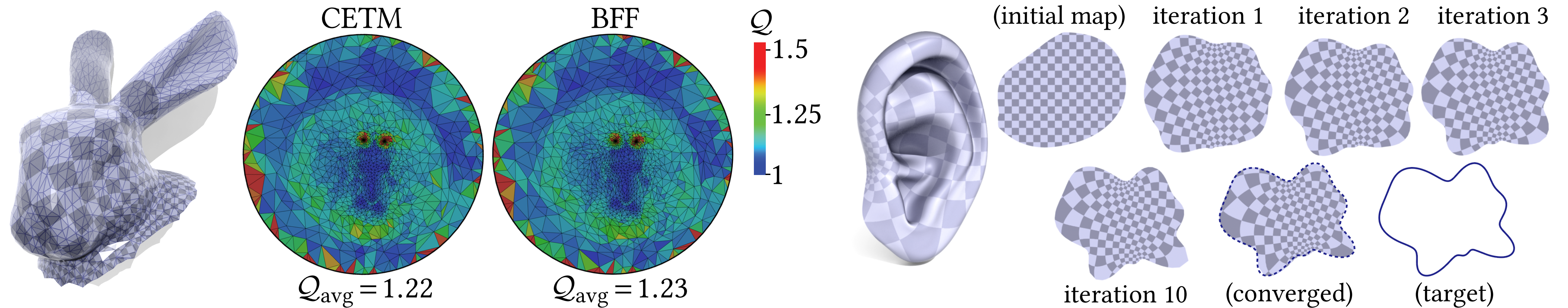
Maps are seamless by construction

Allow interactive editing of cone angles

Results indistinguishable from CETM

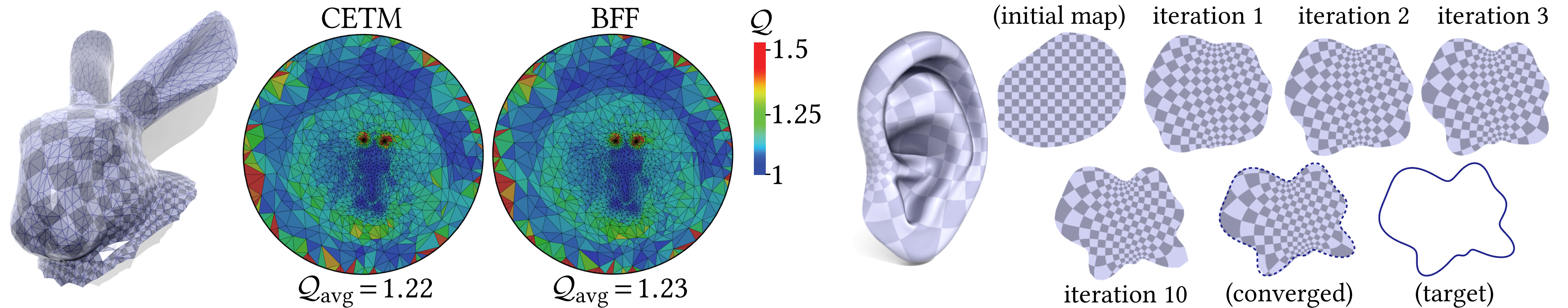


Uniformization and Arbitrary Target Shapes



Iterative procedure converges in fewer than 10 iterations

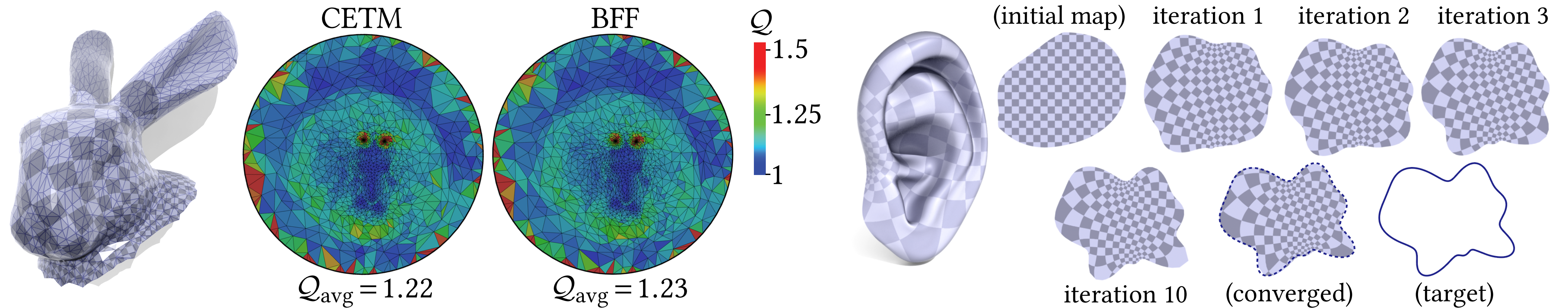
Uniformization and Arbitrary Target Shapes



Iterative procedure converges in fewer than 10 iterations

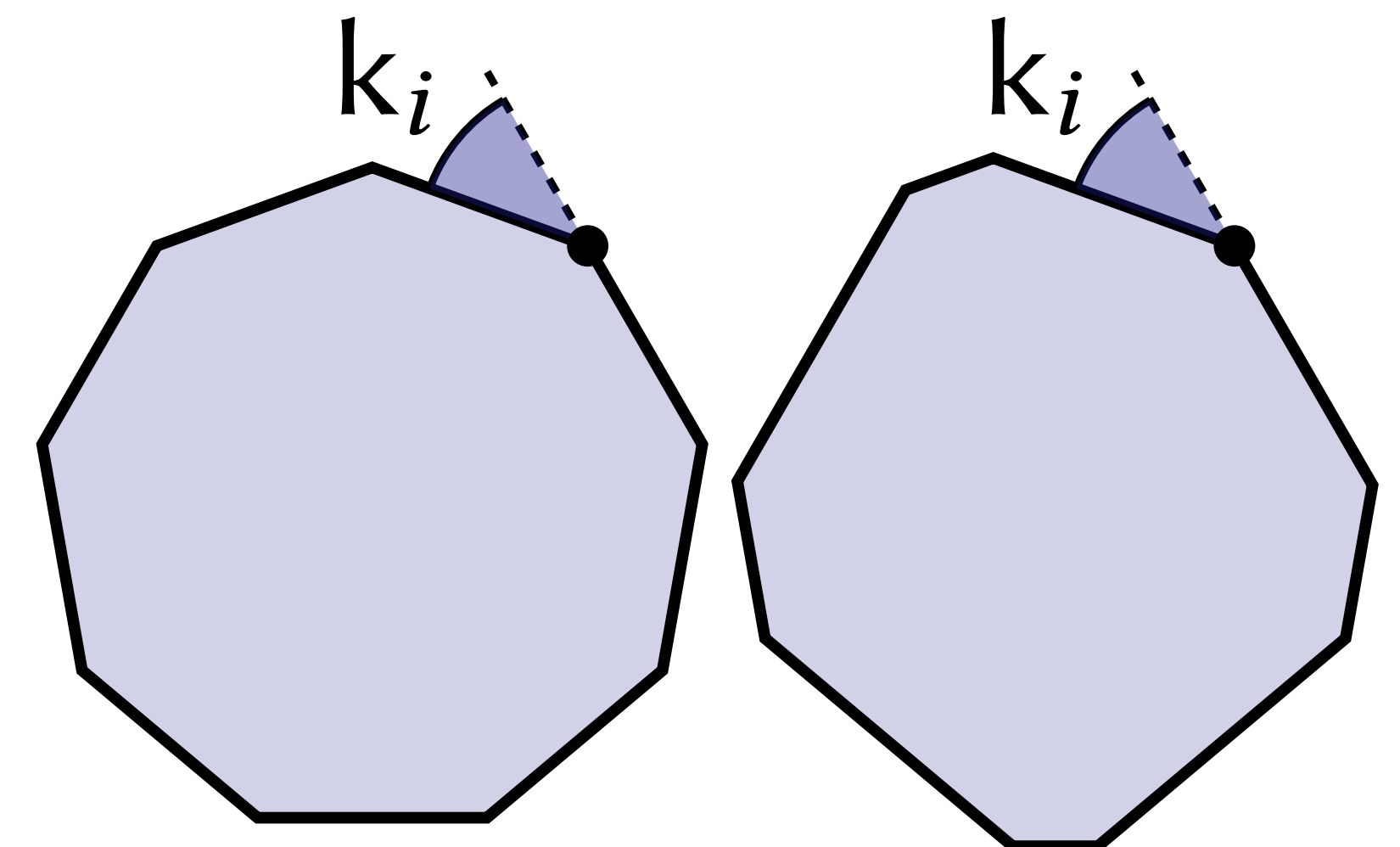
Prescribing exterior angles does not work

Uniformization and Arbitrary Target Shapes

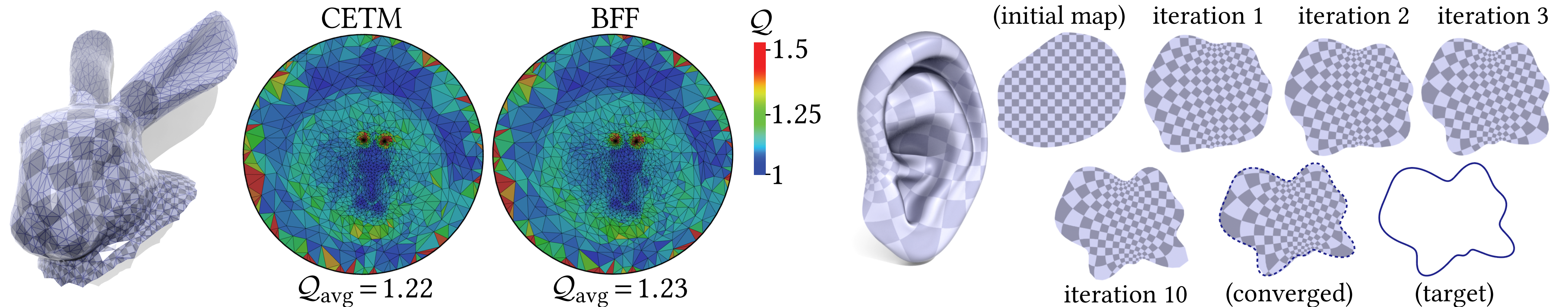


Iterative procedure converges in fewer than 10 iterations

Prescribing exterior angles does not work



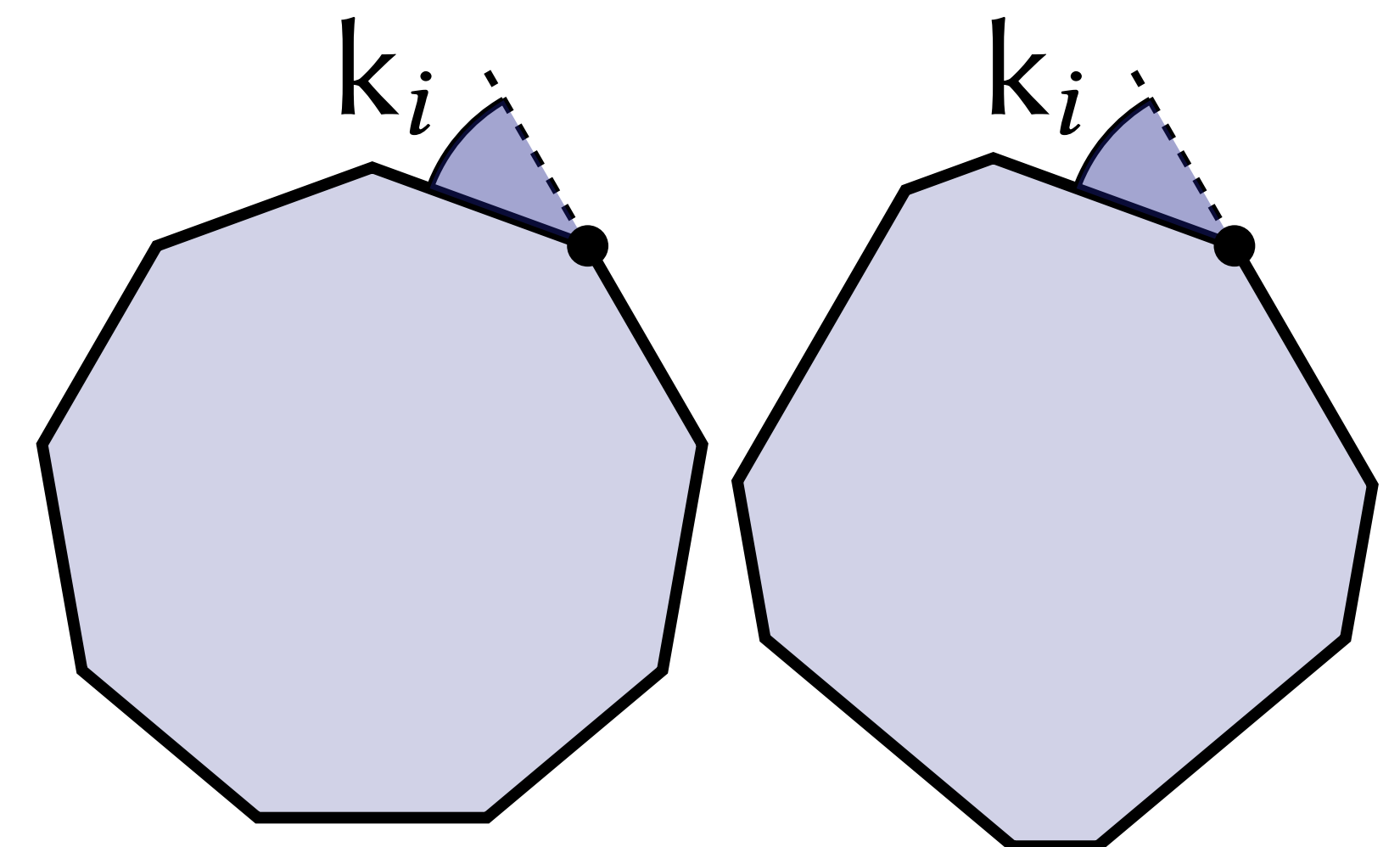
Uniformization and Arbitrary Target Shapes



Iterative procedure converges in fewer than 10 iterations

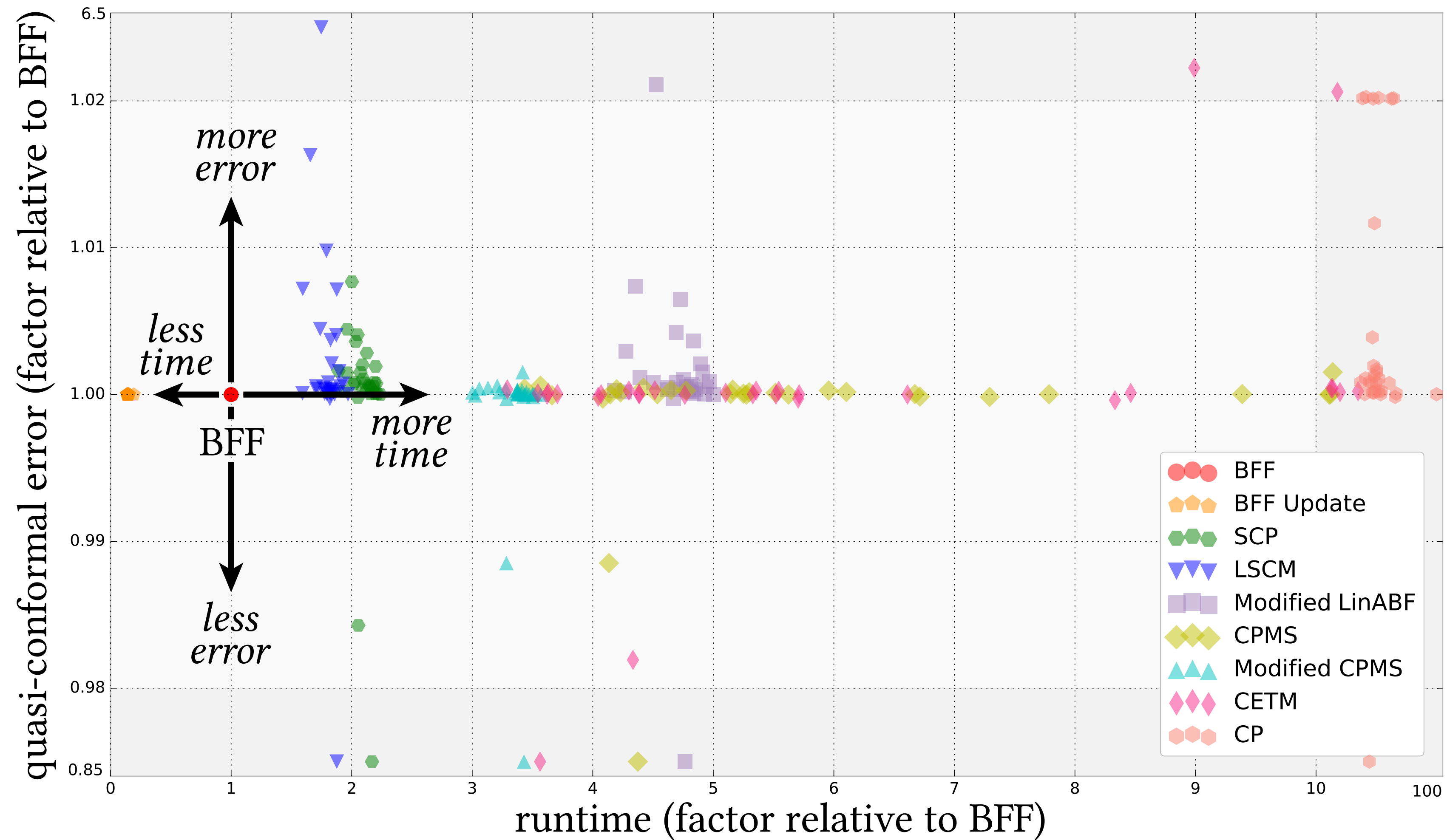
Prescribing exterior angles does not work

To uniquely prescribe target shape, need to control
change in angle per unit length



EVALUATION

Performance



Fast Computation

Single Sparse Cholesky Factorization

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} = \begin{bmatrix} L_{II} & 0 \\ L_{BI} & L_{BB} \end{bmatrix} \begin{bmatrix} L_{II}^T & L_{BI}^T \\ 0 & L_{BB}^T \end{bmatrix}$$

most expensive step in entire algorithm

Fast Computation

Single Sparse Cholesky Factorization

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} = \begin{bmatrix} L_{II} & 0 \\ L_{BI} & L_{BB} \end{bmatrix} \begin{bmatrix} L_{II}^T & L_{BI}^T \\ 0 & L_{BB}^T \end{bmatrix}$$

$$\Rightarrow A_{II} = L_{II}L_{II}^T$$

most expensive step in entire algorithm

“for free”

Fast Computation

Single Sparse Cholesky Factorization

$$\begin{bmatrix} A_{II} & A_{IB} \\ A_{IB}^T & A_{BB} \end{bmatrix} = \begin{bmatrix} L_{II} & 0 \\ L_{BI} & L_{BB} \end{bmatrix} \begin{bmatrix} L_{II}^T & L_{BI}^T \\ 0 & L_{BB}^T \end{bmatrix}$$

$$\Rightarrow A_{II} = L_{II} L_{II}^T$$

most expensive step in entire algorithm

“for free”

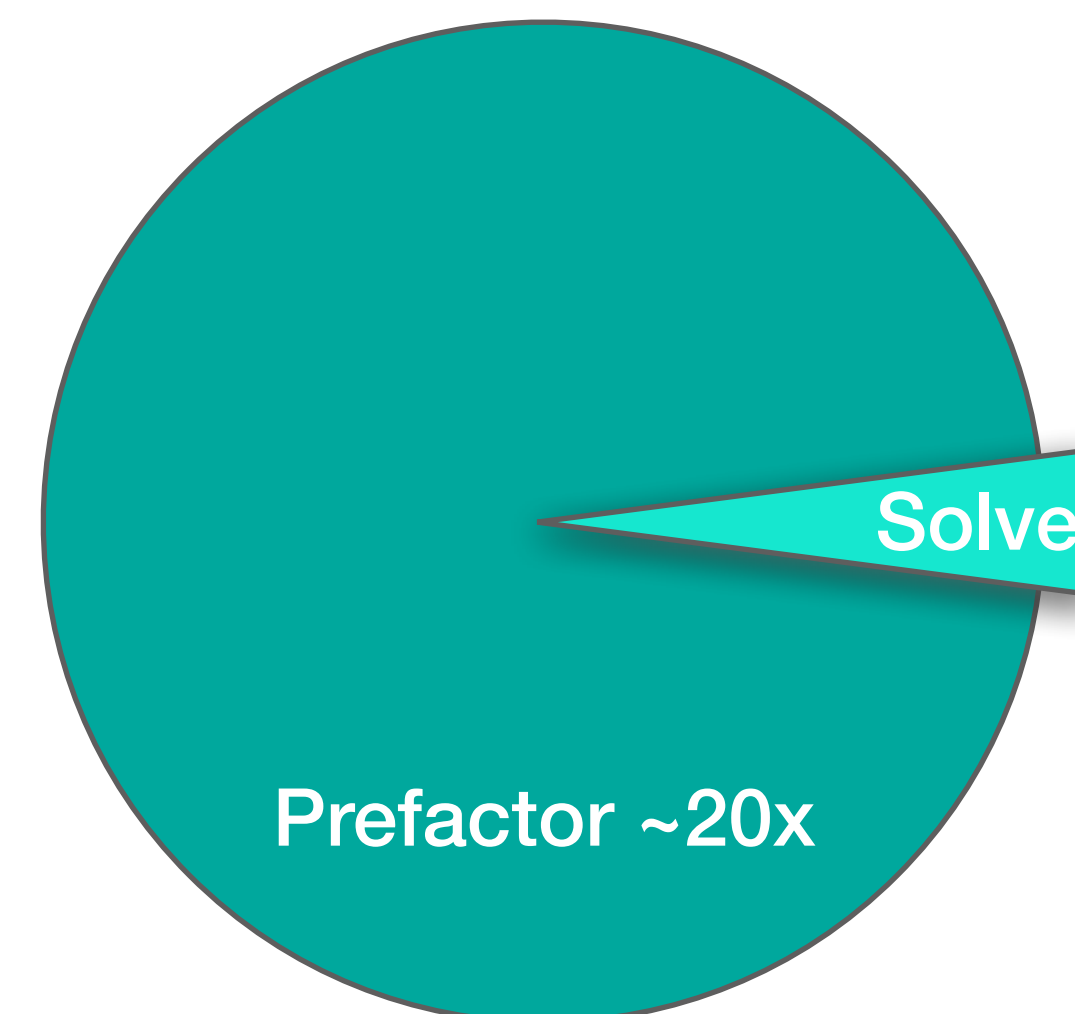
Backsubstitution

$$Ax_1 = b_1$$

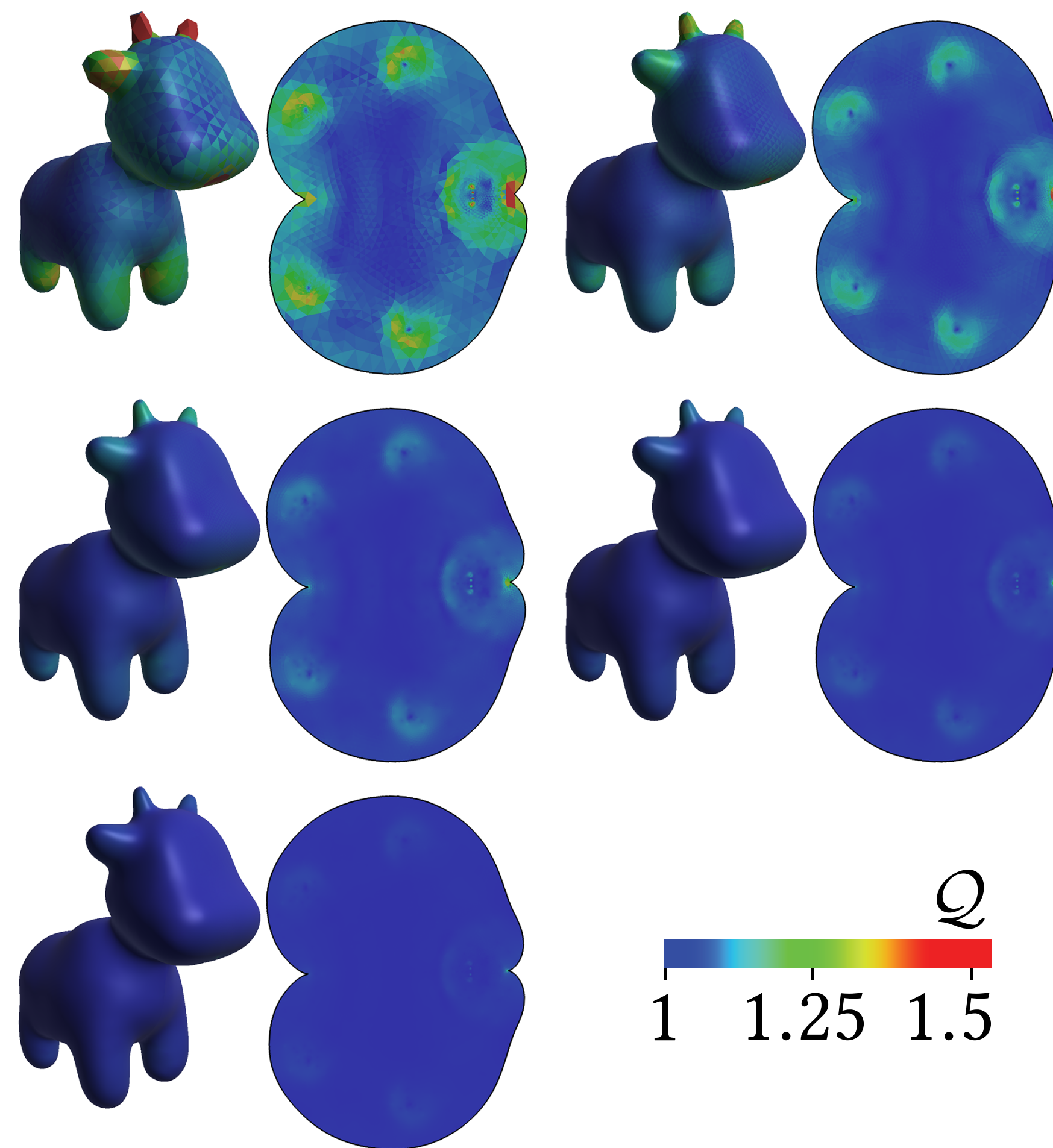
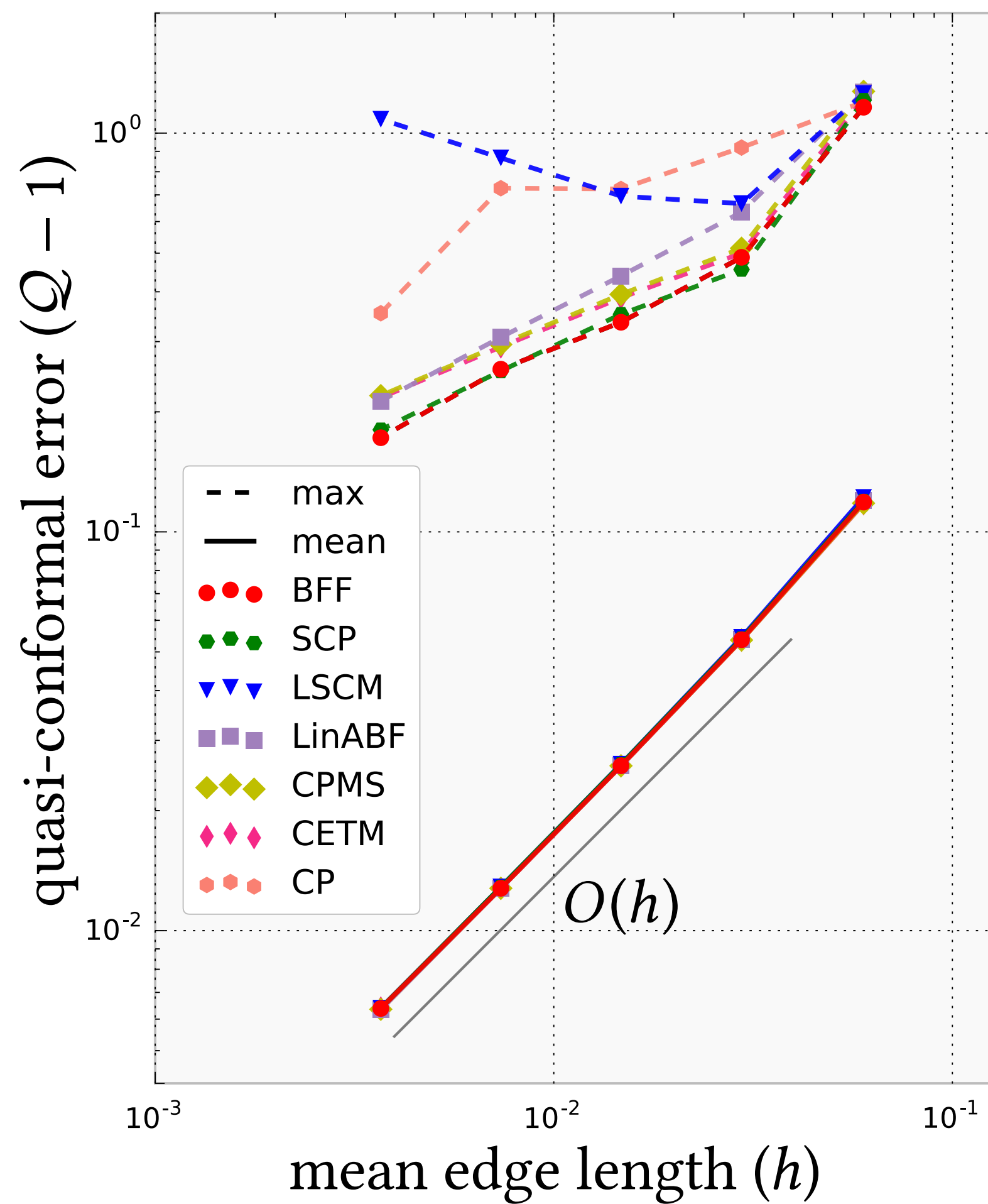
$$Ax_2 = b_2$$

$$Ax_3 = b_3$$

⋮

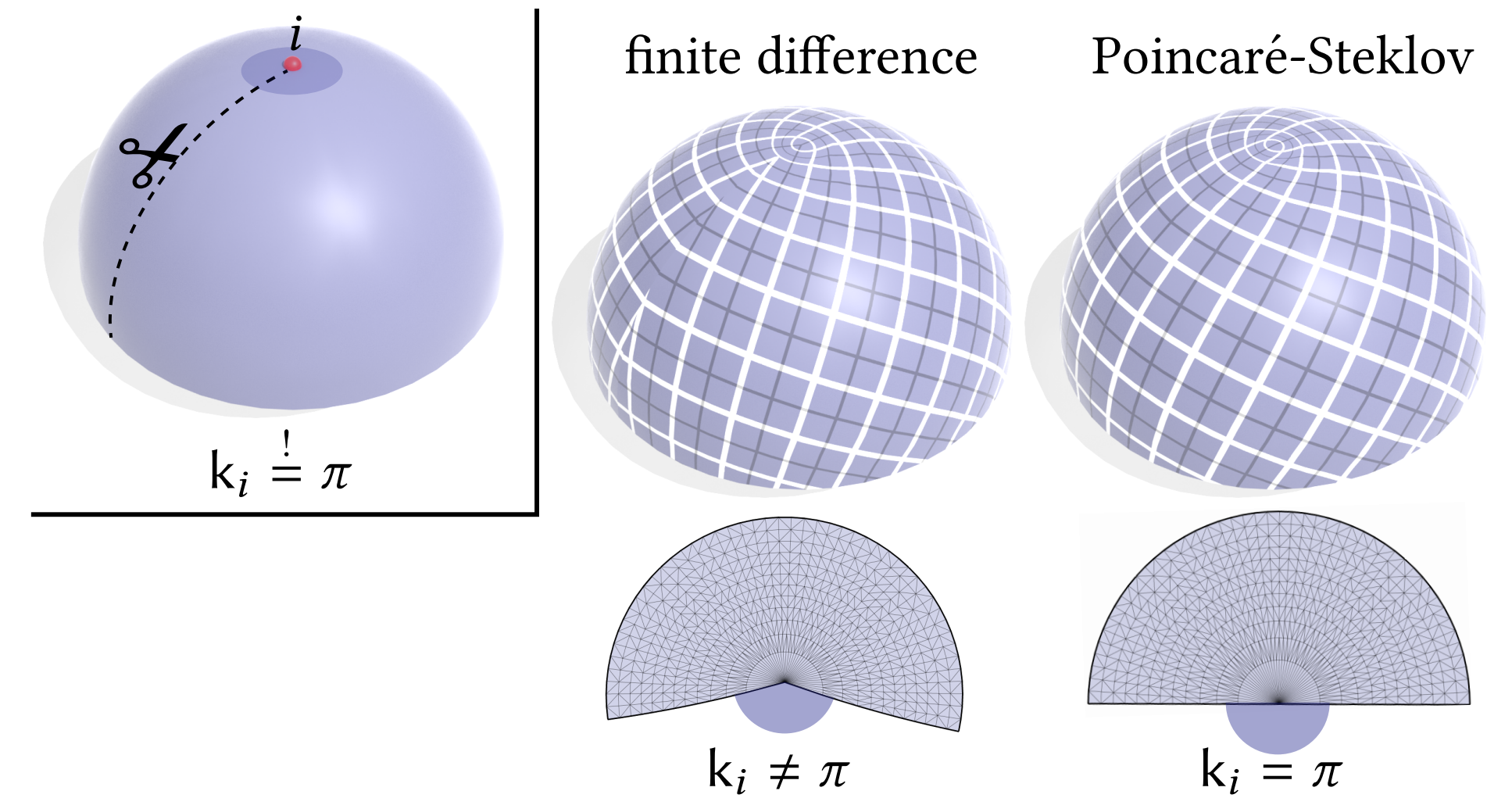


Convergence



Numerical Robustness

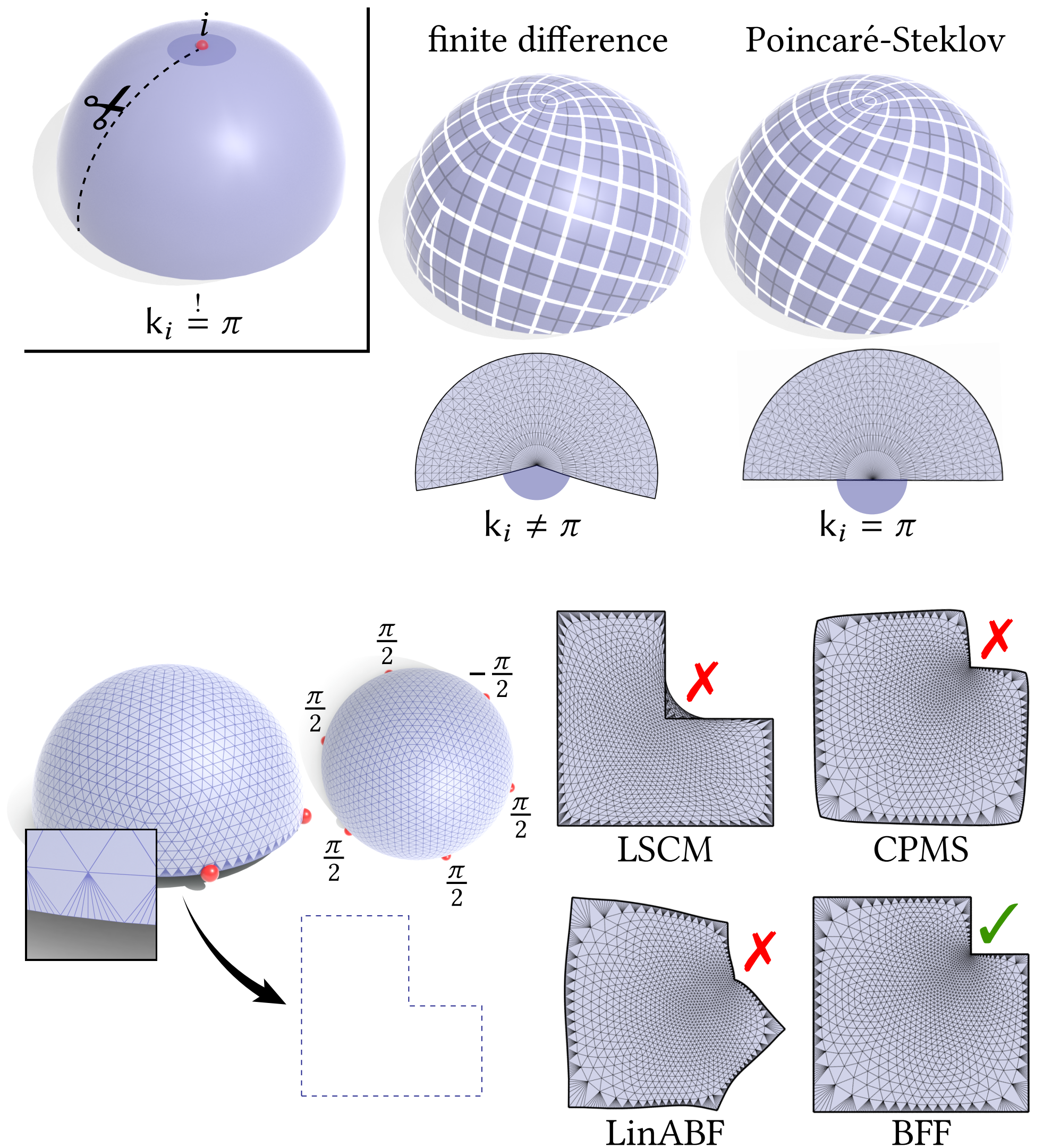
Principled discretization of Poincaré Steklov operators guarantees exact integrability of exterior angles



Numerical Robustness

Principled discretization of Poincaré Steklov operators guarantees exact integrability of exterior angles

Integrability of edge lengths enforced only along boundary



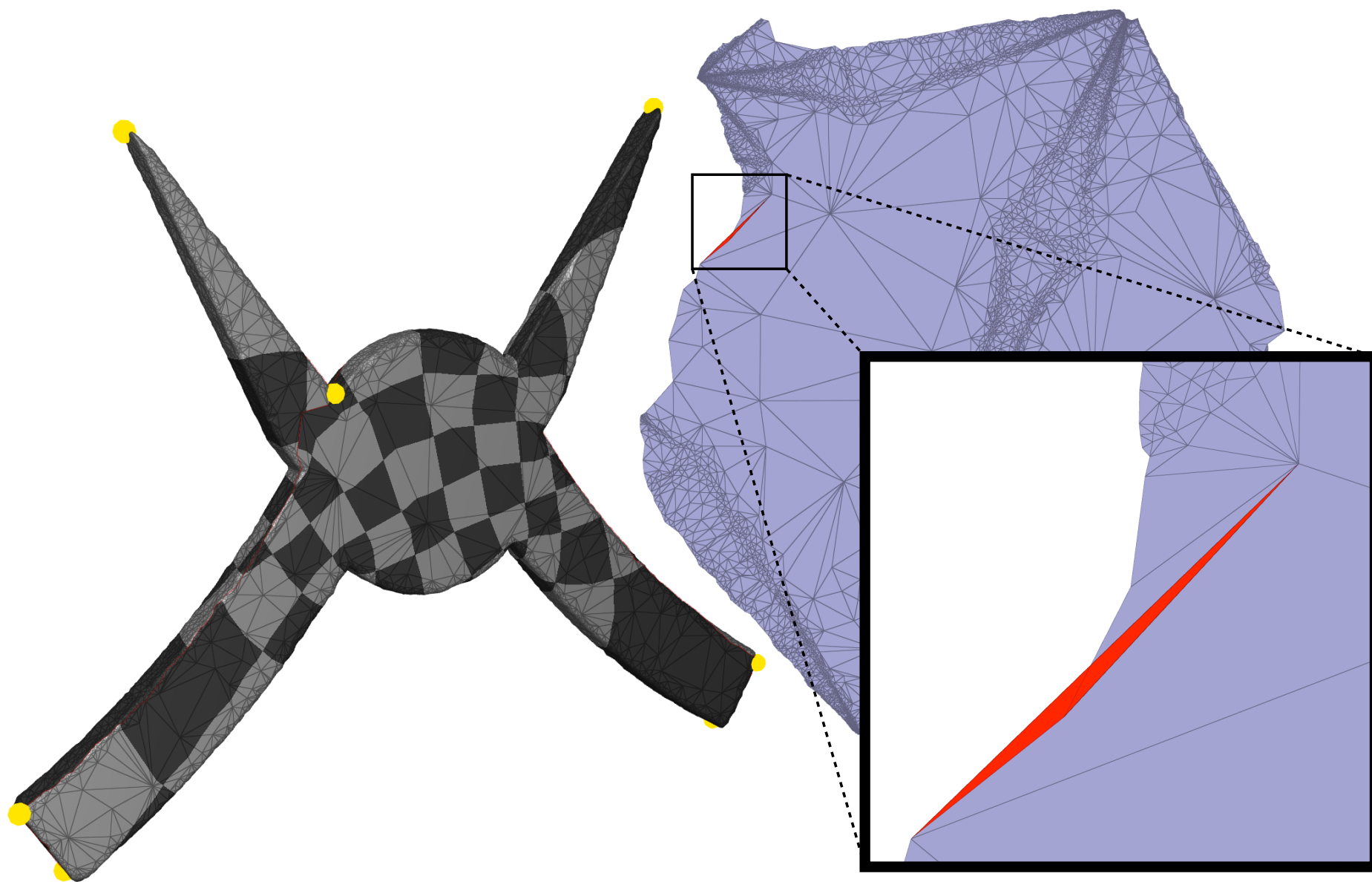
Injectivity (No Flipped Triangles)

BFF provides no guarantees, but maps are usually injective:

Injectivity (No Flipped Triangles)

BFF provides no guarantees, but maps are usually injective:

SHREC: 6/588 meshes; 1-2 flipped triangles

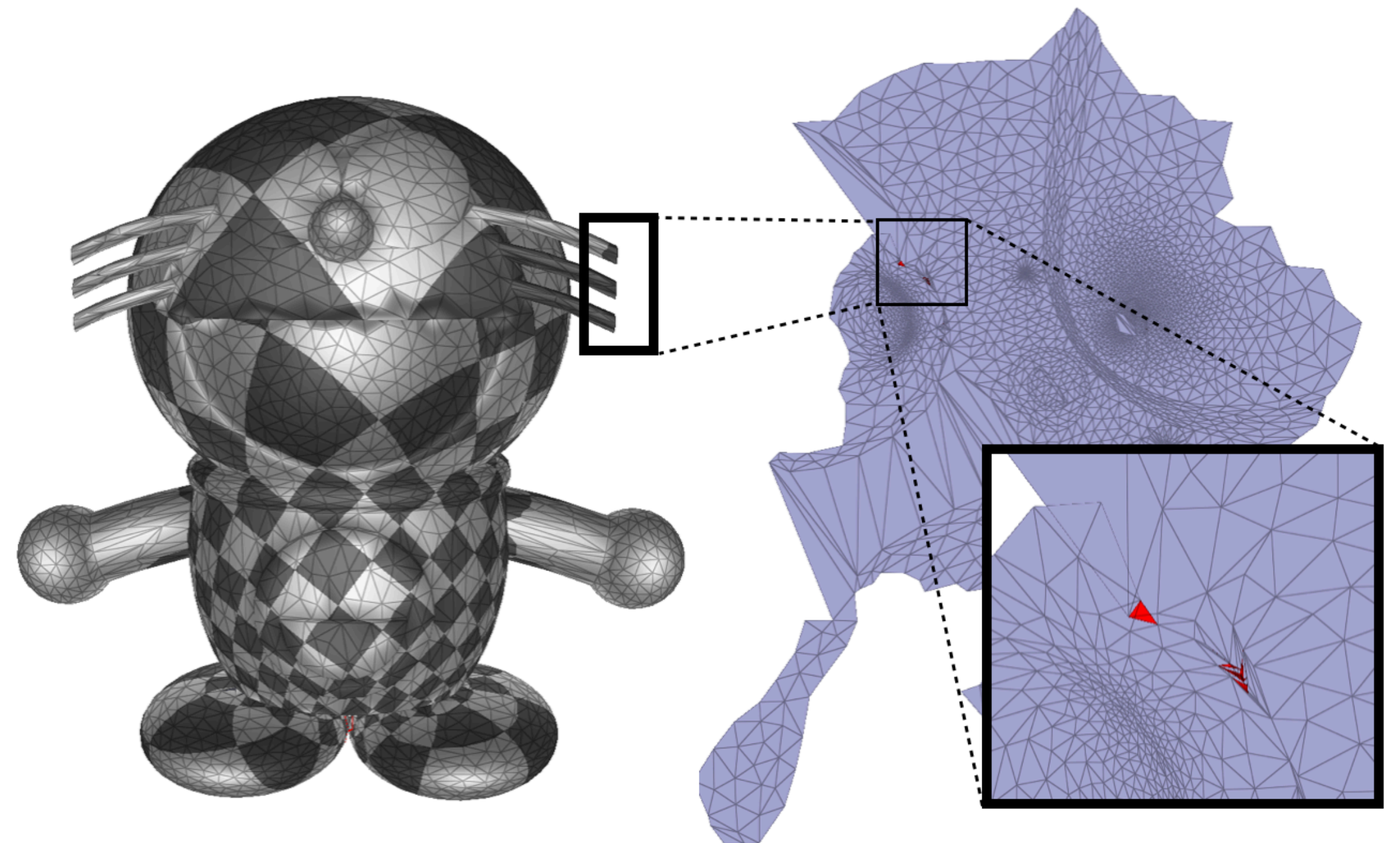
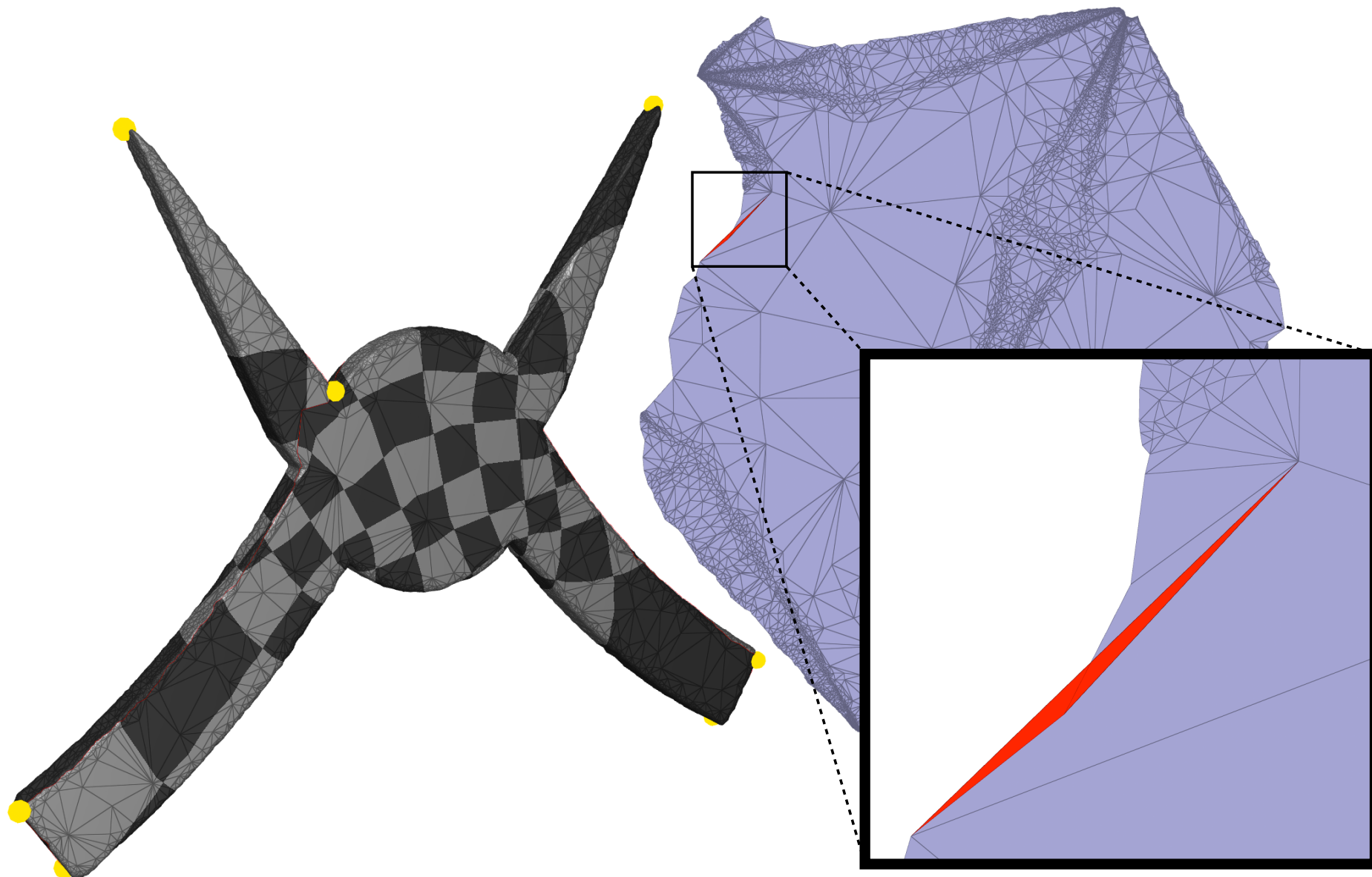


Injectivity (No Flipped Triangles)

BFF provides no guarantees, but maps are usually injective:

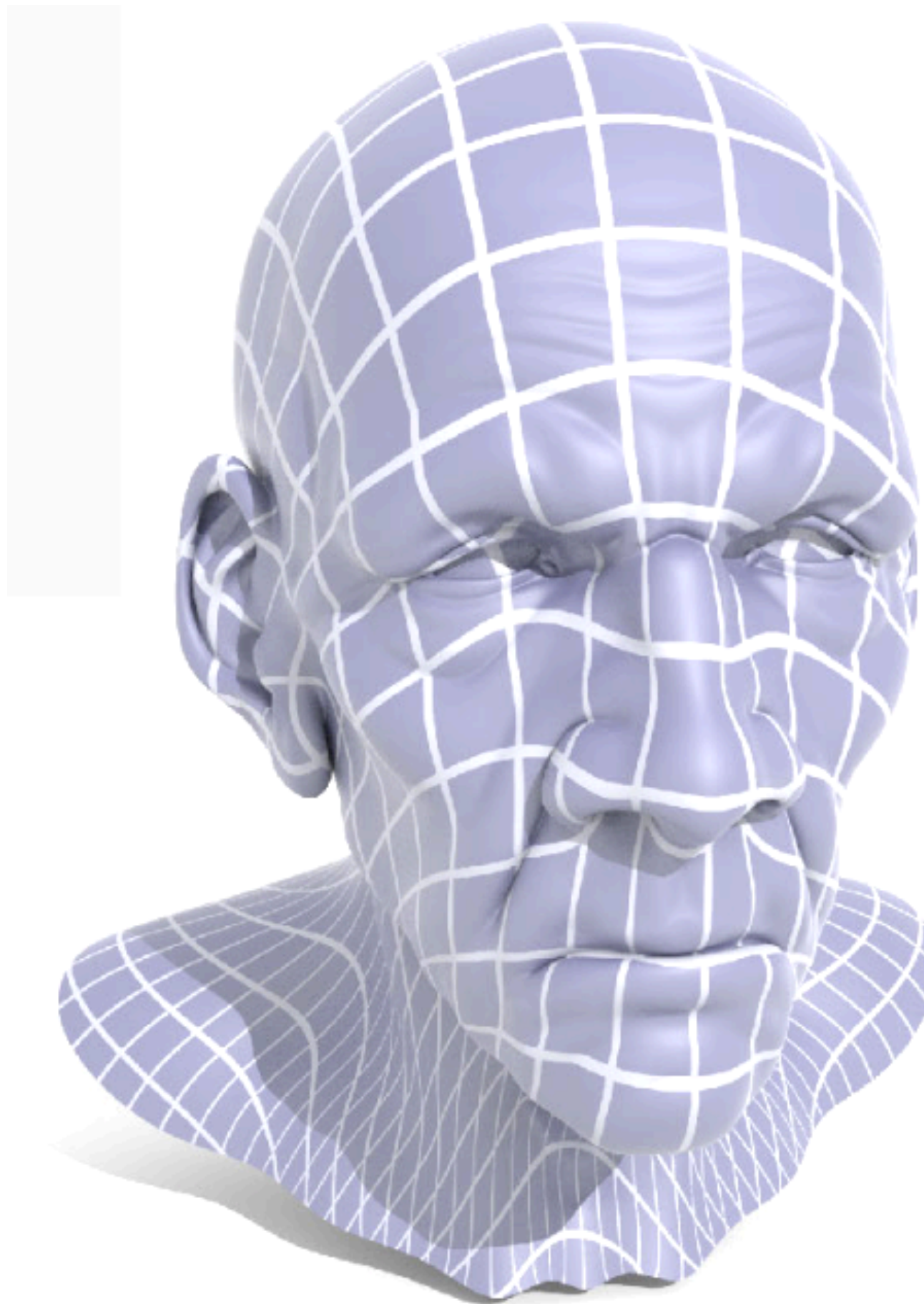
SHREC: 6/588 meshes; 1-2 flipped triangles

Myles & Zorin: 5/116 meshes; > 1% flipped triangles

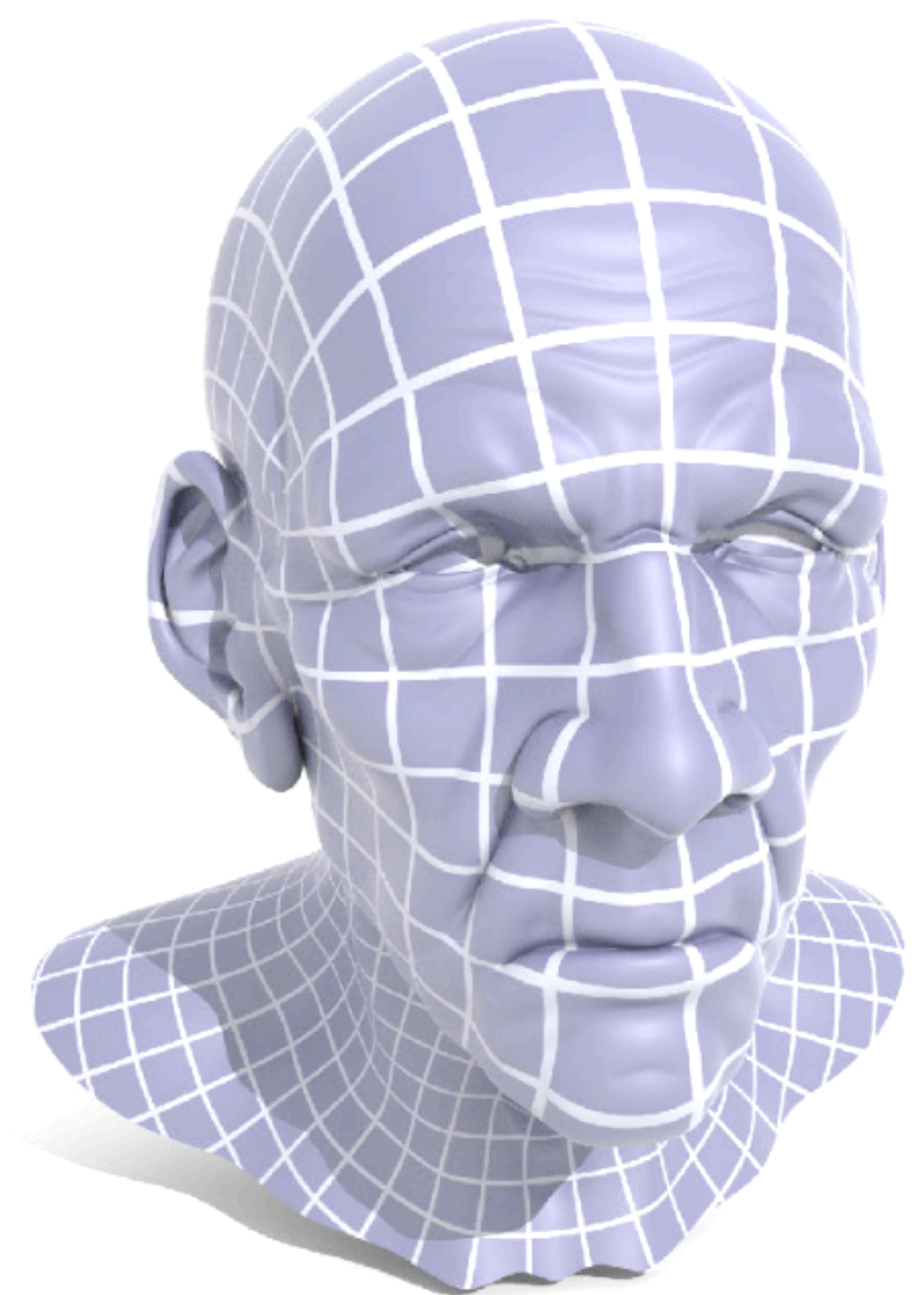


Price of Guaranteed Injectivity

Editing can be 100's of times slower with injective methods



SLIM + PARDISO – 15.9s
[Rabinovich et al 2016]

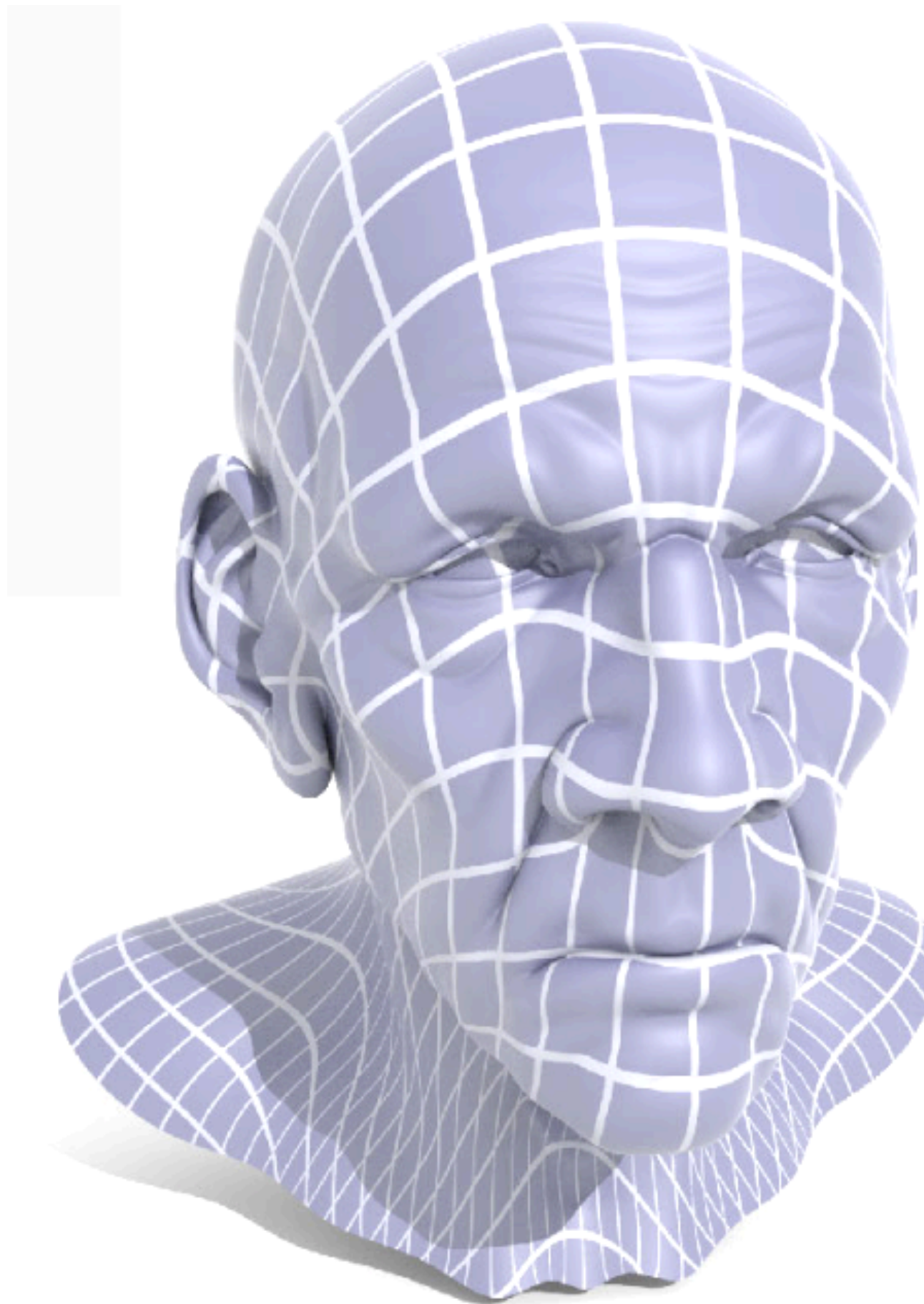


BFF - 0.12s (*126x faster*)
[Sawhney & Crane 2017]

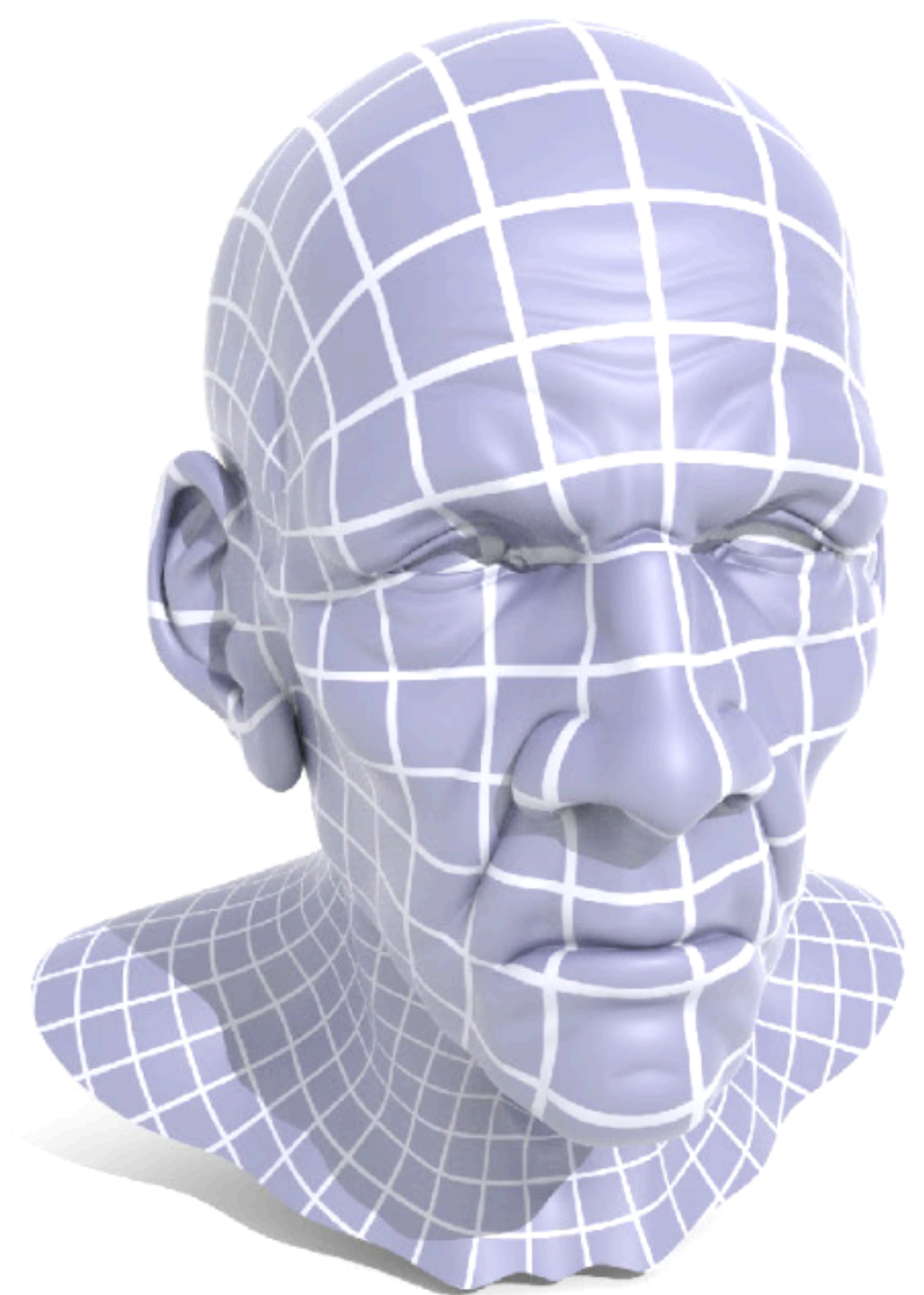
Price of Guaranteed Injectivity

Editing can be **100's** of times slower with injective methods

Best of both worlds:
use fast method like BFF
fallback if necessary

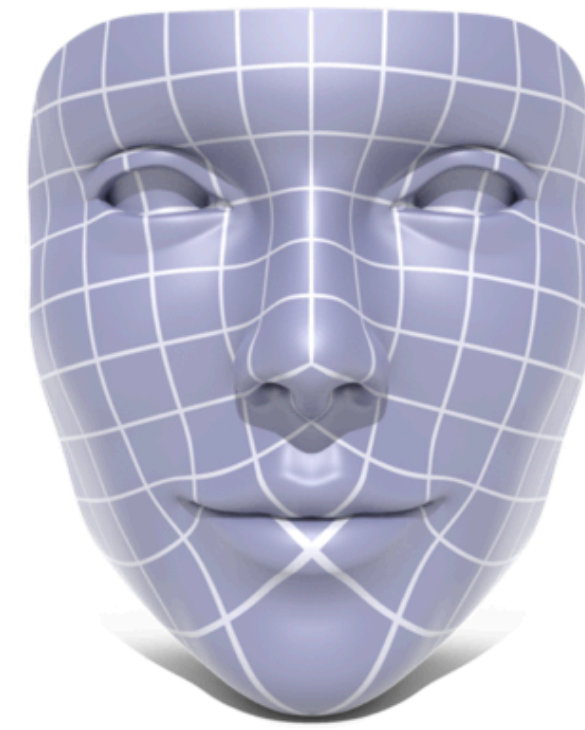


SLIM + PARDISO – 15.9s
[Rabinovich et al 2016]



BFF - 0.12s (*126x faster*)
[Sawhney & Crane 2017]

I Want My BFF To Be Your BFF



Boundary First Flattening

Boundary First Flattening (BFF) is a free and open source application for surface parameterization. Unlike other tools for UV mapping, BFF allows free-form editing of the flattened mesh, providing users direct control over the shape of the flattened domain—rather than being stuck with whatever the software provides. The initial flattening is fully automatic, with distortion mathematically guaranteed to be as low or lower than any other conformal mapping tool. The tool also provides some state-of-the art flattening techniques not available in standard UV mapping software such as *cone singularities*, which can dramatically reduce area distortion, and *seamless maps*, which help eliminate artifacts by ensuring identical texture resolution across all cuts. BFF is highly optimized, allowing interactive editing of meshes with millions of triangles.

The BFF application is based on the paper, “*Boundary First Flattening*” by Rohan Sawhney and Keenan Crane.

geometry.cs.cmu.edu/bff

Thanks!



BACKUP SLIDES

2D Shape Editing & Uniformization

Apply 2D conformal deformations to initial flattening?

Piecewise linear conformal maps do not compose

Composition of methods offers no clear advantage in terms of speed or simplicity



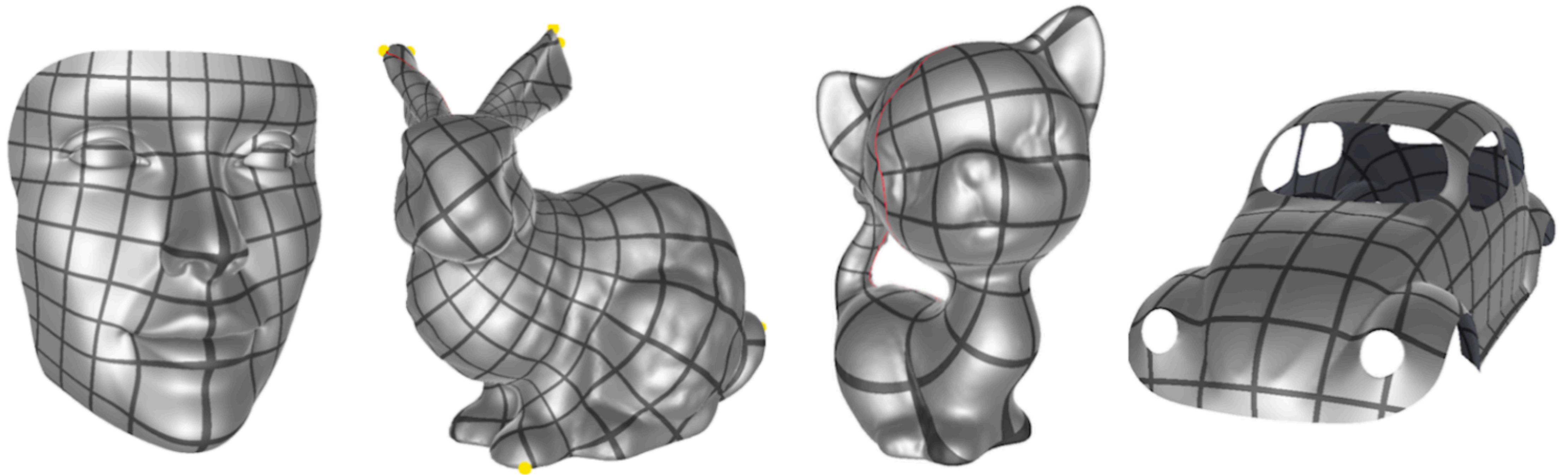
Controllable Conformal Maps for Shape Deformation and Interpolation
[Weber et al 2010]

Topology

For multiply connected domains like annulus, *Hilbert transform* is not valid

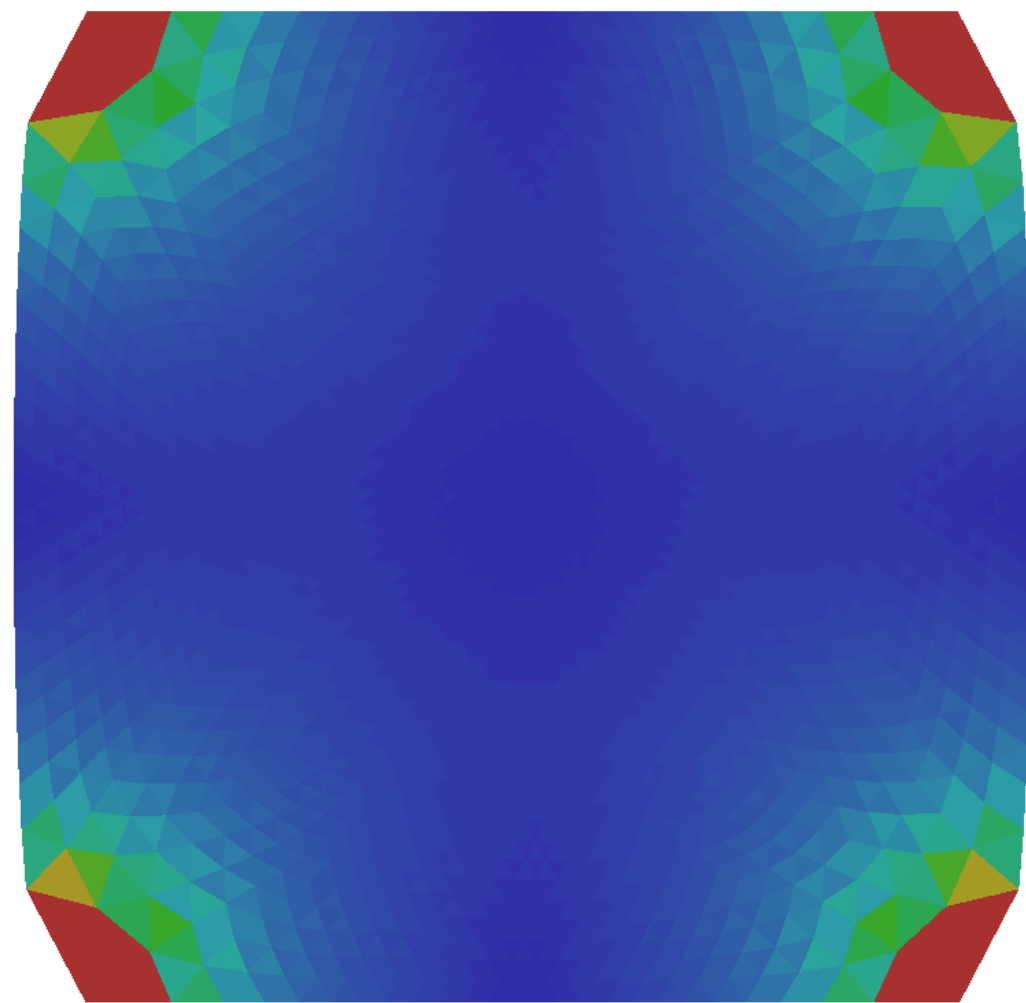
Fill holes with virtual faces to flatten

Cut surface into one or more disks

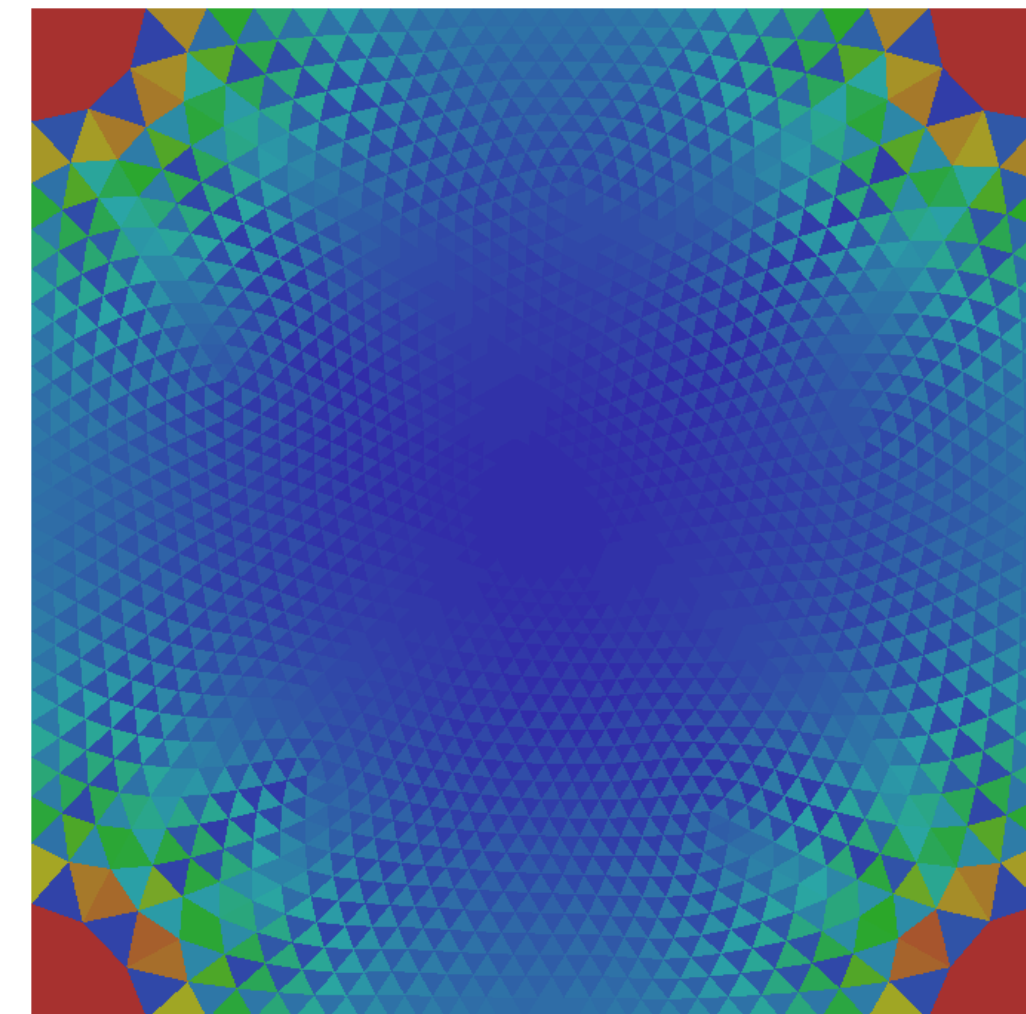


Harmonic vs Holomorphic Extension

Harmonic and holomorphic extension of $\tilde{\gamma}$ converge to the same solution under refinement



Holomorphic Extension



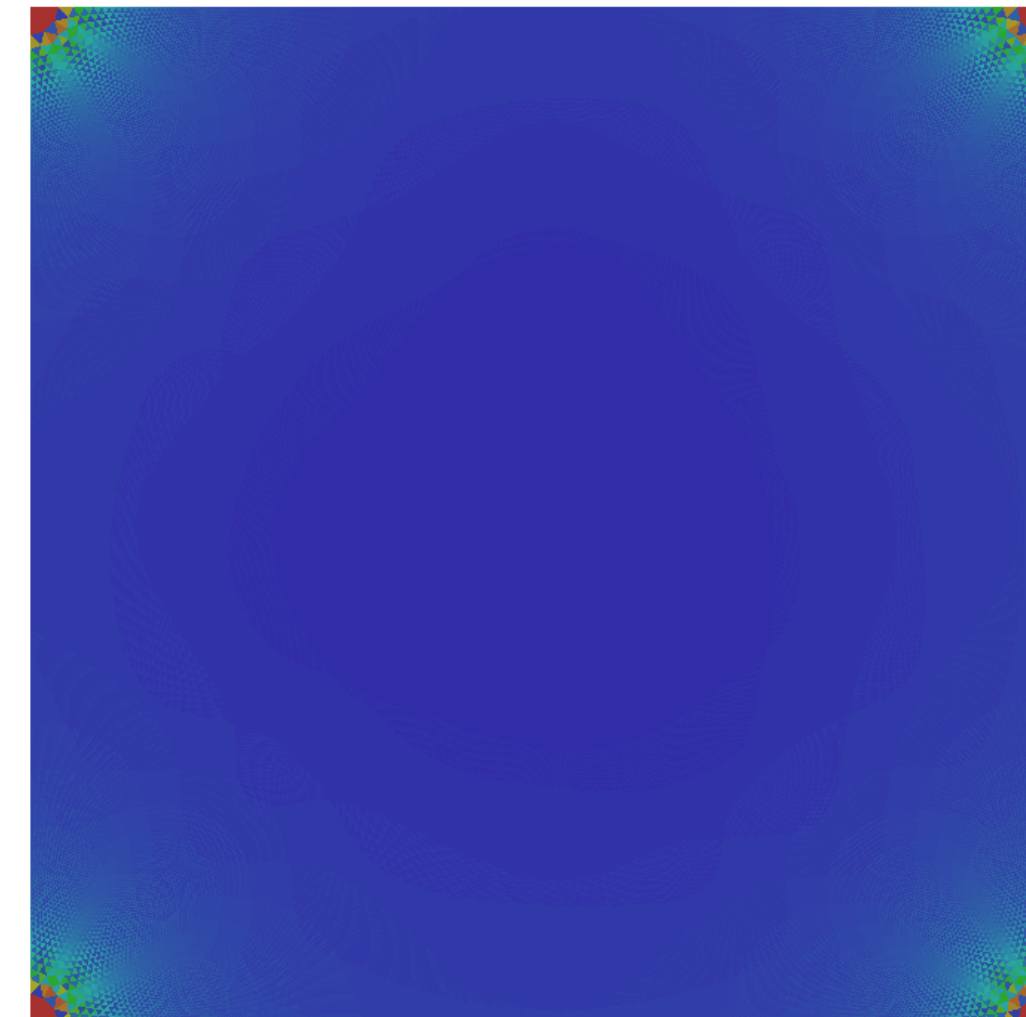
Harmonic Extension

Harmonic vs Holomorphic Extension

Harmonic and holomorphic extension of $\tilde{\gamma}$ converge to the same solution under refinement



Holomorphic Extension



Harmonic Extension

More Details on Discretizing the Yamabe Problem (1)

Multiply *Yamabe equation* by dA and its boundary conditions by ds

$$\begin{array}{lll} \Delta u = K - e^{2u} \tilde{K} & \Delta u \cdot dA = K \cdot dA - \underbrace{\tilde{K} e^{2u} \cdot dA}_{d\tilde{A}} & \text{on } M \\ \Rightarrow & & \\ \frac{\partial u}{\partial n} = \kappa - e^u \tilde{\kappa} & \frac{\partial u}{\partial n} \cdot ds = \kappa \cdot ds - \underbrace{\tilde{\kappa} e^u \cdot ds}_{d\tilde{s}} & \text{on } \partial M \end{array}$$

More Details on Discretizing the Yamabe Problem (2)

Integrate over *dual volumes*

$$\Delta u \cdot dA = K \cdot dA - \tilde{K} \cdot d\tilde{A} \qquad \text{on } M$$

$$\frac{\partial u}{\partial n} \cdot ds = \kappa \cdot ds - \tilde{\kappa} d\tilde{s} \qquad \text{on } \partial M$$

More Details on Discretizing the Yamabe Problem (2)

Integrate over *dual volumes*

$$\Delta u \cdot dA = K \cdot dA - \tilde{K} \cdot d\tilde{A}$$

$$Au = \Omega - \tilde{\Omega} \quad \text{on } M$$



$$\frac{\partial u}{\partial n} \cdot ds = \kappa \cdot ds - \tilde{\kappa} d\tilde{s}$$

$$h = k - \tilde{k} \quad \text{on } \partial M$$

Modification to CPMS

High Level Idea:

Employ *Yamabe Equation* to obtain scale information

Seek edge lengths that describe a flat surface via least squares layout

Modification:

Add boundary control with *Cherrier* boundary conditions

Comparison with BFF:

Least Squares layout does not respect boundary constraints

Amortized cost of editing a map with BFF is 30x faster compared to CPMS
(Layout matrix cannot be prefactored)

Modification to LinABF

High Level Idea:

Optimize corner angles β to find near flat metric

Find planar vertex positions approximating angles via least squares layout

Modification:

To prescribe exterior angles $\tilde{\kappa}$, add linear boundary constraints $\sum \beta_i^{jk} = \pi - \tilde{\kappa}_i$

To prescribe boundary lengths \tilde{l}_{ij} , add boundary condition $\prod_{ijk} \frac{\sin \beta_i^{jk}}{\sin \beta_j^{ji}} = \frac{\tilde{l}_{i-1,i}}{\tilde{l}_{i,i+1}}$

Comparison with BFF:

Artifacts due to linearization and least squares layout

Neither least squares matrix nor angle constraint matrix can be prefactored

I don't know...

D'oh!

